

MATERIAL SCIENCE

(16SMBEPH1)

(Brief notes for reference)

BY

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Note: Students are instructed to refer book for study and reference respectively for further elaborate points as prescribed by the University.

'UNIT-1'

'CRYSTAL STRUCTURE'

TWO MARK QUESTIONS :-

Define unit cell :-

* unit cell is the smallest portion of a crystal lattice.

* It is the simplest repeating unit in a crystal structure.

* The entire lattice is generating by the repetition of the unit cell in different directions.

* The unit cell has 6 parameters. They are three edges - a, b, c and the angles between the edges be α, β and γ .

* The unit cell is divided into types namely,

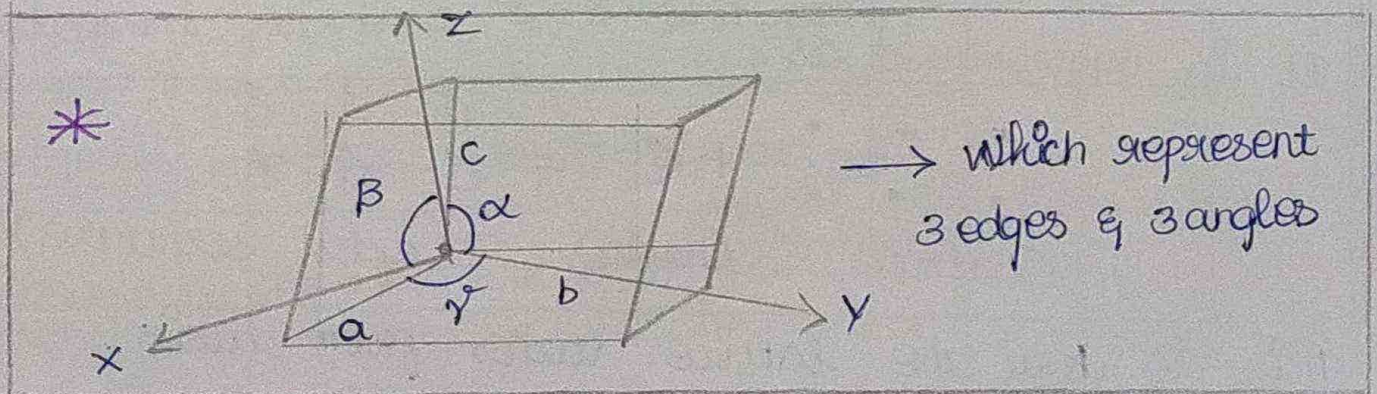
1) Primitive unit cell

2) centered unit cell

- Body centered unit cell

- Face centered unit cell

- End centered unit cell

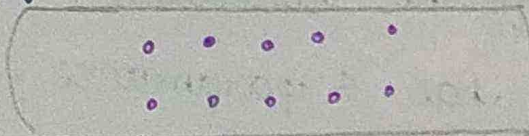


2) Define lattice and how it varies from basis?

* The crystal lattice is the symmetrical three dimensional structural arrangements constituent particle inside a crystalline solid as points.

* In a crystal lattice each atom or molecule is represented by single points. These points are called lattice site or lattice points. These points are joined by a straight line is crystal lattice.

* The crystal lattice is represented by



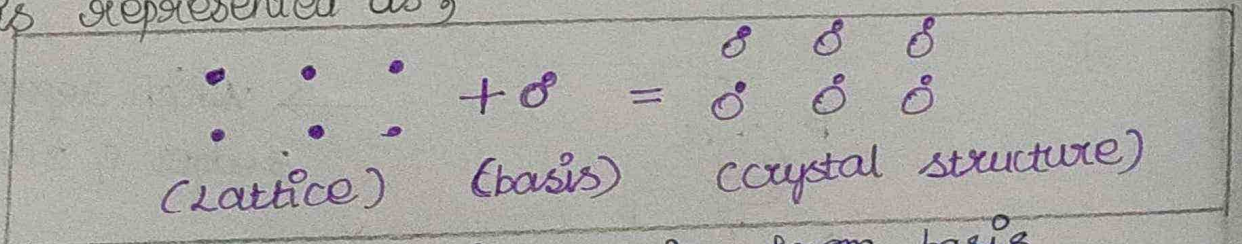
* The crystal basis is the arrangement of atoms that is particular to the mineral being considered.

LATTICE DIFFER FROM BASIS :-

* The lattice which is periodic arrangement of point in space it describe the structure of crystal

* The basis is a collection of atoms in particular fixed arrangement in space.

It is represented as,



This is how the lattice varies from basis.

3) What do you mean by Bravais lattice?

* Bravais lattice is a set of all equivalent atoms in a crystal that are able to be brought back into themselves when they are displaced by the length of the unit vector in a direction parallel to a unit vector.

* There are 14 types of Bravais lattices. They are not always primitive. They are classified according to symmetry and space rotation into the seven crystal systems.

* They are represented as, P, I, F, C. P - Primitive, I - BCC, F - FCC, C - End centered.

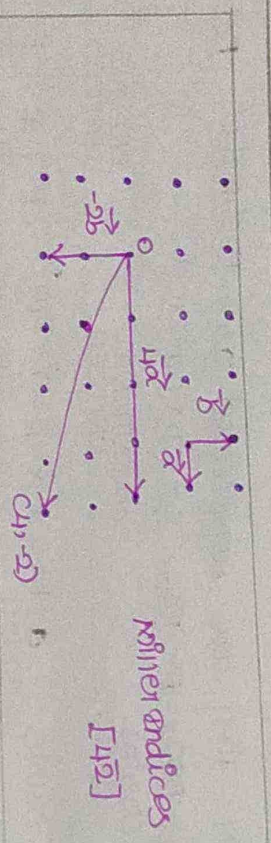
CRYSTAL SYSTEM	CONVENTIONAL UNIT CELL	BRAVAIS LATTICES			
Cubic	$a=b=c, \alpha=\beta=\gamma=90^\circ$	P	I	F	
Tetragonal	$a=b \neq c, \alpha=\beta=\gamma=90^\circ$	P	I		
Orthorhombic	$a \neq b \neq c, \alpha=\beta=\gamma=90^\circ$	P	I	F	C
Hexagonal	$a=b \neq c, \alpha=\beta=90^\circ, \gamma=120^\circ$	P			
Rhombohedral	$a=b=c; \alpha=\beta=\gamma \neq 90^\circ$	P			
Monoclinic	$a \neq b \neq c; \alpha=\beta=\gamma=90^\circ$ $\beta \neq 90^\circ$	P			C
Triclinic	$a \neq b \neq c; \alpha \neq \beta \neq \gamma$	P			

4) What are Miller indices?

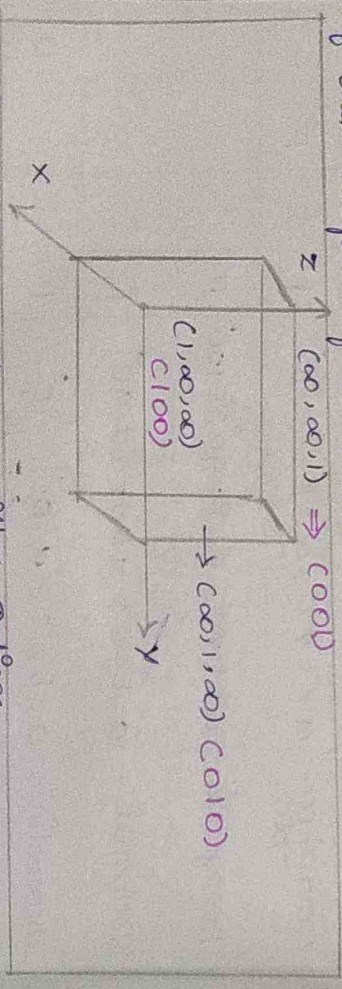
* Miller indices are a method of describing the orientation of a plane or set of planes with in a lattice in relation to the unit cell.

* It is a symbolic vector representation for the orientation of an atomic plane in a crystal lattice and are defined as the reciprocals for the fractional intercepts which the plane makes crystallographic axes.

MILLER INDICES FOR DIRECTIONS AND PLANE EXAMPLES :-



* Miller indices are the reciprocals of the parameters of each crystal face thus,



* these are called as Miller indices.

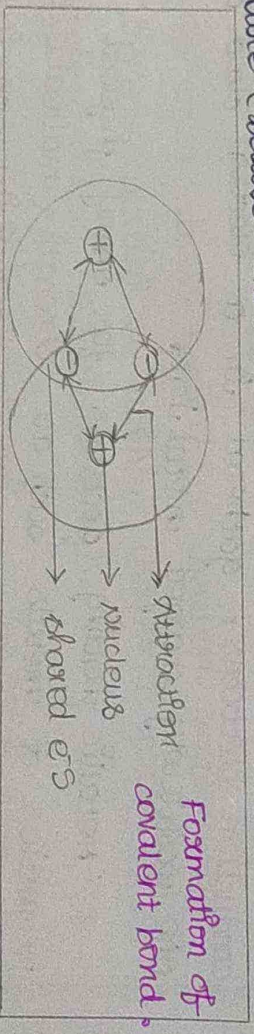
5) Define Covalent Bonding?

* Dr '1916', 'Lewis' suggested the covalent bonding phenomenon.

* A covalent bond is formed by equal sharing of electrons from both the participating atoms. The pair of electrons participating in this type of bonding is called shared pair or bonding pair.

* The covalent bonding among atoms in the sharing of electrons in their valence shells to attain the nearest noble gas configuration and to contribute the stability.

* The sharing will be among similar or dissimilar atoms. Bonding takes place between atoms with small differences in electronegativity which are close to each other in periodic table (between metals and nonmetals).

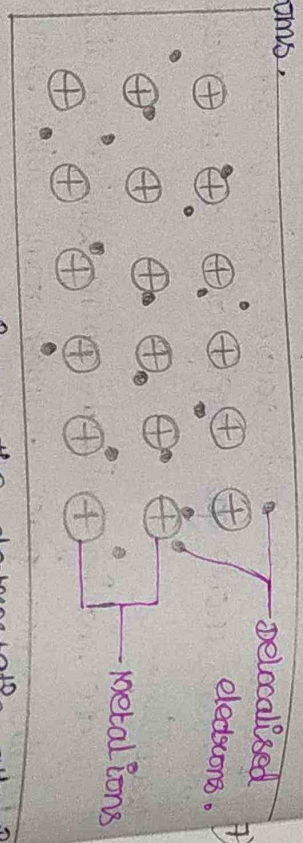


*** EXAMPLES :-**



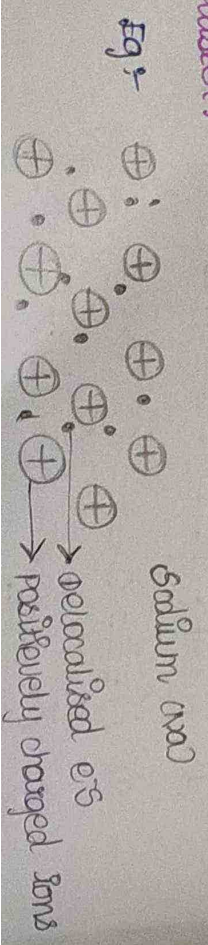
write about metallic bonding?

- * In metals each atom loses all its valence electrons and becomes a positively charged ion.
- * The free electrons form a electron cloud.
- * The electrons are like sea and the metal closely packed ions are immersed in the sea. The valence electrons move freely in the sphere of influence of other atoms.



* Metallic bond constitutes the electrostatic attractive forces between the delocalized electrons called **conduction electrons**, gathered in a electron cloud and the positively charged metal ion.

* Metallic bonding accounts for many physical properties of metals such as **strength, malleability, ductility, thermal and electrical conductivity, opacity and luster.**



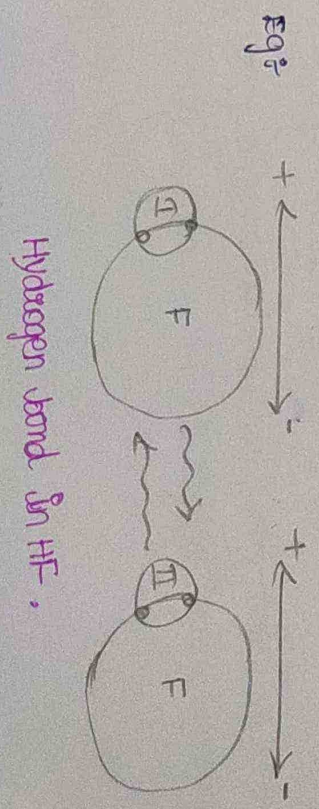
- * The factors that affect metallic bond strength are,
 - 1) The number of e⁻s delocalized from the metal; the greater the number of delocalized electrons the stronger the bond.
 - 2) Size of the cation the smaller the ionic radius, the greater the effective nuclear charge acting on the electron sea.

write short note on hydrogen bonding:

* A hydrogen bond is the attractive interaction of a **hydrogen atom** and a **electronegative atom**. such as **nitrogen, oxygen or fluorine**, that comes from another molecule or chemical group.

* The hydrogen has a **polar bonding** to another electronegative atom to create the bond.

* These bonds can occur between molecules (intermolecularly) or within different parts of a single molecule (intramolecularly).



Hydrogen bond in HF.

Part-B

WRITE ABOUT TYPES OF BRavais LATTICES :-

* Bravais lattice is a set of all equivalent atoms in a crystal that are able to be brought back into themselves when they are displaced by the length of the unit vector in a direction $n\hat{l}$ to a unit vector.

* There are 14 types of Bravais lattices. They are not always primitive. They are classified according to symmetry and space rotation into the seven crystal system.

* A Bravais lattice is an infinite array of discrete points with an arrangement and orientations that appears exactly the same, for whichever of the point array is viewed.

* A (3D) Bravais lattice consist of all points with position vectors R of the form

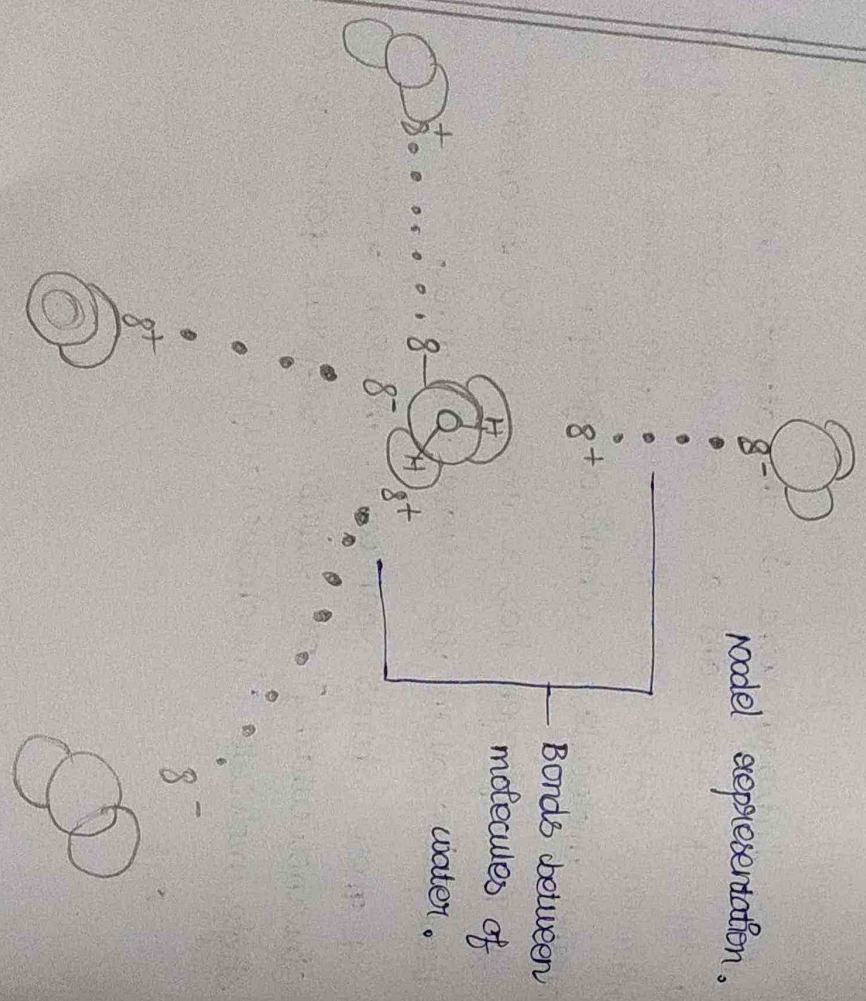
$$R = n_1 a_1 + n_2 a_2 + n_3 a_3 \rightarrow \text{①}$$

* Here, a_1, a_2 and a_3 are any three vectors not all in the same plane. n_1, n_2 and n_3 are any integral values.

* The hydrogen bond is stronger than a van der Waals interaction, but weaker than covalent or ionic bonds.

* This types of bond occur in both inorganic molecules such as water and organic molecules like alcohol.

* Another example is the hydrogen bond between molecules of water.



* Thus the point $\Sigma n_i a_i$ is reached by moving n_i steps of length a_i in the direction of a_i for $i=1, 2, 3$

* The vectors a_i are called primitive vectors and are said to generate or span the lattice.

* They are represented as P, I, F and C.

P - primitive, I - BCC, F - FCC, C - end (or) Base centers

CRYSTAL SYSTEM	CONVENTIONAL UNIT CELL	BRavais LATTICES		
		P	I	F
CUBIC	$a=b=c, \alpha=\beta=\gamma=90^\circ$	P	I	F
TETTRAGONAL	$a=b \neq c, \alpha=\beta=\gamma=90^\circ$	P	I	
ORTHORHOMBIC	$a \neq b \neq c, \alpha=\beta=\gamma=90^\circ$	P	I	F
HEXAGONAL	$a=b \neq c, \alpha=\beta=90^\circ, \gamma=120^\circ$	P		
TRIGONAL	$a=b=c, \alpha=\beta=\gamma \neq 90^\circ$	P		
MONOCLINIC	$a \neq b \neq c, \alpha=\beta=\gamma=90^\circ$	P		
TRICLINIC	$a \neq b \neq c, \alpha \neq \beta \neq \gamma$	P		

SYSTEM	BRavais LATTICE	CHARACTERISTICS OF SYMMETRY ELEMENTS
Simple Cubic	Simple Body-centered, Face-centered	Four 3-fold rotation axes (along cube diagonal)
tetragonal	simple, Body centered	one 4 fold rotation axis.
orthorhombic	simple, base-centered, body centered and Face centered.	Three mutually orthogonal 2-fold axis of rotation.
monoclinic	simple, base centered	one 2 fold axis of rotation.
triclinic	simple	none
trigonal	simple	one 3-fold rotation axis.
Hexagonal	simple	one 3-fold rotation axis.

2) WRITE ABOUT SIMPLE CUBIC CRYSTAL WITH EXAMPLE

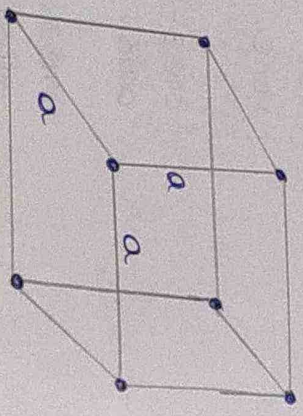
* Simple or primitive cubic lattice (sc) cell has one lattice point at the each corner of the unit cell.

* It has unit cell vectors $a=b=c$ and inter angles $\alpha=\beta=\gamma=90^\circ$.

* The simplest crystal structures are those in which there is only a single atom at each lattice point.

* In the sc structures the spheres fill 52% of the volume.

* The number of atoms in a unit cell is ①



* Let a be the edge length of the unit cell and r be the radius of sphere.

* As spheres are touching each other,

* Therefore $a=2r$. Number of spheres per unit cell = $\frac{1}{8} \times 8 = 1$

* Where the co-ordination number and packing factor be,

* Each corner of the atom touches four atoms in its horizontal plane, and two atoms one vertically above it and one vertically below it.

* So there are six equally spaced nearest neighbour atoms at each distance a from the atom. Therefore, the co-ordination number is six.

$CN=6$,

Packing factor = $\frac{\text{Volume of all atoms in the unit cell}}{\text{Volume of the unit cell}}$

= $\frac{\text{No. of atoms in unit cell} \times \text{Volume of one atom}}{\text{Volume of unit cell}}$

= $\frac{1 \times \frac{4}{3} \pi r^3}{(2r)^3}$

= $\frac{4\pi r^3}{3(2r)^3}$ ($\because a=2r$)

= $\frac{\pi}{6} = 0.52$

Packing factor = 52%.

- * It is a loosely packed structure.

Example 3-

* Platinum.

* Two adjacent Pt atoms contact each other, so the edge length of this length of Pt is equal to two Pt atomic radii: $l = 2r_1$.

* therefore, the radius of Pt atomic radii: $r_1 = 291$.

* density is given by $\text{density} = m/v$

* The density of platinum can be found by determining the density of its unit cell (the mass contained within a unit cell divided by the volume of the unit cell)

* since, Pt unit cell contains one-eighth of a Pt atom of each of its eight corners of a unit cell, containing one Pt atom.

* The mass of Pt: atom $M_2 = \frac{3.011 \times 10^{-25} \text{ g}}$

* The volume of Pt is $- 3.719 \times 10^{-23} \text{ cm}^3$

* therefore, the density of Pt = 9.169 g/cm^3

* The atomic radius r_1 of the a simple cubic (SC) structure.

$$2r_1 = a$$

$$r_1 = a/2$$

DIFFERENCE BETWEEN ELECTROVALENT AND COVALENT BOND.

COVALENT	ELECTROVALENT
<ul style="list-style-type: none"> • A covalent bond is a type of chemical bond that is formed due to electron sharing between two atoms. • The nature of a covalent bond is a direct chemical bond between two atoms. • The difference in the electronegativity values of the atoms should be lower than 1.7 in order to form a covalent bond. • The ions are not involved in the formation of a covalent bond (only atoms). • They have high polarity. 	<ul style="list-style-type: none"> • Electrovalent bond is a type of chemical bond that can be defined as an electrostatic attraction between two atoms. • The nature of electrovalent bond is a type of electrostatic attraction between two atoms. • The difference in the electronegativity values of the atoms should be higher than 1.7 in order to form an electrovalent bond. • Ions are involved in the formation of a electrovalent bond. • They have low polarity.

- they have a definite shape.
- in which the liquid or gas will be at room temperature.

- the melting and boiling points are high due to internal energy. many covalent bonds must be broken if the solid is to be melted but a large amount of thermal energy is required.

- these are mostly poor conductors because electrons are held either on the atoms or within the covalent bonds. they cannot move through the lattice.

- most covalent substances are brittle.

- they don't have a definite shape,

- in which the solid will be at a room temperature.

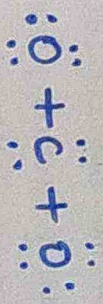
- very high melting points due to strong bonding among atoms due to internal energy.

- solid compounds don't conduct electricity when a potential is applied because there are no mobile charge particles.

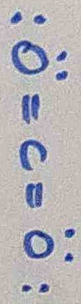
- most substances are brittle.

EXAMPLE :

CO₂ :



(gas)



- they are soluble in non-polar solvents

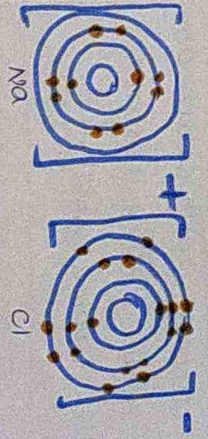
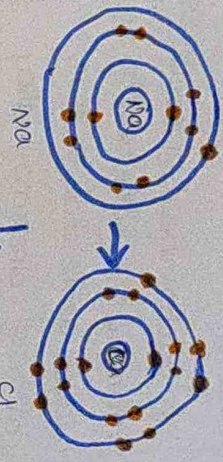
Example explanation :

- the Lewis structure of CO₂ in double bond the CO₂ has total 1 carbon atom and 2 oxygen atoms.

- Each oxygen atom has a valence electrons whereas the carbon atom only has the

EXAMPLE :

NaCl :



- they are soluble in polar solvents like water due to strong attraction among ions.

- when sodium loses its one valence e⁻s gets smaller in size, while Cl goes larger when it gains an additional valence electrons.

- after the reaction takes place the charged Na⁺ & Cl⁻ ions are held together by

- If valence electron to satisfy the octet rule.

- carbon need 4 more electrons as it has 4 valence electrons. since each carbon atom has 3 lone pairs of electrons, they can be each share 1 pair of electrons with carbon as a result, filling carbon's outer valence shell.

- electrostatic force from a ionic bond.

- when they approach, close the orbitals of electrons begin to overlap each other then electrons repel each other by virtue of the repulsive electrostatic force.

4) DESCRIBE MILLER INDICES WITH EXAMPLES:

- Miller indices are used to specify directions and planes.

- these directions and planes could be in lattice or in crystals.

- the number of indices will match with the dimension of the lattice or the crystal.

- eg. In 2D there will be two axes and 2D there will be two indices.

- $[hkl]$ - represents a direction.
- $\langle hkl \rangle$ - represents a family of directions.

- (hkl) represents a plane
- $\{hkl\}$ represents a family of planes.

MILLER INDICES FOR DIRECTION:-

- A vector or passing from the origin to a lattice point can be written as;

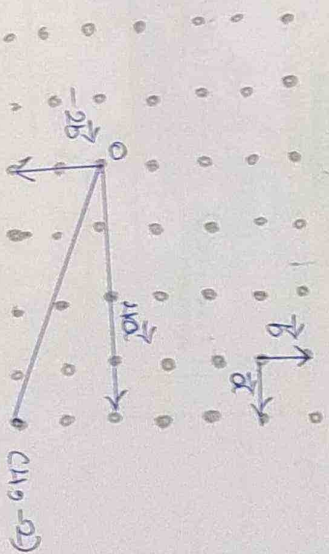
$$r_1 = x_1 a + y_1 b + z_1 c$$

where, a, b, c - basic vectors and (x_1, y_1, z_1) - miller indices.

indices:

- Fractions in (x_1, y_1, z_1) are abbreviated by multiplying all components by their common denominator.

- eg. $(1, 3/4, 1/2)$ will be expressed as $(4, 3, 2)$



Miller indices $\rightarrow [1 \ 3/4]$

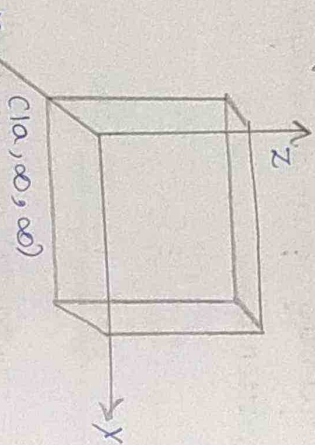
MILLER INDICES FOR PLANES

- Consider the plane which is one of a infinite number of parallel planes each a consistent distance (a)

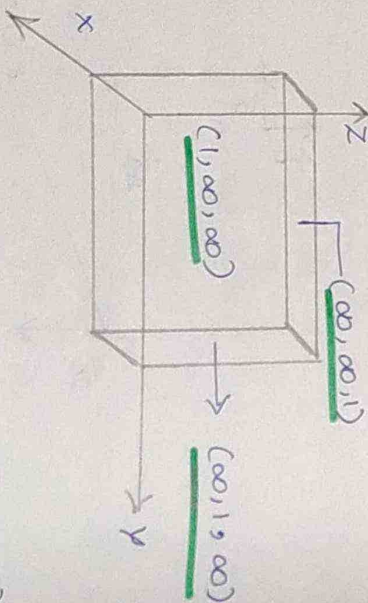
away from the origin.

* The plane intercepts the x axis at point a, parallel along y and z axes.

* Thus, this plane can be designated as $(1/a, \infty, \infty)$



likewise it can be designated the left side as $(\infty, 1, \infty)$ and the upper plane can be written as $(\infty, \infty, 1)$



* where, $(1, \infty, \infty) = (100)$, $(\infty, \infty, 1) = (001)$ and $(\infty, 1, \infty) = (010)$

* The intercepts of the lattice planes along the x, y and z axes, then take the reciprocals of the intercepts and obtain their lowest integer ratios.

FAMILY OF DIRECTIONS:

It is a set of directions related by symmetry operations.

Index	Members in family for cubic lattice.
$\langle 100 \rangle$	$[100], [\bar{1}00], [010], [0\bar{1}0], [001], [00\bar{1}]$
$\langle 110 \rangle$	$[110], [\bar{1}10], [1\bar{1}0], [\bar{1}\bar{1}0], [101], [10\bar{1}], [110], [1\bar{1}0], [011], [0\bar{1}1], [01\bar{1}], [0\bar{1}\bar{1}]$
$\langle 111 \rangle$	$[111], [\bar{1}11], [1\bar{1}\bar{1}], [11\bar{1}], [\bar{1}\bar{1}\bar{1}], [1\bar{1}1], [\bar{1}1\bar{1}], [\bar{1}\bar{1}1]$

IMPORTANCE OF MILLER INDICES:

* It is important to have a notation system for atomic planes since these planes influence.

- optical properties
- Reactivity
- surface tension
- Dislocations.

* This is called as Miller indices. It is used as a symbolic representation for the orientation of an atomic plane in a crystal lattice and are defined as the reciprocals for the fractional intercepts.

Some of the multiplicity factors are:

cubic	hkl 48	hhl 24	hko 24	hho 12	hhh 8	hoo 6	ool 6
Hexagonal	hk.l 24	hh.l 12	h.o.l 12	hk.o 12	hh.o 6	ho.o 6	oo.l 2
trigonal	hkl 16	hhl 8	hol 8	hko 8	hho 4	hoo 4	ool 2
orthorhombic	hkl 8	hko 4	hol 4	hko 4	hho 2	hoo 2	ool 2

5) WRITE ABOUT VANDERWAALS BONDING:-

* A weak dipole-dipole interaction is the origin of the van der Waals bond, which is therefore characterized by a low cohesive energy and so low melting temperatures.



* Also spontaneous dipole formation in one atom may induce an equal and opposite dipole in another atom nearby.

* Another type of van der Waals bonding is observed for certain polar molecules that have permanent dipole. The van der Waals potential energy can be approximated as

$$E(r) = \frac{A}{r^n} - \frac{B}{r^m}$$

- 1st term - classical dipole-dipole interaction as r⁶.
- 2nd term - repulsion for small r.
- 1st term - repulsion for small r.

* On the equation, a & b are empirical parameters as in n. If we equilibrium we have r₀ and E(r₀) are the equilibrium separation and energy for a stable bond to form E(r₀) must be negative thus

$$\frac{dE}{dr} = 0 \therefore r_0 = \left[\frac{nA}{mB} \right]^{\frac{1}{n-m}} \text{ and } m < n$$

$$E(r_0) = \frac{B}{r_0^m} \left[\frac{m}{n} - 1 \right]$$

Some downward goes potential - in which the minimum interaction energy and its distance.

	r ₀ (Å)	E(r ₀)
He	2.02	1 × 10 ⁻²²
H ₂	2.04	4
O ₂	3.02	15
N ₂	3.1	13
CO ₂	4.5	40

* Once a random dipole is formed in one atom, an induced dipole is formed in the adjacent atom. This is the type of bonding present in H_2 molecules and it is known as vanderwaals bonding.

* Vanderwaals force include attractions and repulsions between atoms, molecules and surfaces as well as other intermolecular forces. They differ from covalent and ionic bonding in that they are caused by covalent and ionic bonding in that they are caused by nearby positive, in the fluctuating polarizations of nearby particles.

* Hydrogen bonds occur in biogenic molecules such as water and organic molecules such as DNA and proteins.

* Vanderwaals attractions van occur between any two or more molecules and are dependent on slight fluctuations of the electron densities.

* Three types of vanderwaals force, D dispersion, dipole-dipole and hydrogen.

* Vanderwaals interaction is the weakest of all intermolecular attractions between molecules.

* However, with a lot of vanderwaals force interacting between two object, the interaction can be very strong.

* Spontaneous dipole formation is one atom may induce an equal & opposite dipole in another atom nearby so causing attraction. This is the vanderwaals bond.

* Another type of vanderwaals bonding is observed for certain polar molecules that have a permanent dipole moment.

* Although unlinked atoms are electrically neutral electrons with them are in a constant state of motion and so may momentarily form small charge dipoles.

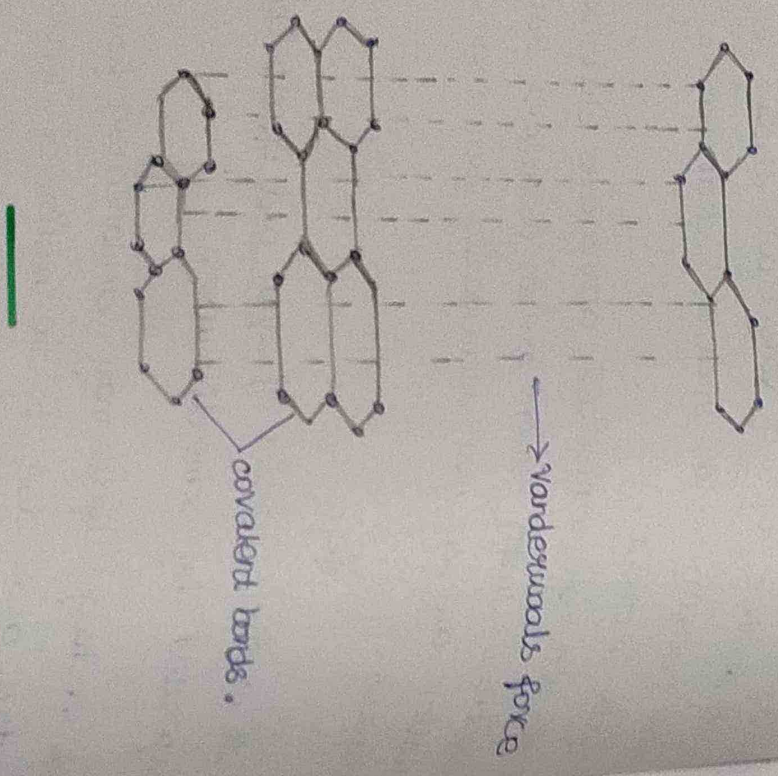


* A dipole consist of equal and opposite charges separated by some distance.

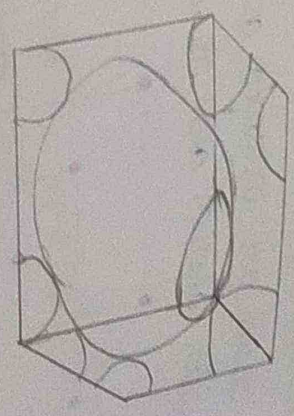
* A charge dipole may spontaneously form in a neutral atom due to the motion of electrons around the nucleus.

* The direction and magnitude of this dipole constantly fluctuates but may induce similarly fluctuating dipoles in other atoms.

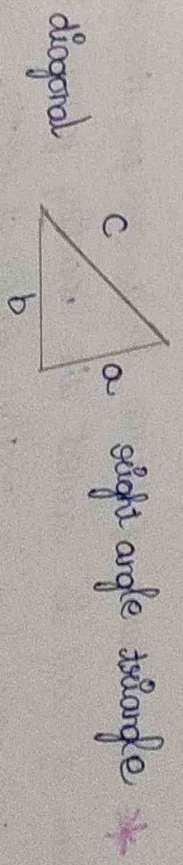
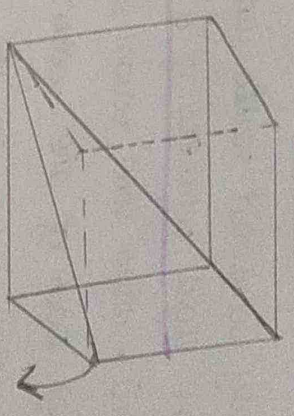
Graphenes bonding forces in graphite :-
 * weak forces between graphenes suggest that they are the vanderwaals forces.



Structure include Strontium, Radium, Francium, Barium, Caesium, Aluminium, Thorium, Vanadium, Alpha iron or Iron pyrites.
 * Metals have a bcc structure are usually harder and less malleable than close-packed metal such as fcc.



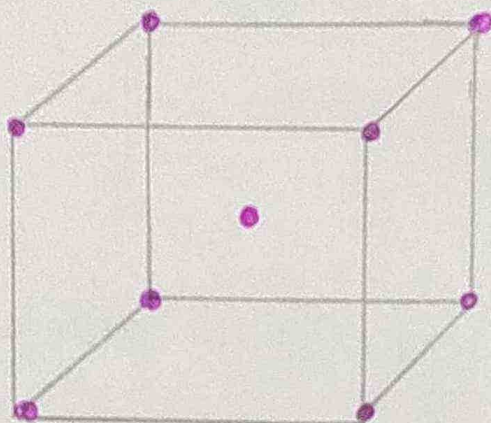
Determination of unit cell length and atomic radius for bcc!



1) Describe Bcc and Fcc with Examples &

BODY CENTERED CUBIC &

* The atoms are arranged at the centers of the cube with another atom at the cube centre.



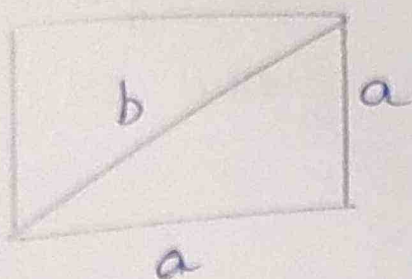
8 corner atoms one atom at the centre.

* The body centered cubic unit cell has atoms at each of the eight corners of a cube. (like the cubic unit cell) + plus one atom in the centre of the cube. Each of the corner atoms in the corner of another cube so the corner atoms are shared among eight unit cell.

* The volume of atoms in a cell per the total volume of cell is called the packing factor. The bcc unit cell has a packing factor of 68%.

* some of the materials that have a bcc

But at the base, the diagonal is,



$$b^2 = a^2 + a^2$$

$$b = \sqrt{2a^2}$$

$$b = \sqrt{2}a$$

For c , $c^2 = a^2 + b^2 = a^2 + (\sqrt{2}a)^2$

$$c^2 = a^2 + 2a^2 = 3a^2$$

$$c^2 = 3a^2$$

$$c = \sqrt{3a^2}$$

$$c = \sqrt{3}a$$

The diagonal $c = \sqrt{3}a$

$$c = 4R$$

$$c = \sqrt{3}a$$

$$a = \frac{4}{\sqrt{3}}R$$

$$\text{The atomic radius } a = \frac{4}{\sqrt{3}}R$$

The atomic packing factor for BCC is

* The atomic packing factor for BCC structure

is given by,

$$\text{APF} = \frac{\text{Total number of atoms}}{\text{volume of unit cell.}}$$

we know that,

$$= 1 \text{ body atom} + 8 \text{ corner atoms}$$

$$= 1 + 8 \left(\frac{1}{8}\right)$$

$$= 1 + 1$$

$$= 2 \text{ atoms}$$

$$a = \frac{4R}{\sqrt{3}} a$$

$$\text{APF} = \frac{2 \text{ atoms} \left(\frac{4}{3} \pi R^3\right)}{a^3}$$

$$a = \frac{4R}{\sqrt{3}} a$$

Applying it we get,

$$= \frac{2 \left(\frac{4}{3} \pi R^3\right)}{\left(\frac{4R}{\sqrt{3}}\right)^3}$$

$$= \frac{\frac{8}{3} \pi R^3}{\frac{4^3 R^3}{(\sqrt{3})^3}}$$



$$= \frac{8\pi (\sqrt{3})^3}{3(4^3)}$$

$$= 0.68$$

$$= 68\%$$

$$= 68\%$$

The atomic packing factor of a unit cell is i.e.)
the volume of space occupied is 68%

BCC structures stronger and brittle?

* Although BCC materials have higher number of slip systems than FCC, the slip planes are not closely packed. In FCC, the slip planes are not closely packed it is at the same homologous temperature.

* ductile and brittle are relative terms, since the deformation of a material and the corresponding mode of failure depends on the many conditions in addition to crystal structure such as stress, rate of loading and ambient temperature among things.

* BCC metals they do have slip systems, consisting of the $\{110\}$, $\{12\bar{2}\}$ and $\{11\bar{2}\}$ family of planes, each with their own preferred direction of slip fail to exhibit the extent of ductility as shown by FCC metals.

* This is because BCC structure is not a close packed one the slip planes are of the highest planar density but not close packed.

* This leads to increased activation energies for dislocation motion along a slip direction as compared to FCC.

* However, at elevated temperatures, they typically brittle BCC transitions into a relatively ductile material.

* At temperatures below the ductile-brittle transition temperature of the fracture toughness is exceeded before the stress is sufficient to induce dislocation motion and brittle fracture is observed.

* These observed reasons shows that BCC are strong and brittle.

EXAMPLES ?

- one of the example for bcc is chromium (Cr).
- chromium is a metal in group VI B of the periodic table with atomic number 24, an atomic weight of 51.996 and a density of 7.19. It has a melting temperature of 1875°C.
- The electronic configuration for chromium is (Ar)(3d)⁵(4s)¹ and it has an atomic radius of 0.13 nm (0.130 nm).
- At room temperature chromium has a bcc crystal structure with a basis of one Cr atom.

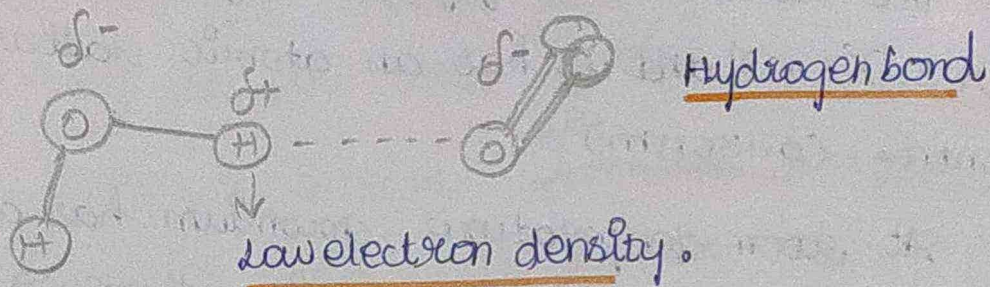
$$E = \underline{248 \text{ GPa}}$$

Formula	→	<u>Cr</u>
lattice type	→	<u>Body centered cubic</u>
group	→	<u>group 6</u>
Melting point	→	<u>2180 K (1907°C, 3465°F)</u>
Boiling point	→	<u>2944 K (2671°C, 4840°F)</u>
Density	→	<u>7.199/cm³</u>

- Some other example of bcc be Cr, W, Fe (α)
Ta, Mo etc.

2) Describe in detail about hydrogen bonding:

* A hydrogen bond is a dynamic attraction between a pair typically electronegative atoms involving a hydrogen atom located between them. Hydrogen bonds are responsible for the life-giving properties of water.



* Polar molecule such as water molecules have a weak, partial negative charge at one region of the molecule (the oxygen atom in water) and a partial positive charge elsewhere (the hydrogen atoms in water).

* The water molecule (O-H) bond is highly polar bond.

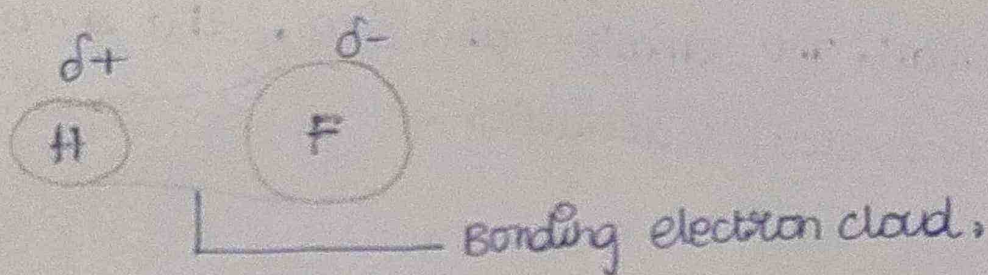
* Hydrogen has no inner shell electron and is very small in size, the positive charge density developed is high.

* The nucleus of hydrogen atom is exposed to attraction by nearby electron cloud, a lone pair of

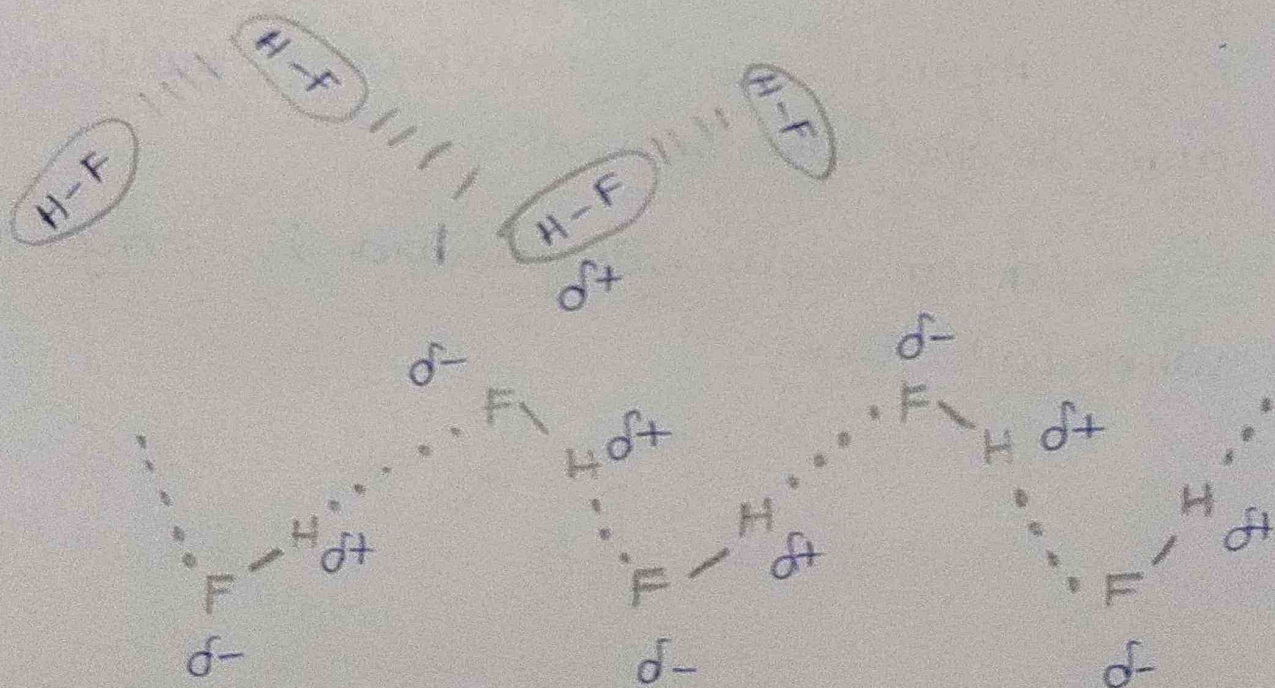
electrons on the electronegative atom

* Hydrogen bonding is a special case of dipole-dipole interactions.

* when hydrogen bonded to a highly electronegative atom (such as nitrogen, oxygen, fluorine), the bonding electron pair is drawn towards the electronegative atom.



Hydrogen bonding in Hydrogen fluoride,



Hydrogen fluoride (HF)

condition for H-Bonding :-

- A hydrogen atom must be directly bonded to a highly electronegative atom (eg. F, O and N)
- An unbonded pair of electrons (lone pair electrons) is presented on the electronegative atom.
- The size of the electronegative atom should be small. The smaller the size, the greater is the electrostatics attraction.

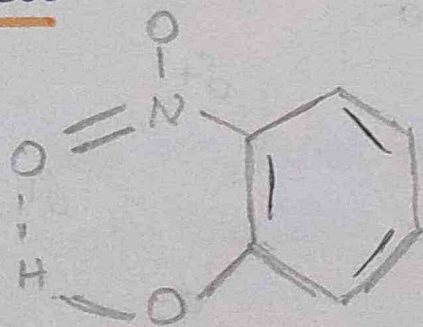
Intermolecular hydrogen bond :-

- Hydrogen bond formed between two molecules.

Intramolecular hydrogen bond :-

- Hydrogen bond formed between two different atoms in the same molecule.

- Intermolecular hydrogen bond is stronger than a vanderwal's forces.



- Even though hydrogen bond is a weaker bond.

Strength of hydrogen bond :-

● Hydrogen bonding is very weak bond. The strength of hydrogen bond is intermediate between the weak van der Waal's forces and the strong covalent bonds. Thus whereas the bond dissociation energy of a covalent bond is 209-418 kJ/mol. That for H-bond is only 12.6-41.8 kJ/mol.

Explanation :-

* In H_2O_2 there are intermolecular hydrogen bonds between molecules.

* However, in H_2S , H_2Se and H_2Te the interaction between molecules is dipole-dipole interactions.

* The strength of hydrogen bond is stronger than dipole-dipole interactions.

* To break the hydrogen bonds, more energy is required.

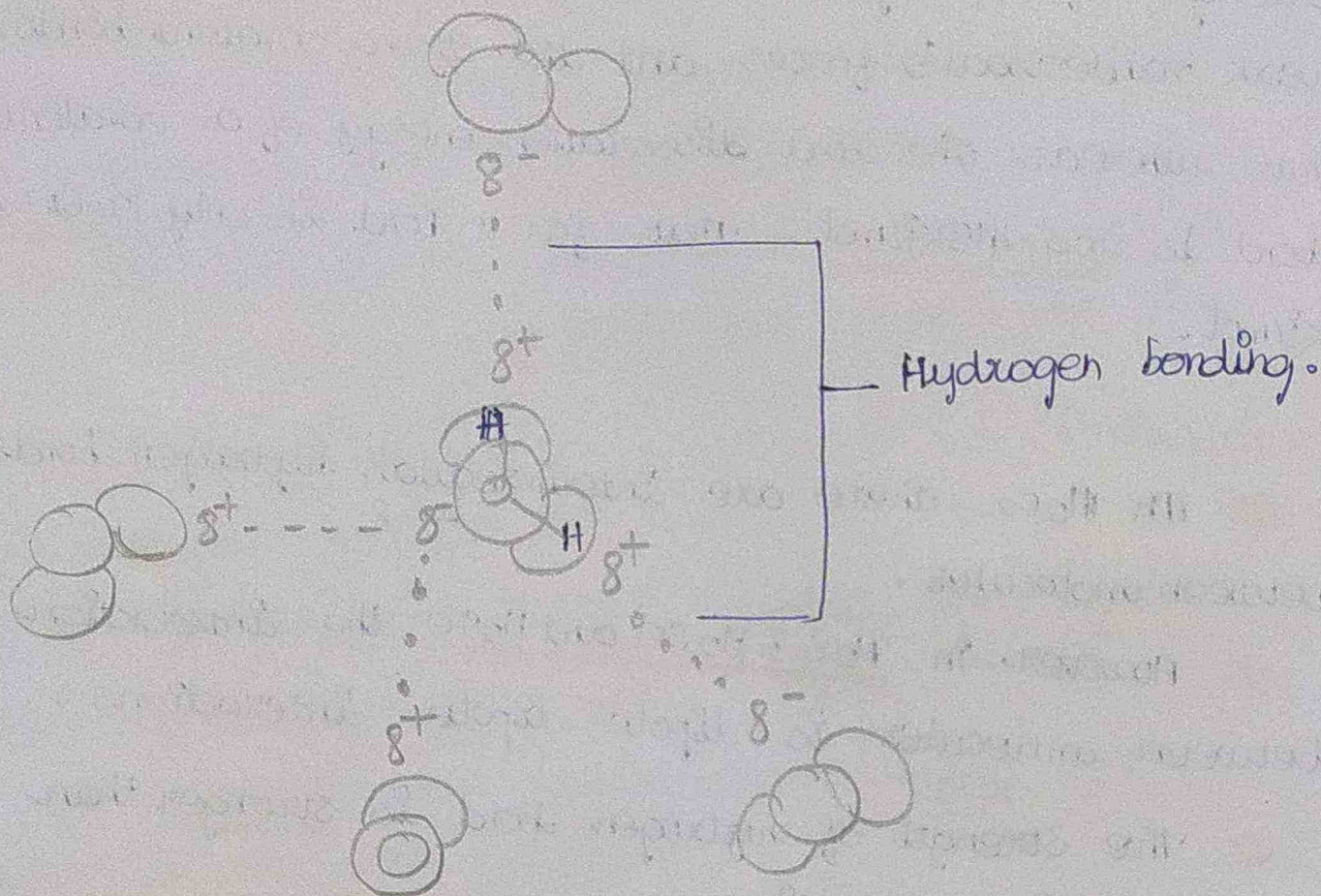
* H_2O has the largest enthalpy change of vaporization.

Consequences of H-bond :-

● High melting and boiling points :-

● The compound having H-bond show abnormally high melting and boiling point.

♦ Due to the containing hydrogen bond to the fact that some extra energy is needed to break these bonds.



* As hydrogen attached to carbon atom can also participate in hydrogen bonding when the carbon atom is bound to electronegative atoms as in the case in chloroform CHCl_3 .

* the electronegative atom attracts the electron cloud from around the hydrogen nucleus and by decentralizing the cloud leaves the atom with a

positive partial charge.

* Because of the small size of hydrogen relative to other atoms and molecules.

* The resulting charge through only partial represent a large density.

* A hydrogen bond results when this strong positive charge density.

* Attracts a lone pair of electrons on another heteroatom which becomes hydrogen-bond acceptor.

properties :

- 1) Hydrogen bonds are directional
 - 2) These bonds have low melting points.
 - 3) They are good insulators.
 - 4) They are soluble in polar and non-polar solvents
 - 5) They are transparent to light.
 - 6) These are stronger than dispersion bond
 - 7) Solids may be crystalline or non-crystalline.
-

UNIT-2: 'Two Mark Questions'

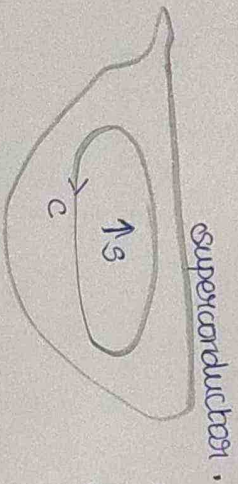
1) What is Meissner's effect?

* When the superconducting material is placed in a magnetic field under the condition when $T < T_c$ and $H \leq H_c$, the flux lines are excluded from the material. It explains as follows,

* There is another much more fundamental characteristics which distinguishes the super conductor from a normal but ideal conductor.

* The superconductor expels magnetic flux. i.e.,

$$\boxed{B=0}$$



The nature of superconducting $C_s \sim e^{-BA}$

$$0 = \oint \mathbf{E} \cdot d\mathbf{l} = \int \nabla \times \mathbf{E} \cdot d\mathbf{s}$$

$$= \int \nabla \times \mathbf{E} \cdot d\mathbf{s}$$

$$\boxed{V = -\frac{1}{c} \int \frac{\partial B}{\partial t} \cdot d\mathbf{s}}$$

* Since s and c are arbitrary.

$$0 = -\frac{1}{c} \int \mathbf{B} \cdot d\mathbf{s}$$

$$\boxed{B=0}$$

Thus, for an ideal conductor, it matters if the field cooled or zero field cooled.

$$B = \mu H = 0 \Rightarrow H = 0$$

$$\mu = \chi H = \frac{\mu - 1}{4\pi} H$$

$$\boxed{\chi_s c = -\frac{1}{4\pi}}$$

$$\boxed{M = -\frac{1}{4\pi} H_{ext}}$$

Ideal conductor

zero-field cooled

$$T > T_c$$

$$B \neq 0$$



field cooled:

$$T > T_c$$

$$B \neq 0$$



$$T < T_c$$

$$B = 0$$



$$T < T_c$$

$$B \neq 0$$



$$T < T_c$$

$$B \neq 0$$



$$T < T_c$$

$$B = 0$$



2) What do you mean by superconductivity?

* The phenomenon of superconductivity in which the electrical resistance of certain materials completely vanishes at low temperature is one of the most interesting and sophisticated condensed

matter in physics.

* It was discovered by the Dutch physicist

Heike Kamerlingh Onnes, who was the first to liquefy helium which boils at 4.2 K (at std pressure).

* On 11/11/111 Kamerlingh Onnes and one of his assistants discovered the phenomenon of superconductivity while studying the resistance of metal at low temperatures

* they studied mercury because very pure sample could easily be prepared by distillation.

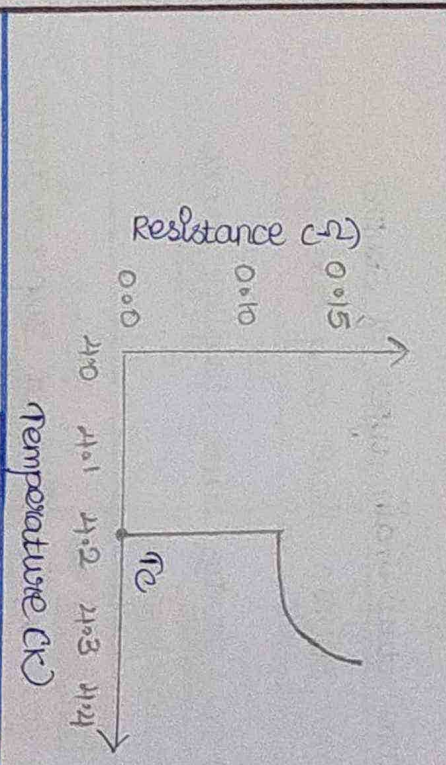
* As in many other metals, the electrical resistance of mercury decreased steadily upon cooling, but dropped suddenly at 4.2 K and became undetectably small.

* Many other elemental metals were found to exhibit zero resistance when their temperatures were lowered below a certain characteristic temperature of the material called the critical temperature T_c

High- T_c super conductor $T_c(K)$

- $\text{Nb}_2\text{Ba}_2\text{Co}_2\text{Cu}_2\text{O}_{10+x}$ 125
- $\text{HgBa}_2\text{Ca}_2\text{Cu}_2\text{O}_8+x$ 135
- $\text{Hg}_0.8\text{Tl}_{0.2}\text{Ba}_2\text{Ca}_2\text{Cu}_2\text{O}_8.33$ 134

* The phenomenon of losing resistivity when sufficiently cooled to a very low temperature.

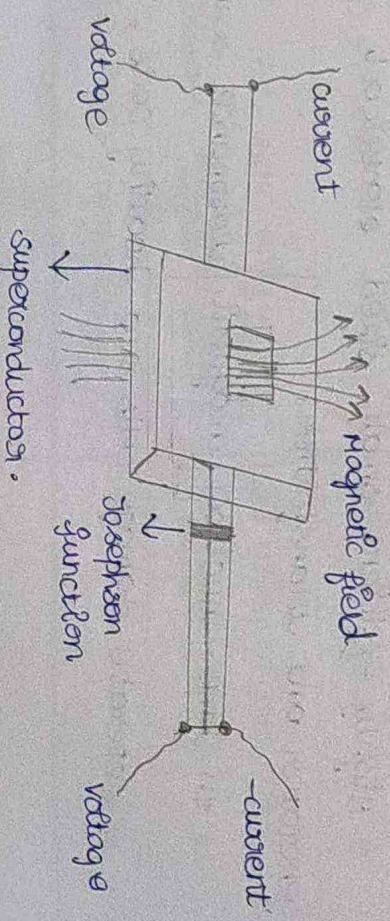


3) Define SQUID :-

* SQUID - Superconducting Quantum Interference Devices.

* A SQUID is the most sensitive type of detector known to science, consisting of a superconducting loop with two Josephson junctions.

* SQUIDs are used to measure magnetic fields.



* It has a principle of small change in magnetic field produces variation in the flux quantum.

* There are two main types of superconducting junctions.

1) DC SQUIDS have only one Josephson junction.

2) AC SQUIDS have two or more junctions.

4) Write any four applications of superconductors:

- Larger distance power transmission (e.g.)
- Switching device (easy destruction of superconductivity).
- Sensitive electrical equipment (small variation in magnetic field).

→ Large constant current).

- memory / storage element (persistent current)
- Highly efficient small sized electrical generator and transformer.

- On MRI - nuclear magnetic resonance scanning.
- separate damage cells and healthy cells.

FIVE MARK QUESTIONS

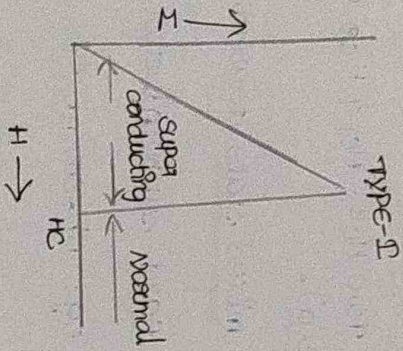
Difference between TYPE I and TYPE II superconductors.

TYPE-I	TYPE-II
* Sudden loss of magnetisation.	* Gradual loss of magnetisation.
* Exhibit Meissner's effect.	* Does not exhibit Meissner's effect.
* one H _c - 0.1 tesla	* two H _c - H _{c1} & H _{c2} (≈ 30 tesla).
* in normal state	* mixed state present
* soft superconductor	* hard superconductor.
• Eg: Pb, Sn, Hg	• Eg: Nb ₃ Sn, Nb-Ti
* These are <u>perfect</u> diamagnetics.	* These are <u>not perfect</u> diamagnetics.
* They have only one <u>critical magnetic field</u> .	* They have <u>two critical magnetic fields</u> .
* These materials undergoes a sharp transition from the	* These materials undergoes a gradual transition from

superconducting state of the normal state at the critical magnetic field.

* The highest value of critical magnetic field is 0.1wb.

* applications are very limited.



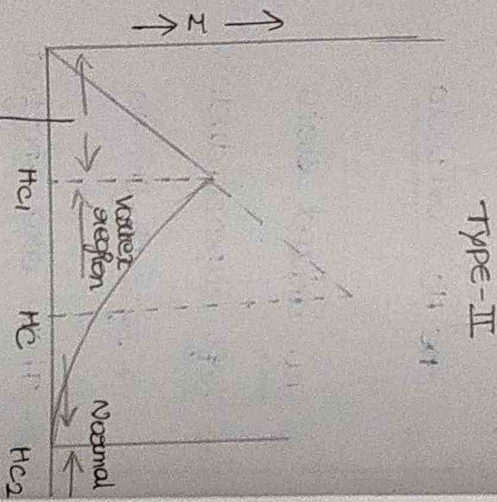
* As seen from magnetization curve, transition at H_c is reversible. If H_c is again lowered below H_c the material again becomes superconducting.

Eg: Pb, Sn, Hg

the superconducting state to the normal between the two critical magnetic fields.

* The upper critical field can be of the order of 5wb

* they are used to generate very high magnetic field.



* As seen from magnetization curve, transition at H_c is not reversible.

Eg: Nb-Sn, Nb-Zr

29

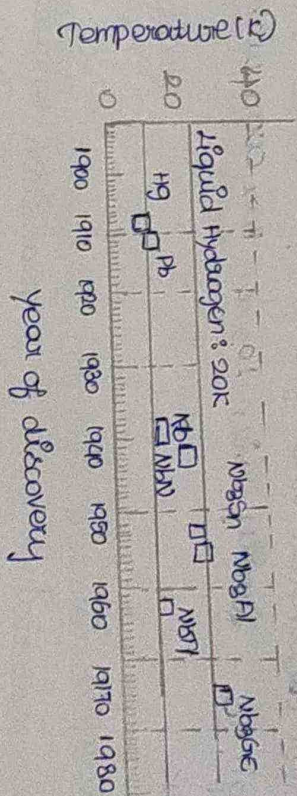
Visible states on high temperature superconductors - superconductivity?

* The phenomenon of losing resistivity when sufficiently cooled to a very low temperature.

* It was discovered by Heike Kamerlingh Onnes, Leiden (1908). \rightarrow for liquefaction of Helium.

* The superconductivity: ideal conductivity was discovered by Hilm on 1911.

* Many metals becomes superconducting at low temperatures.



High Temperature Superconductors :-

* It has been long dream of scientist working in the field of superconductivity.

* to find a material that becomes a superconductor at room temperature.

* A discovery of this type will revolutionize every aspect becomes a superconductor at some of modern day technology such as power transmission and storage communication, transport and even the type of computers we make.

* Any superconductor with a transition temperature above 30K is in general called high T_c superconductor.

* Till the year 1986, the highest known transition temperature T_c was 30K in the Nb₃Ge alloy.

* Till the year 1986 the H. Bednorz and Müller discovered the first superconductor of the high T_c family viz, LaO_{2-x}F_x Ba_{1-x}CO₃ with T_c of 35K.

Examples :-
Material transition temperature (K)

- La_{1.85}Ba_{0.15}CO₃ 36
- YBa₂CU₃O₇ 90
- Tl₂Ba₂CU₂O₈Cl₂ 125

Characteristics :-

* They have high transition temperatures (T_c) and high accompanied by high critical currents (I_c) and high critical magnetic field (H_{c2})

* They have a modified perovskite crystal structure. The structure is highly anisotropic.

* They are oxides of copper in combination with other elements. They have a layered structure consisting of one or more CuO₂ layers.

* The most important characteristic of high T_c superconducting oxides is their metallic properties.

* The conductivity is much smaller in a direction perpendicular to CuO₂ planes.

Preparation of high T_c ceramic superconductors
YBa₂CU₃O_{7-x}.

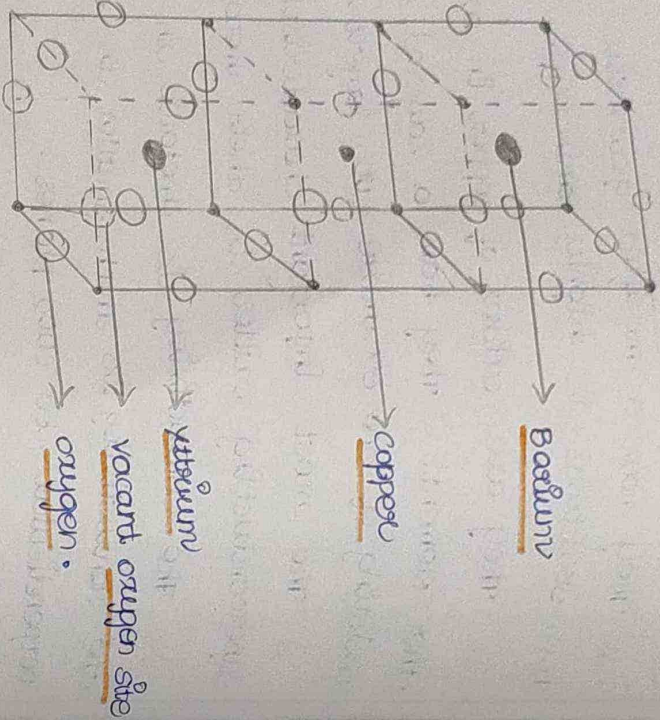
* The preparation of yttrium barium copper oxide superconductors by the shake and bake method. This method involves a few step process.

- 1) mixing the chemicals
- 2) calcination (initial firing).

2)

3) The Intermediate ferrite
 4) The final oxygen annealing.

crystal structure of $(YBaCu_3O_{7-x})$



* Three body centered cubic unit cells are stacked one above another.

* The atom distributions in the unit cell are:

• copper atom at body corners = $8 \times \frac{1}{8} \times 3 = 3$

• Barium = $1 \times 2 = 2$, Yttrium $\Rightarrow 1 \times 1 = 1$

• oxygen atom at midpoint of edges

$12 \times \frac{1}{4} \times 3 = 9$

Some oxygen positions are vacant such that their number is between 6.5 and 7.

* The superconducting properties appear to be a sensitive function of the oxygen content and therefore of the partial pressures of oxygen during heat treatment.

Applications:

- large distance power transmission (e.g.)
- switching device (easy destruction of superconductivity)
- sensitive electrical equipment (small voltage drop \rightarrow large constant current).
- memory / storage element (persistent current)
- highly efficient small sized electrical generator and transformer.

3) Meissner London equation:

* In Meissner's effect that one of the conditions for the superconducting state is the magnetic flux density $(B) = 0$.

* In this condition, enable the superconductor that is the magnetic flux cannot penetrate.

* The magnetic flux does not suddenly drop to zero inside the surface.

* The phenomenon of flux penetration inside the superconductor was explained by H. London and F. London.

London Fierz equation :-

* Let n_s and v_s be the number density and velocity of superconducting state electrons.

* The equation of motion or acceleration of electrons in the superconducting state is given by,

$$m(n_s \frac{dv_s}{dt}) = -eE$$

(1)

$$\frac{dv_s}{dt} = -eE/m \rightarrow (2)$$

m - mass of electrons, e - charge

current density $\Rightarrow J_s = -ne_s v_s$

* Differentiate it with respect to time,

$$\frac{dJ_s}{dt} = -ne_s \frac{dv_s}{dt} \Rightarrow (3)$$

* Put equation (2) in above equation we get,

$$\frac{dJ_s}{dt} = (ne_s e^2 E) / m$$

$$-ne_s \frac{dv_s}{dt} = ne_s e^2 E / m$$

$$\frac{dJ_s}{dt} = (ne_s e^2 E) / m \rightarrow (2)$$

Equation (2) is known as London's Fierz equation.

London second equation :-

* Take curl (that is cross or vector product) of London's first equation we get,

$$\nabla \times \frac{dJ_s}{dt} = [ne_s e^2 \nabla \times E] / m \rightarrow (3)$$

* By differential form of Faraday's law of electromagnetic induction (or Maxwell's third equation),

$$\text{curl } E = -dB/dt$$

$$\nabla \times E = -dB/dt$$

Substitute in (3) we get,

$$\nabla \times \frac{dJ_s}{dt} = -[ne_s e^2 (dB/dt) / m]$$

* Integrate both sides with respect to time, we get,

$$\nabla \times J_s = -[ne_s e^2 (B) / m] \rightarrow (4)$$

* This is known as London's second equation.

Flux penetration from London equation :-

* To explain Meissner effect from London equations consider the differential form of Ampere's circuital law.

$$\nabla \cdot B = \mu_0 J_s$$

where, B is magnetic flux density,
 J_s is current density.

Take curl on both sides of above equation,

$$\nabla \times (\nabla \cdot B) = \mu_0 (\nabla \times J_s) \rightarrow \textcircled{5}$$

$$\text{As, } \nabla \times (\nabla \times B) = \nabla (\nabla \cdot B) - \nabla^2 B$$

Putting the above equation and London second equation in $\textcircled{5}$ we get.

$$\nabla \times (\nabla \times B) = \mu_0 (\nabla \times J_s)$$

$$\nabla (\nabla \cdot B) - \nabla^2 B = - [\mu_0 n_s e^2 (B) / m]$$

* But $\nabla \cdot B = 0$

(Maxwell's second equation of Gauss law for magnetism).

* Therefore, above equation becomes,

$$\nabla^2 B = I (\mu_0 n_s e^2 (B) / m) \rightarrow \textcircled{6}$$

$$\text{where } \lambda_1^2 = m / \mu_0 n_s e^2 \quad (\text{del}^2 B = B / \lambda_1^2)$$

$$\textcircled{6} \quad \lambda_1 = (m / \mu_0 n_s e^2)^{1/2}$$

where, λ_1 is known as London's penetration depth and it has units of length.

$$\nabla^2 B = B / \lambda_1^2 \rightarrow \textcircled{7}$$

The solution of differential equation $\textcircled{7}$ is,

$$B = B(0) e^{-x/\lambda_1} \rightarrow \textcircled{8}$$

where,

* $B(0)$ is the field at the surface and x

is the depth inside the superconductor.

The equation $\textcircled{8}$ shows that a uniform magnetic field equal to zero can not exist in a superconductor, which is Meissner effect.

In the pure superconducting state the only field allowed in the exponentially decreasing field as the flux penetrates from external surface and it is given by $\textcircled{8}$.

$$\text{Suppose } x = \lambda_1$$

Equation $\textcircled{8}$ becomes,

$$B = B(0) / e$$

London penetration depth :-

* The London penetration depth is the distance inside the surface of a superconductor.

* At which the magnetic field reduces

to λ_L times its value at the surface.

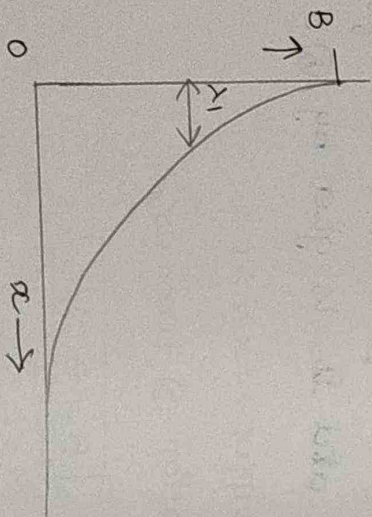
* The London penetration depth depends on the temperature and becomes much larger, as T approaches critical temperature T_c .

* The relation is,

$$\lambda_L(T)/\lambda_L(0) = [1 - T/T_c]^2]^{-1/2}$$

where,

- $\lambda_L(T)$ } London penetration depth at T
- $\lambda_L(0)$ } Kelvin and 0 respectively.



* The λ_L varies in the interior of the superconductor.

* The value of λ_L found experimentally range from 30nm to 200nm.

'TEN MARK QUESTIONS'

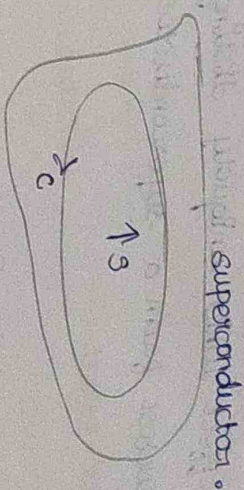
1) Explain in detail about Meissner's effect:-

* When the superconducting material is placed in a magnetic field under the condition when $T \leq T_c$ and $H \leq H_c$, the flux lines are excluded from the material. It explains as follows,

* There is another, much more fundamental characteristics which distinguishes the superconductors from a normal, but ideal, conductor.

* The superconductor expels magnetic flux, $[B=0]$ within the bulk of a superconductor.

* This is fundamentally different than an ideal conductor, for which $[B=0]$ since, for any closed path,



* A closed path and the surface it contains within a superconductor.

$$0 = IR$$

$$= V$$

$$V = \oint \mathbf{E} \cdot d\mathbf{l}$$

$$= \int_V \nabla \cdot \mathbf{E} \cdot d\mathbf{V}$$

$$= -\frac{1}{\epsilon} \int_V \frac{\partial B}{\partial t} \cdot d\mathbf{S} \rightarrow \text{①}$$

since, S and ϵ are arbitrary.

$$0 = -\frac{1}{\epsilon} B \cdot S$$

$$B = 0 \rightarrow \text{③}$$

* Thus for an ideal conductor, it matters if it field cooled or zero field cooled.

* where as for a superconductor, regardless of the external field and its history.

* If $r < r_c$, then $B = 0$ inside the bulk.

* This effect which unambiguously distinguishes an ideal conductor from a superconductor, is called the Meissner effect.

$$B = \mu H = 0$$

$$\mu = 0$$

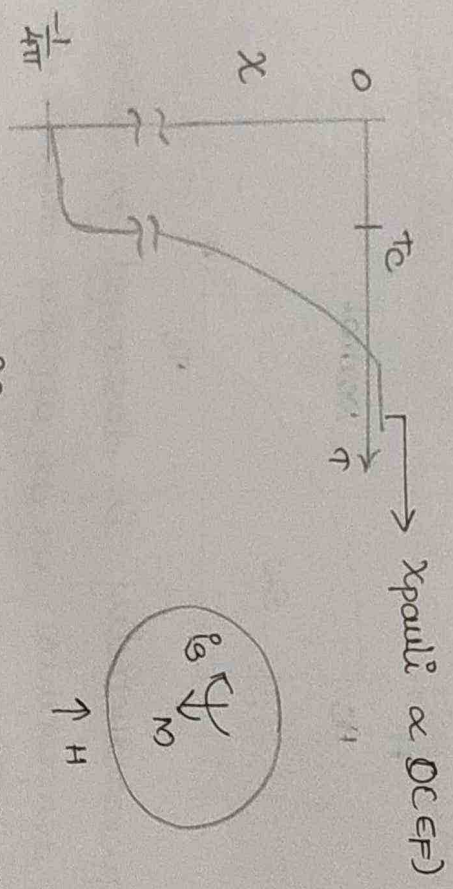
$$M = \chi H \rightarrow \textcircled{A}$$

$$M = \frac{\mu - 1}{4\pi} H \rightarrow \textcircled{B}$$

$$\chi_{SC} = -\frac{1}{4\pi} \rightarrow \textcircled{C}$$

So the measured χ in a superconducting metal is very large and negative (diamagnetic). This can also be interpreted as the presence of persistent surface currents which maintain a magnetization of

$$M = -\frac{1}{4\pi} H_{ext} \rightarrow \textcircled{C}$$



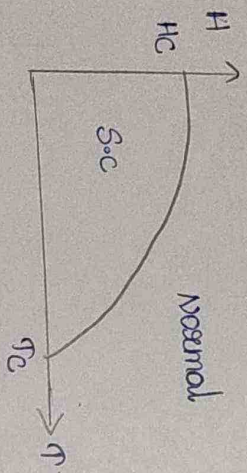
magnetic susceptibility versus temperature.

Surface currents on a superconductor are induced to expel the external flux.

* the magnetization of an the interior of the superconductor in a direction opposite to the applied field.

* the energy associated with this current increases with heat.

* at some point it is then more favorable (a lower energy state and these screening to a normal metallic state and these screening current abate. thus there exists an upper critical field H_c .



* superconductivity is destroyed by either raising the temperature or by applying magnetic field.

* The meissner effect can be understood from classical electron magnetic theory as a consequence of Faraday's law,

$$\text{emf} = \oint \vec{E} \cdot d\vec{l} = - \frac{\partial \Phi_B}{\partial t} \rightarrow \oplus$$

this last expression is really just a statement of lenz's law pertaining to how nature abhors a changing flux.

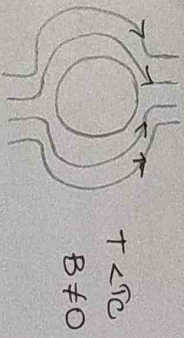
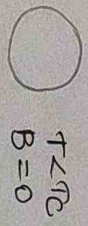
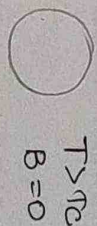
Ideal conductor

$$\frac{\partial}{\partial t} \left\{ \int \frac{m \vec{v}}{q_s n_s} - \oint \vec{J} \cdot d\vec{l} + \Phi_B \right\} = - \frac{\partial \Phi_B}{\partial t} \rightarrow \textcircled{8}$$

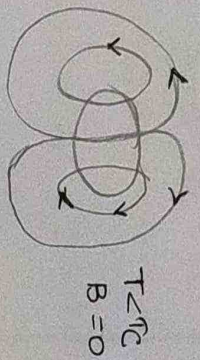
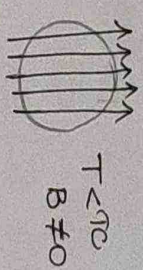
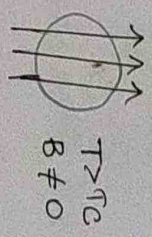
$$\frac{\partial}{\partial t} \left\{ \int \frac{m \vec{v}}{q_s n_s} - \oint \vec{J} \cdot d\vec{l} + \Phi_B \right\} = \frac{\partial}{\partial t} \{ \Phi_J + \Phi_B \} = 0$$

$\hookrightarrow \textcircled{9}$

Zero-field cooled

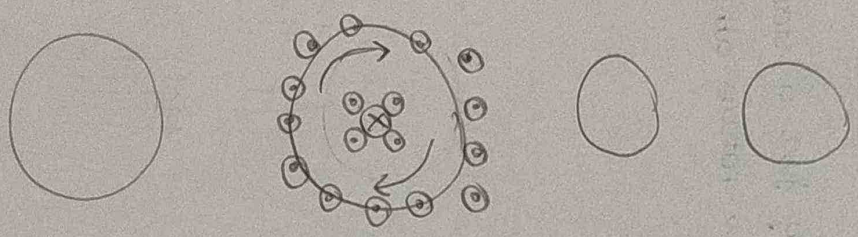


Field cooled.

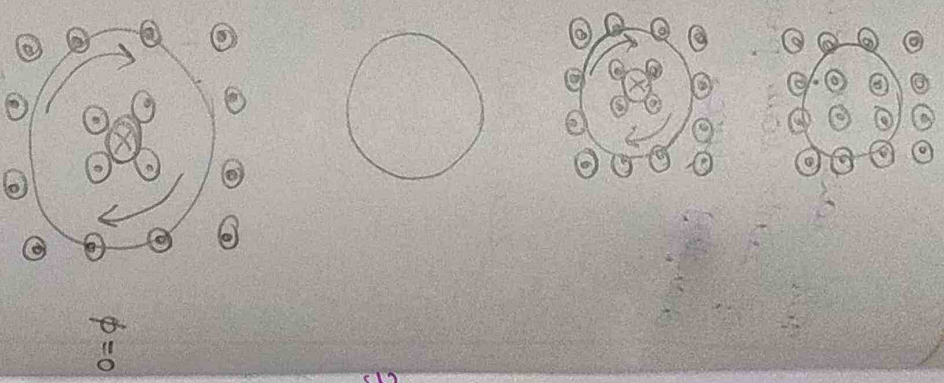


Superconductivity

zero field cooled



field cooled.



Application of Meissner's effect :-

- * This effect of superconductivity is used in magnetic levitation.
- * which is the base of modern high speed bullet trains.
- * In superconducting state (phase), due to exclusion of external magnetic field, the sample of superconducting material levitates above magnet or vice versa.
- * Modern high-speed bullet train use the phenomenon of magnetic levitation.

Josephson Effect AC and DC?

Introduction :-

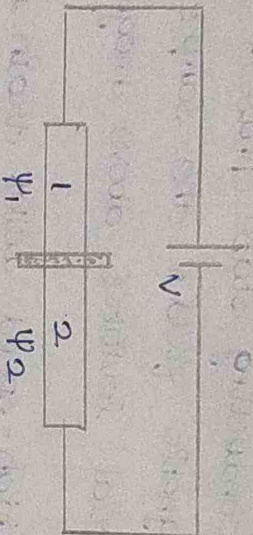
* In 1962, B.D. Josephson analysed what happens at junction between two closely spaced superconductors, separated by an insulating barrier.

* If the insulating barrier is thick, the electron pairs can not get through; but if the layer is thin enough (approx 1nm) there is a probability for electron pairs to tunnel.

* This effect later became known as 'Josephson Tunneling'.

* Besides, displaying a broad range of interesting macroscopic quantum mechanical properties,

* The Josephson junction offers a vast survey of possible applications in analog and digital electronics such as signal detectors, oscillators, mixers & amplifiers.



* Two superconductors separated by a thin insulator.

AC and DC effect :-

* The main concept used to discuss the Josephson effect is that of the phase of the paired electron

* The idea of spatial correlation of electrons with the idea of the existence of Cooper pairs.

* Cooper pairs are set of two electrons that are attracted to one another because an electron attracts positive ions.

* When an electron has attracted a positive ion to a displaced position, we can imagine the

displacement as moving out of the area while the two
atoms remains displaced for a time.

On the region of crystal where the two ions
are displaced the crystal has a net positive charge than
displaced and so this region can attract another electron.
material

* Cooper pairs of electrons are formed because
of the virtual exchange of phonons between the
electron.

* returning to the coupling of superconductors
through an oxide layer, we write a set of
time dependent 'Schrödinger-random equations' that
allow for coupling.

$$\hbar \frac{\partial \psi_1}{\partial t} = H_1 \psi_1 + \hbar U \psi_2 \quad \rightarrow \textcircled{1}$$

$$\hbar \frac{\partial \psi_2}{\partial t} = \hbar U \psi_1 + H_2 \psi_2 \quad \rightarrow \textcircled{2}$$

We assume $H_1 = H_2 = 0$,

$$\hbar \frac{\partial \psi_1}{\partial t} = \hbar U \psi_2 \quad \rightarrow \textcircled{3}$$

$$\hbar \frac{\partial \psi_2}{\partial t} = \hbar U \psi_1 \quad \rightarrow \textcircled{4}$$

$$\psi_1 = e_1 \exp(i\phi_1) \quad \rightarrow \textcircled{5}$$

$$\psi_2 = e_2 \exp(i\phi_2) \quad \rightarrow \textcircled{6}$$

using (3) & (4) we get,

$$i\rho_1 - e_1 \psi_1 = v\rho_2 \exp(i\Delta\phi) \rightarrow (8)$$

$$i\rho_2 - e_2 \psi_2 = v\rho_1 \exp(-i\Delta\phi) \rightarrow (9)$$

where,

$$\Delta\phi = (\phi_2 - \phi_1) \rightarrow (7)$$

Phase difference between the electrons on two sides

$$e_1 = v\rho_2 \sin \Delta\phi \rightarrow (10)$$

$$e_1 \phi_1 = -v\rho_2 \cos \Delta\phi \rightarrow (11)$$

$$e_2 = -v\rho_1 \sin \Delta\phi \rightarrow (12)$$

$$e_2 \phi_2 = -v\rho_1 \cos \Delta\phi \rightarrow (13)$$

Assume $\rho_1 \approx \rho_2 \approx \rho$

$$\frac{d}{dt} (\phi_2 - \phi_1) = 0 \rightarrow (14)$$

$$\phi_2 \equiv \phi_1 = \text{constant} \rightarrow (15)$$

$$e_1 \equiv e_2 = \dots \rightarrow (16)$$

current density J is,

$$J \propto \frac{d}{dt} e_2^2 = 2e_2 \dot{e}_2 \rightarrow (17)$$

So, $J = J_0 \sin(\phi_2 - \phi_1) \rightarrow (18)$

Ans:

$q = 2e$ with $\hbar q, V$

$$\hbar \hbar \frac{\partial \psi_1}{\partial t} = \hbar V \psi_2 - e V \hbar \psi_1 \rightarrow (19)$$

$$\hbar \hbar \frac{\partial \psi_2}{\partial t} = \hbar V \psi_1 + e V \hbar \psi_2 \rightarrow (20)$$

Again,

$$i \dot{\psi}_1 - e_1 \psi_1 = v E_2 \exp(i \Delta \phi) - e V \psi_1 \rightarrow (21)$$

$$i \dot{\psi}_2 - e_2 \psi_2 = v E_1 \exp(-i \Delta \phi) + e V \psi_2 \rightarrow (22)$$

Separate real and imaginary parts

$$\dot{\psi}_1 = v E_2 \sin \Delta \phi \rightarrow (23)$$

$$\dot{\psi}_2 = -v E_1 \sin \Delta \phi \rightarrow (24)$$

$$\dot{\psi}_1 \approx -\dot{\psi}_2 \rightarrow (25)$$

$$e_1 \dot{\psi}_1 = -v E_2 \cos \Delta \phi + e V \rightarrow (26)$$

$$e_2 \dot{\psi}_2 = -v E_1 \cos \Delta \phi - e V \rightarrow (27)$$

Remembering $e_1 \approx E_2 \approx E$

$$\dot{\psi}_2 - \dot{\psi}_1 \approx -2eV \rightarrow (28)$$

$$\Delta \psi \approx (\Delta \psi)_0 - 2eVt \rightarrow (29)$$

current density .

$$j = j_0 \sin [(\Delta \psi)_0 - 2eVt] \rightarrow (30)$$

$$\omega_J = 2eV = 2e \frac{\text{voltage}}{h} \rightarrow (31)$$

For AC Josephson effect which occurs when

$$\omega = \frac{q}{h} \text{ voltage} \rightarrow (32)$$

These experiments also contributed to better accuracy in the determination of fundamental constants.

Purpose of Josephson effect?

* working of a SQUID

UNIT-3

- 'NANOMATERIALS'

TWO MARKS

1) Write about nanomaterials.

- * Nanomaterials are commonly defined as materials with an average grain size less than 100 nanometers.
- * Nanomaterials have extremely small size which having at least one dimension 100nm.
- * One billion nanometers equal one meter.
- * The average width of human hair is on the order of 100,000 nanometers.
- * A single particle of smoke is in the order of 1,000 nanometers.
- * Two principal factors cause the properties of nanomaterials to differ significantly from bulk materials.

- Increased relative surface area

- Quantum effects

- * 1 nanometer = 10 angstroms, 1nm there may be 3-5 atoms.

2) Write any four properties of nanomaterials

* The mechanical properties of nanomaterials increase with decrease in size, because smaller in size, lesser is the probability of finding imperfections such as dislocations, vacancies, grain boundaries.

* The optical properties is the reduction of material dimension has pronounced effect on these properties, the size dependence is due to,

- surface plasmon resonance (SPR).
- quantum size effects.

* Magnetic properties of nanomaterials differ to that of bulk.

* For a ferromagnetic material, total energy is,

$$E_{tot} = E_{exc} + E_{ani} + E_{dem} + E_{app}$$

* where, E_{exc} - exchange energy, E_{ani} - anisotropic energy, E_{dem} - demagnetization energy, E_{app} - energy due to applied magnetic field.

$$E_{dem} = \mu_0 H^2, \quad D_{eff} = \frac{9\gamma_B}{H_0 \mu_0^2}$$

* surface scattering, change of electronic structure quantum transport, Effect of microstructure plays important role in electrical properties.

3) What is fullerene?

* It was discovered by 1985, Kroto Smalley and Sawil.

* It is a carbon allotropic.

* Football sphere (bucky ball), ellipsoid, tube, bucky tube, nanotube).

* Similar structure to graphite?

- Hexagons
- Pentagons (curvature).

* Euler: 12 pentagons to make sphere.

EXAMPLES:

* C60 - Buckminster fullerene.

• Smallest structure with no pentagons touching.

• ~ 7nm diameter

• melting point ~ 550K

* Bucky onions - one fullerene inside another.

• upto 40 layers observed.

• Nanotube generation normally produces some onions

* these fullerenes are useful because of size, stability, hydrophobia.

4) write about CNT?

* carbon nanotubes are tubular forms of carbon that can be envisaged as graphene sheets rolled into cylindrical form.

* these nanotubes have diameters of few nano-meters and their lengths are up to several micrometers.

* Each nanotube is made up of a hexagonal network of covalently bonded carbon atoms.

* carbon-nanotubes are of two types;

- single-walled;
- multi-walled.

* A single walled carbon nanotube (CNT) consists of a single graphene cylinder.

* whereas, a multi-walled carbon nanotube (MWCNT) comprises of several concentric graphene cylinders.

* depending on the way of rolling of graphene sheets in which single & multiwalled tubes are of different types, viz, armchair, zig-zag and chiral could be produced.

1) What are metallic glasses?

* It shows the property of both metals and alloys.

* metallic glasses are metal alloys that are amorphous. that is they don't have long range atomic order.

* the major advantages of such glasses are that they are generally homogeneous in composition, offer strong and superior corrosion resistance.

* metallic glasses are two types based on their base material used in preparation.

1) Metal-metal glasses:

- Eg: Ni-Nb, Mg-Zn and Cu-Zr

2) Metal-metalloid glasses:

- Eg: Fe, Co, Ni and metalloids like B, Si, C and P are used.

* there is no grain boundaries and dislocations.

* they have very tetrahedral closely packed structure.

* the metallic glasses are strong and ductile.

* this is known as metallic glasses.

6) What are ceramics?

* Ceramics once separated purely to pottery and to oxides made by firing materials extracted from Earth.

* Ceramics are generally thought of as inorganic and nonmetallic solids with a range of useful properties, including very high hardness and strength, extremely high melting points and good electrical and thermal insulations.

* The best known ceramics are pottery, glass, brick, porcelain and cement.

* Ceramics a nonmetallic and inorganic solid is so broad that it covers a much wider range of materials.

* Ceramic include simple materials such as graphite and diamond, made up from different crystalline arrangements of the element carbon.

* alumina, silicon carbide, silicon nitride, zirconia and sapphire are the types of ceramics.

FIVE MARK QUESTIONS

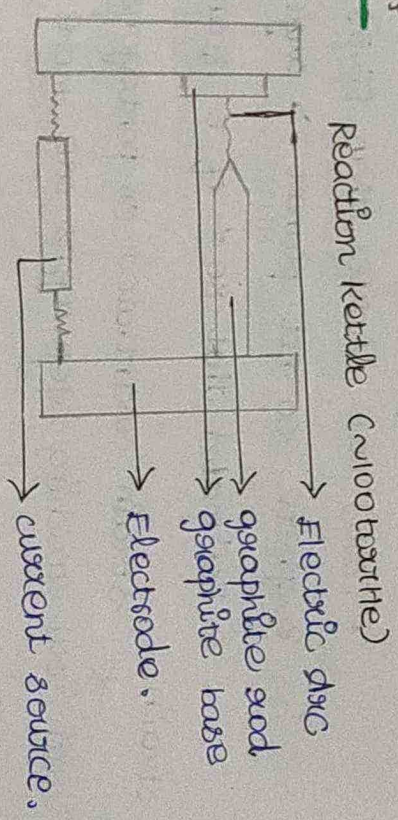
Write the properties of fullerene :-

Fullerene :-

- * It is a carbon allotrope.
- * It is a hollow sphere (bucky ball), ellipsoid, tube (bucky tube), (nanotube)
- * Similar structure to graphite :
 - Hexagons
 - pentagons (curvature) .
- * Euler : 12 pentagons to make sphere .

Production :-

*



- Before : vaporization laser .
- 1990 .
- graphite electrodes
- Fill chamber with He (inert gas), ~100 torr
- Run current through graphite .

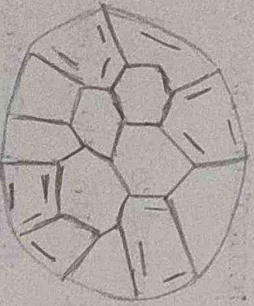
- Get black soot
- ~10% C₆₀
- Some larger fullerenes.

Properties :-

- * stable, but not totally unreactive
- * In graphite,
 - sp² bonding
 - planar, 120°

* Fullerenes :

- [6,6] double bonds, hexagons.
- [6,5] single bonds, pentagons to hexagons
- [6,6] are shorter than [6,5]
- sphere, so not planar → angle strain
- Estimated that 80% of π -formation due to strain.
- * strain concentrated on pentagons → structures with out touching pentagons are more stable (C₆₀)



* slightly soluble in some solvents.

- reduce, carbon adsorbable etc.
- in water: large clusters (nC₆₀) of 250-350

nm.

* toxic ?

- 2004: found increase in cellular damage to fish with ~5ppm in water.
- 2005: computer simulation found deformation of DNA by C₆₀ in water.

* wave-particle duality with $\lambda = 3\text{pm}$, 1999.

* Examples :- C₆₀ :-

- Buckminster fullerene
- smallest structure with no pentagons touching
- ~7nm diameter.
- melting point ~550K.
- It is arranged as 12 pentagons and 20 hexagons.

Physical properties :-

- * Do not dissolve in water.
- * cannot conduct electricity.
- * Soft and slippery.
- * Brittle.

* low melting point solids

Chemical properties :-

* Fullerenes are stable but not totally unreactive

* the sp^2 -hybridized carbon atoms, which are at their energy minimum in planar graphite, must be bent to form the closed sphere or tube, which produces angle strain.

* Fullerene is electrophilic addition at 696-double bonds which reduces angle strain by changing sp^2 -hybridized carbons into sp^3 hybridized ones.

* The change in hybridized orbitals causes the bond angles to decrease from about 120° in the sp^2 orbitals to about 109.5° in the sp^3 orbitals.

* This decrease in bond angles allows for the bonds to bend less when closing the sphere or tube and thus the molecule becomes more stable.

* Fullerenes are sparingly soluble in many solvents - aromatic such as toluene and carbon disulfide

Wide properties of CNT's :-

* Strength :-

Carbon nanotubes are the strongest, flexible and stiffest materials yet discovered in terms of tensile strength and elastic modulus respectively.

* Hardness :-

The hardness (152 GPa) and bulk modulus (462-516 GPa) of carbon nanotubes are greater than diamond, which is considered the hardest material.

* Electrical properties :-

Because of the symmetry and unique electronic structure of graphene, nanotube has a very high current carrying capacity.

* Thermal conductivity :-

All nanotubes are expected to be very good thermal conductors along the tube.

* EM wave absorption :-

There has been some research on filling nanotubes with metals, such as Fe, Ni, Co, etc., to increase the absorption effectiveness of nanotubes in the

microwave regime.

* Thermal properties :-

- All nanotubes are expected to be very good conductors and insulators laterally to the tube axis.

* Mechanical properties of engineering fibre :-

Material	Spun yarn strength	Fibre strength
Carbon nanotube	1.3-2, 1, 10-60	10-100, 10
HS steel	4.8, 0.2, 21.1	< 10
Carbon fibre - PAN	1.7-2, 0.2-0.6, 1.4-5	0.3, 0.3
Carbon fibre - pitch	2.2-2.2, 0.4-0.96, 2.2-3.3	0.2, 0.2
E/S - glass	2.5, 0.07-0.08, 2.07-4.05	4.4, 0.2
Kevlar - 49	1.21, 0.13, 3.6-4.1	2.2, 2.2

* properties of conductive materials :-

Materials	Thermal conductivity	Electrical conductivity
Carbon nanotube	> 3000	$10^6 - 10^4$
Copper	400	6×10^4
Carbon fibre - pitch	1000	$2 - 8.5 \times 10^6$
Carbon fibre - PAN	8-105	$6.5 - 1.9 \times 10^6$

Applications of CNT's

DT's applications are,

* carbon nanotube membranes for transdermal drug delivery

- * For cancer treatment
- * For cardiac autonomic regulation
- * Tissue regeneration
- * platelet adhesion.
- * In drug delivery.

Electronic applications

- * conductive composites
 - Electrode arrays.
 - Nanosensors.
 - sensors - Biomedical industry, automotive industry
- Food Industry, Environmental monitoring.

- FED display
- template.

Mechanical field

- * CNT Based Actuators
- High technology applications, including humanoid robots, artificial and damaged hearts, artificial limbs,

unmedical prosthetic devices etc,

* CNT based composites :-

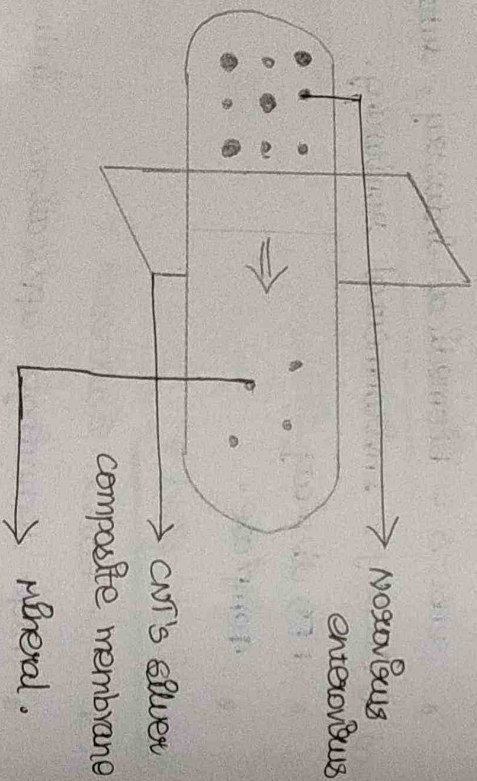
- * polymer matrix composite,
- * ceramic matrix composite.

medical field :-

- * drug delivery and cancer therapy
- * CNT's as biosensors.

other applications :-

- * As thermal materials.
- * for air and water filtration
- * hydrogen storage
- * energy storage.



TEN MARKS QUESTIONS

1) write in detail about CNT and its properties :-

CNT

* Carbon nanotubes (CNT) are the basis of

nanotechnology.

* carbon with an atomic number of 6 plays a fundamental role in nanotechnology.

* they were discovered by Iijima accidentally while studying the surface of graphite electrode used in electric and discharge.

* the accidental observation laid a foundation of exciting field of nanotechnology and started a new direction in the carbon research.

* A CNT is a hexagonal array of carbon atoms rolled up into a long, thin, hollow cylinder and are known for the, size, shape and seamless physical properties.

* they can be modified (manipulated) chemically and physically for their application in material science, electronics, energy management, biomedical application and many more.

Structure of Nanotubes :-

* A carbon nanotube is a tube shaped material made of carbon and has diameter on the nanometer scale.

Two types of carbon nanotubes are observed:
single walled nanotubes (SWNT) and multiwalled tubes (MWNNT).

SWNT :-

* they have diameter close to 1 nanometer or tube length may vary millions of times longer.

* they can be formed in three different forms, achiral, zigzag and chiral forms on basis of rolling of graphene sheet into a seamless cylinder. For, foam has a special effect on electrical property of nanotubes.

MWNNT :-

* The discovery of C60 motivated the researchers to search for other carbon compounds containing curved graphenes.

* This led to the discovery of multiwalled nanotubes were made of concentric cylinders of rolled up graphene sheets capped with semi-fullerenes.

* the length of a tube was in the range of few μm , the diameter was (10-20nm)

* As the size increases, these structures exhibit properties between fullerenes and graphite.

Properties of carbon nanotubes :-

Strength :-

* carbon nanotubes have higher tensile strength than steel and kevlar.

* the strength originates from sp^2 bonds between the individual carbon atoms.

* carbon nanotubes are not strong, they are also elastic.

* upon application of force, nanotube can bend and returns to its original shape when the force is removed.

* a nanotube's elasticity does not have a limit, and under very strong forces, it is possible to permanently weaken by defects in the structure of nanotube.

* A nanotube's strength can be weakened by defects in the structure of the nanotube.

* A nanotube's strength can be weakened by defects in the structure of the nanotube.

* defects occur α° from atomic vacancies or a rearrangement of the carbon bonds.

* defects in the structure can cause a small segment of the nanotubes to become weaker, which in turn cause the tensile strength of the entire nanotube to weaken.

* the tensile strength of a nanotube depends on the strength of the weakest segment in the tube similar to the way the strength of a chain.

Electrical properties:-

* The sp^2 bands between carbon atoms results in conducting nature of carbon nanotubes.

* they also withstand strong electric currents because of the strong nature of bonds.

* single walled nanotubes can serve electrical signals at speeds up to 100 GHz, when used as interconnects on semi-conducting devices.

* The electronic properties can be manipulated application of external magnetic field, mechanical force, etc.

Thermal stability :-

* carbon nanotubes are able to withstand high temperatures, thus making us very good thermal conductors.

conductors.

* The temperature stability of carbon nanotubes is estimated to be upto 28000 C and about 750 C in air.

* The carbon nanotubes are shown to transmit over 15 fibres the amount of weight per micro are composed to copper wires.

* This property has special application in field emission flat-panel displays and cold-cathode guns used in microscopes.

* In nanoelectronics SWiRE have been used to fabricate transistors that can function at room temperature and are potential for devices operating at terahertz (THz) frequencies.

* These are the properties of carbon nanotubes.

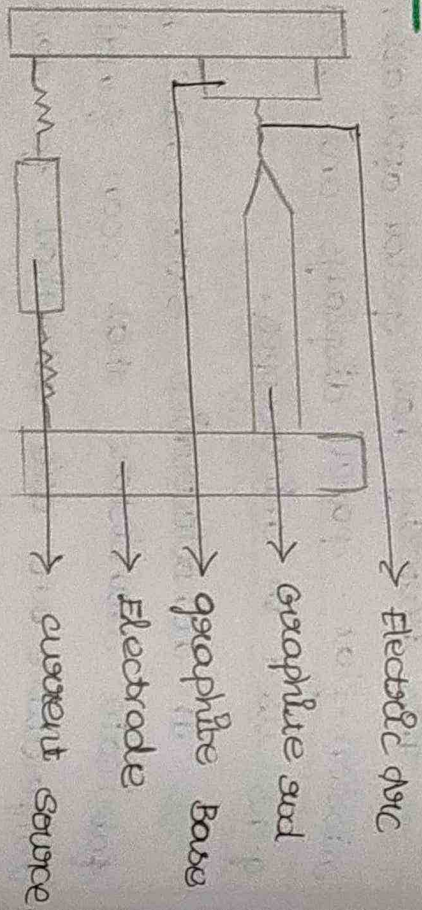
* In which the products containing carbon

nanotubes are crushed or pulverized in a waste dump.

2) What is fullerene? write its properties:-

- * Discovered 1985, Kroto, Smalley and Curl.
- * It is a carbon allotrope.
- * Hollow sphere (buckyball), ellipsoid, tube (buckytube, nanotube).
- * Similar structure to graphite.
- Hexagons
- Pentagons.
- * Euler - 12 pentagons to make sphere.

Production:-



- Before - Vaporization laser
- 1990
- Graphite electrode
- Fill chamber with He (inert gas) ~ 100 Torr
- Run current through graphite.

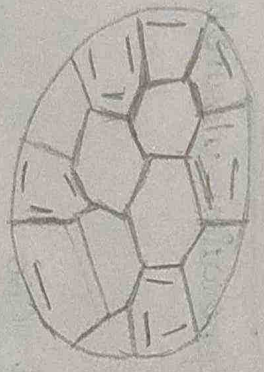
- * Get black soot
- * ~10% C60
- * some larger fullerenes.

Parapheresis?

- * stable but not totally unreactive.
- * on graphite:
 - sp² bending
 - planar 120°

* Fullerenes:

- 1) [6,6] double bonds, hexagons.
 - 2) [6,5] single bonds, pentagons to hexagons.
 - 3) [6,6] are shorter than [6,5]
 - 4) sphere, so not planar → angle strain.
 - 5) Estimated that 80% of 5-junction due to strain.
- strain concentrated on pentagons → structures with cut touching pentagons are more stable (C60).



- * significantly soluble in some solvents
- * naphthalene, carbon disulfide etc.
- * in water: large clusters (inc60) of 250-350 molecules?
- * 2001 - found increase in cellular damage to fish with ~5ppm in water.
- * 2005: computer simulation found deformation of DNA by C60 in water.
- * wave particle duality with $\lambda = 3\text{pm}$, 1999

C60 :-

- Buckminsterfullerene
- smallest structure with no pentagons touching
- ~.7nm diameter
- melting point ~550K

Bucky onions :-

- one fullerene inside another
- upto 70 layers observed
- nanotube generation unusually produces some onions.

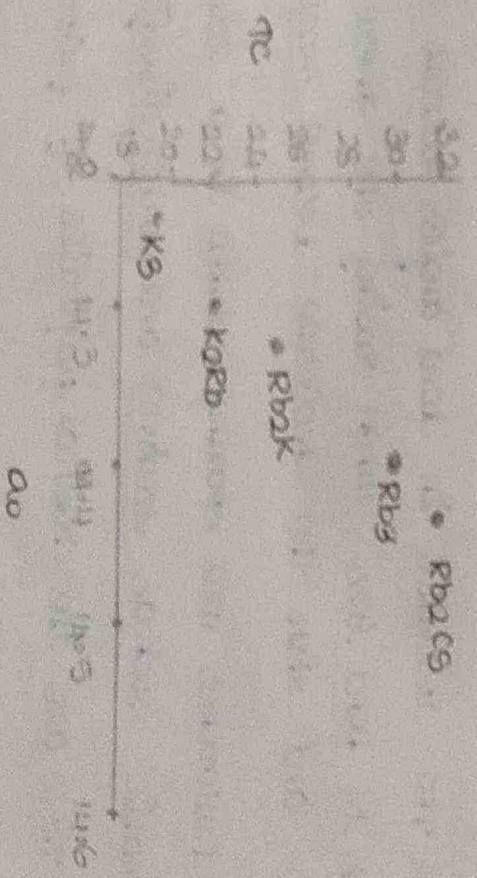
Fullerene :-

- Bulk solid C60
- FCC structure.

ultrahard fullerite :

- * 310 ± 40 GPa hardness
- * diamond : < 240 GPa (sometimes 150 GPa).
- * A_3C_{60} , A_6C_{60}
- * alkali metal scatters for each sphere.
- * 3 metal holes copy for spheres (blue)
- * A_3C_{60} - conductor
- * A_6C_{60} - insulator at room temperature.
- * A_3C_{60} becomes a super conductor
- * lattice constant a_0 changes to accommodate the metal carbon.

* different T_c .



Physical properties :-

- * do not dissolve in water.
- * cannot conduct electricity.
- * soft and slippery.
- * Brittle.
- * low melting points.

chemical properties :-

* Fullerenes are stable but not totally unreactive.

* the sp^2 hybridized carbon atoms, which are at their energy minimum in planar graphite, must be bent to form the closed sphere or tube, which produces angle strain.

* The decrease in bond angles occurs for bonds to bend less when closing the sphere or tube and thus the molecule becomes more stable.

* Fullerenes are spatially soluble in a solvent - aromatic such as toluene and carbon disulfide.

* These are the chemical properties of fullerene.

Write about the physical vapour deposition and chemical vapour deposition:

Physical vapour deposition:

* It is called as PVD - physical vapour transport.
* It describes a variety of vacuum deposition methods which can be used to produce thin films and coatings.

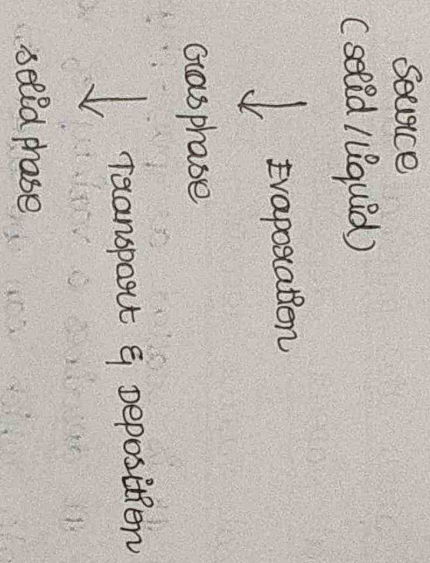
* PVD is characterised by a process in which the material goes more a condensed phase to a vapour phase and then back to a film condensed phase.

* The most common PVD processes are sputtering and evaporation.

* PVD is the manufacture of films which require the thin films for mechanicals, optical, chemical or electric functions.

* Examples include semiconductor devices such as,

- thin film sensor panels
- PET film
- balloons
- titanium
- unfilled coating cutting tools for metal working.



* Examples are chemical vapour deposition, Electron beam physical vapour deposition etc.,

chemical vapour deposition:

* Chemical vapour deposition (CVD) is a chemical process used to produce high purity, high performance solid materials.

* In typical CVD process, the substrate is exposed to one or more volatile precursors which react and decompose on the substrate surface to produce a desired deposit.

* During this process, volatile by-products are also produced, which are removed by gas flow through the reaction chamber.

Steps Involved in chemical vapour deposition:

(transport of reactants by forced convection to the deposition region.)



(transport of reactants by diffusion from the main gas stream to the substrate surface.)



(Adsorption of reactants on the water (substrate) surface.)



(chemical decomposition and other surface reactions take place.)



(rearrangement of by-products from the surface.)

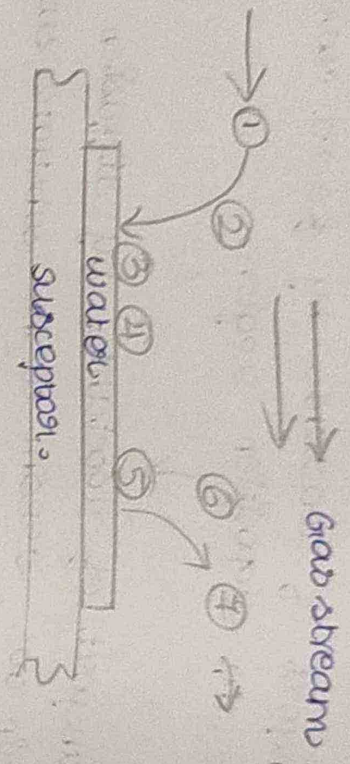


(transport of by products by forced convection away from the deposition region.)

These are the steps which are involved in the chemical vapour deposition.

* The end are of types are as is represented

Schematic diagram - steps involved in CVD,

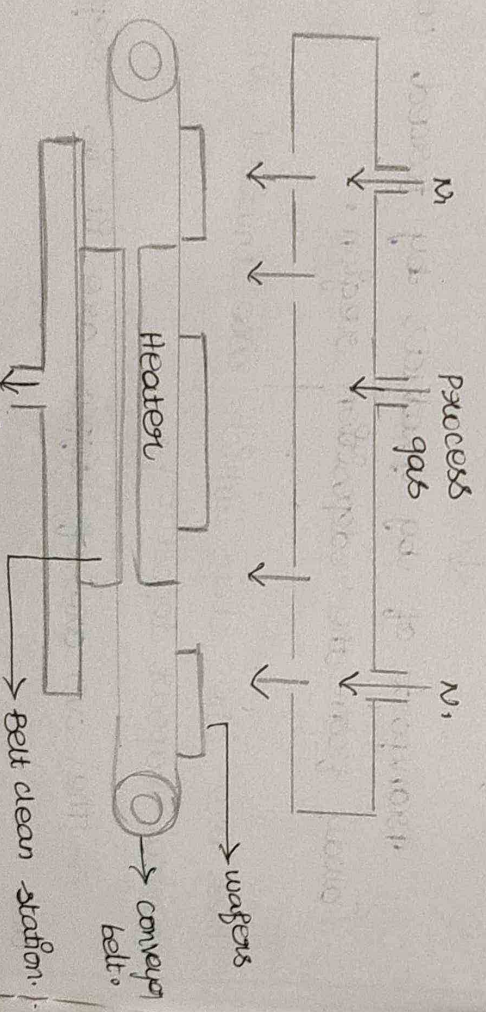


The types are,

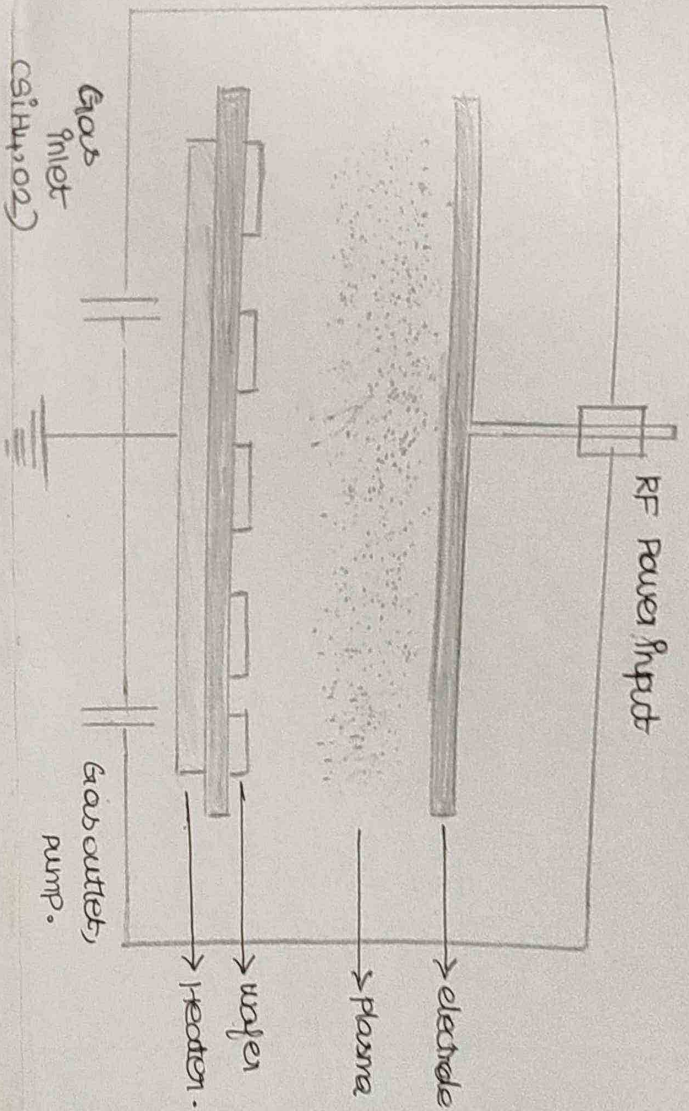
- 1) Atmospheric pressure CVD
- 2) Low pressure CVD
 - Plasma enhanced CVD
 - Photochemical vapour deposition
 - Thermal CVD.

Diagram of APCVD and LPCVD and about the

Advantages :-



PECVD 3-



Advantages of CVD :-

- variable shaped surfaces given reasonable access to the coating powders of gases, such as screw threads, blind holes or channels or recesses, can be coated evenly without blind stop on edges.
- High purity can be obtained
- High density - nearly 100% of theoretical value.
- Material formation below the melting point.

'Two Marks' Unit-4

1) What are metallic glasses?

- * Metallic glasses are the newly developed engineering materials.
- * Metallic glasses show the properties of both metals and alloys.
- * Most metals and alloys are crystalline, so their atoms are arranged in some regular pattern that extends over a long distance.
- * In contrast glass is an amorphous, brittle and transparent solid.
- * Thus, metallic glasses are metal alloys that are amorphous that is, they do not have a long range atomic order.
- * The major advantages of such glasses are that they are generally homogeneous in composition and offer strong and superior corrosion resistance.
- * They also have good magnetic properties and corrosion resistance.
- * Eg: Ni-Nb and Fe, Co, Ni with B, Si, C, P.

2) What are ceramics?

- * An inorganic compound consisting of a metal and one more nonmetals.
- * Important examples,
- * Silica - Silicon dioxide (SiO₂) the main ingredient in most glass products.
- * High hardness, electrical and thermal insulating, chemical stability and high melting temperatures.
- * Ceramics can be processed in modern ceramic and particulate ceramics.

3) What are SAW materials?

- * A surface acoustic wave (SAW) is an acoustic wave travelling along the surface of a material exhibiting elasticity, with amplitude that typically decays exponentially with depth into the substrate.
- * The velocity of acoustic waves is typically 3000 m/s, which is lower than the velocity of the electromagnetic waves.
- * A basic SAW device consists of two IDTs on a piezoelectric substrate such as quartz. The input IDT launches and the output IDT receives the waves.

• Glass fibres - thermal insulating wool, self-reinforced plastics, and fibre optics communications fibres.

- Abrasives - aluminium oxide and silicon carbide.
- cutting tool materials - tungsten carbide, aluminium oxide and cubic boron nitride.
- ceramic insulator - application include electrical transmission components, spark plugs and micro-electronic chip substrates.
- Bioceramics - oxidized teeth and bones.

Methods to strengthen ceramic materials:

- * Make stoching more uniform.
- * decrease grain size. In polycrystalline ceramic products.
- * minimize porosity.
- * Introduce compressive surface stresses.
- * use fiber reinforcement.
- * Heat treat.

Physical properties of ceramics:

* Density - In general, ceramics are lighter than metals and heavier than polymers.

* Melting temperatures - higher than for most metals.

* Some ceramics decompose rather than melt.

* Electrical and thermal conductivities - lower than for metals, but the range of values is greater, so some ceramics are insulators while others are conductors.

* Thermal expansion - somewhat less than for metals, but effect are more damaging because of brittleness.

Applications:

- Industrial sectors:
- Tapered heads for use in automotive engines
- Oil free bearings
- Aerospace turbine blades
- nuclear fuel rods
- High weight accuracy
- cutting tools
- thermal barriers
- ceramic substrates for electronic devices
- abrasives
- furnace / kiln furniture.

2) Explain optical materials with eg:

* Materials used for optical components

* Various kinds of materials are used for making optical elements.

* Optical materials are usually understood to be transparent materials.

* Some materials with good light transmission in some spectral ranges, exhibiting little absorption and scattering of light.

* However, absorption can be utilized for optical filters, and even light scattering is used in some applications.

* Further more, some materials are useful for making optical components which do not transmit light.

* For example, some materials with full transparency can be used as substrates for mirrors.

* In which,

- Crystalline Materials
- Semiconductors
- Polycrystalline Ceramics.

Crystalline Materials :-

* Most crystalline optical materials are monocrystalline, since light scattering at interfaces between grain boundaries could be detrimental.

* Optical crystals are basically always artificially grown materials. The growth velocity is usually very small because otherwise one would not obtain a single crystal.

* Therefore, crystalline optical materials tend to be more expensive than glasses or ceramics.

* This is particularly so in the mid and far infrared, where there is a limited choice of materials with good transparency.

* In some cases, optical anisotropy is required for example in the form of birefringence, which is obtained for crystal symmetry.

* Optical crystal particularly those without special dopants, are highly pure materials with very consistent optical properties.

* In contrast to glasses, where the exact composition of the used raw materials may

sometimes very.

* And there are certain fluctuations of the local chemical composition.

Semiconductors -

* Semiconductors are not transparent in the visible spectral region, because their band gap energy is smaller than the photon energy of visible light.

* However, they exhibit good transparency in the infrared.

* For example, silicon, germanium and gallium arsenide are used for infrared optics. The refractive index is usually around 4.

* Semiconductor materials are used for infrared optical windows.

* For example, there are nonlinear frequency conversion devices with quasi-phase matched gallium arsenide.

* There is also the whole research area of silicon photonics, including integrated optics on the basis of silicon.

Polycrystalline ceramics

* Polycrystalline materials have been found some applications in optics.

* Their large diameter is the major competing at quasi standards.

* However, like certain transparent ceramic materials like alumina (sapphire) and yttrium aluminum garnet (YAG = Y₃Al₅O₁₂) have been developed with good optical quality including low scattering losses.

* This can be achieved by the used materials, are very pure and the sintering process have small dimensions, so that the grain also remain perfectly exempt at sinter sintering.

* The optical properties of ceramics can be similar to those of glasses.

* Therefore, ceramic materials can be used for many typical of optical components such as, lenses, prisms, optical windows etc.

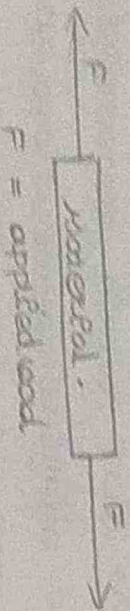
* An advantage of ceramics over large crystals is that they can be made with very large dimensions without a sintering optical growth.

3)

Factors affecting mechanical properties of materials

Tensile strength:

* This is the ability of a material to withstand tensile (stretching) loads without rupture occurring. The material is in tension.



Compressive strength:

* This is the ability of material to withstand compressive (squeezing) loads without being crushed or broken. The material is in compression.



Shear strength:



There are some of the mechanical properties.

The factors that affect these properties are,

- Grain size
- Heat treatment
- Atmospheric exposure
- Low and high temperature.

Effect of grain size :-

- * The metals are composed of crystals (or) grains. If the grain size of a metal is small it is called a fine grained metal on the other hand, when the grain size is comparatively large then it is called a coarse grained metal.
- * A fine grained metal has a greater tensile and fatigue strength. It can be easily work hardened.
- * A coarse grain causes the surface of roughness.
- * Coarse grain metal is difficult to polish.

Effect of heat treatment :-

- * To refine the grain and improve machinability.
- * To relieve the internal stress induced in the metals during cold and hot working of the metals.
- * To improve resistance to corrosion.
- * To modify the structure, either coarse grained or fine grained.
- * To improve chemical, magnetic, electrical and thermal properties.

Effect of atmospheric exposure :-

- * characteristics properties of the metal.
- * value of the protective film on its surface.
- * presence of certain reducing agents.
- * local cells formed due to development of the protective film surface cracks and discontinuity on the protective film surface.

Effect of low temperature :

- * decrease in temperature there is an increase in the tensile strength and yield strength of all metals.

- * alloys of nickel, copper and aluminium retain most of their ductility and toughness at low temperature.
- * For Bcc - low temperature metals show better properties than fcc metals.

Effect of high temperature :-

- * yield stress and ultimate tensile strength decrease with rise in temperature.
- * at high temperature, the toughness of steel is reduced.
- * at high temperature, creep takes place and the material fails even at very small stress.

Fibre reinforced metals :-

* Fibre reinforced vase made of metals, ceramics, glasses or polymers, boron, carbon, Al_2O_3 , SiO_2 .

* The most common form in which fibre reinforced composites are used in structural applications called laminate.

Properties :-

- low coefficient of expansion
- High dimensional stability
- High tensile strength
- High heat stability.
- Better abrasion and wear resistance.
- Better toughness
- Impact strength
- Low density
- Good shear properties
- High stiffness.

Advantages :-

* Higher performance for a given weight leads and fuel savings.

* Excellent strength to weight and stiffness to weight ratios can be achieved by composite materials.

* Production of cost is reduced.

* Composites may be made by a wide range of processes.

* Composite offer excellent resistance to corrosion, chemical attack and outdoor weathering.

Disadvantages :-

* Composites are more brittle than wrought metals and thus are more easily damaged.

* Hot curing is necessary in many cases requiring special equipment.

* Repair at the original cure temperature is requiring tool and pressure.

Application ->

- Body components.
- Chassis components.
- Engine components.

TEN MARK

Explain in detail about Bio-materials :-

Biomaterials :-

* Biomaterial is used to make devices to replace a part or a function of the body in a safe, reliable, economic and physiologically acceptable manner [Hench and Esterledge 1982].

materials of synthetic as well as of natural origin in contact with tissue, blood and biological fluids and intended for use for prosthetic, diagnostic, therapeutic and storage applications without adversely affecting the living organism and its components [Bruck - 1980].

Late early 1960, 1970's biomaterial field solidified. In 1975 society for biomaterials formed.

Characteristics of Bio-materials :-

Physical requirements :-

- * Hard materials.
- * Flexible materials.

Chemical requirements :-

- * must not react with any tissue in the body.
- * must be non-toxic to the body.
- * long-term replacement must not be biodegradable.

Main Features for medical Applications :-

- #### Biofunctionality :-
- * playing a specific function in physical and the mechanical terms.

Bio-compatibility :-

- * that refers to a set of properties that a material must have to used.

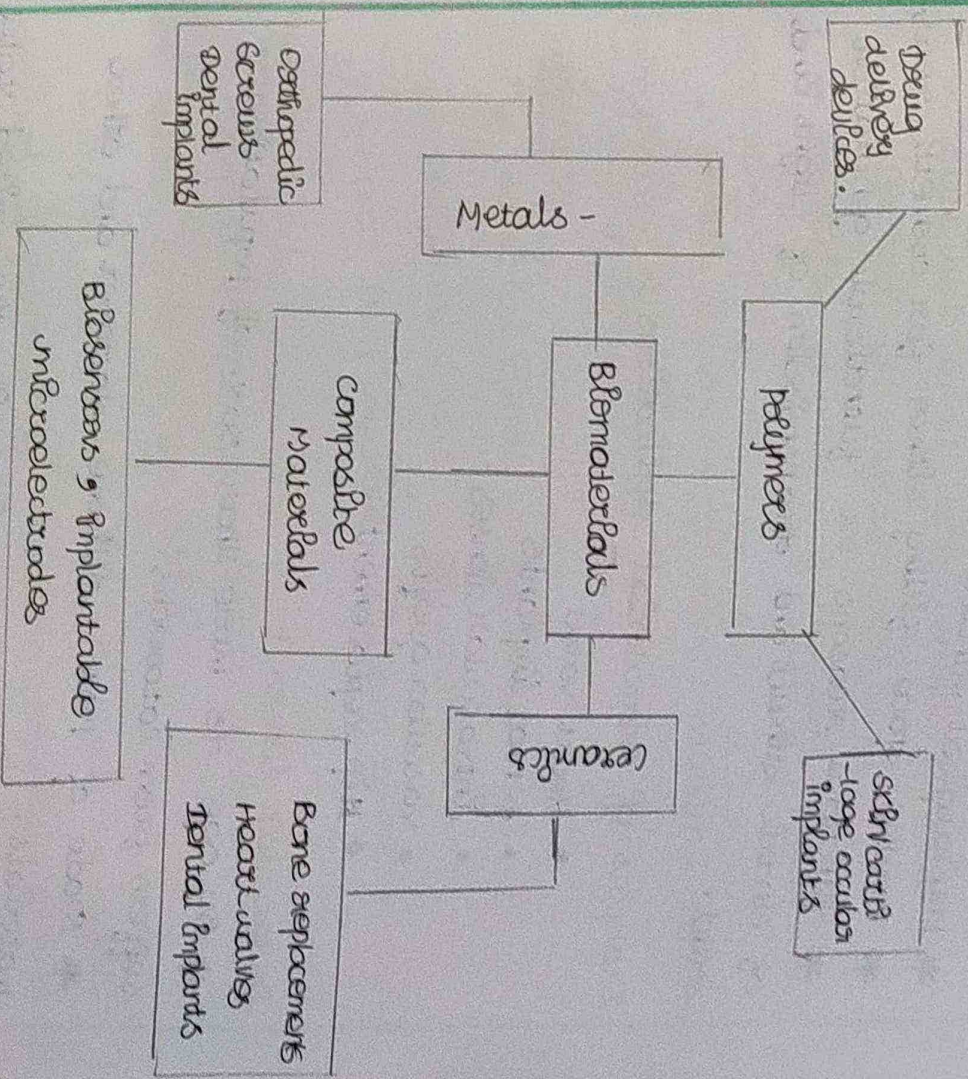
- * safety in a biological organism.

Bio-compatible Material features :-

- * absence of carcinogenicity (the ability or tendency to produce cancer).

absence of immunogenicity (absence of recognition of an external factor which could create rejection).

absence of teratogenicity (ability to cause birth defects).
absence of toxicity.



Function of Biomaterials :-

- * The functions of implants fall in one of the categories.

- * food bearing or transmission
- * The control of fluid flow in order to stimulate uncoiled.
- * Physiological function or situation.
- * Passive space filling either for cosmetic reasons
- * functional reasons or functional generation of electric stimuli and transmission of light and sound.

Examples of Biomaterial Applications :-

- Heart valve
- Dental Implants
- Intraocular lenses
- vascular grafts
- Hip replacement.

Intraocular lenses :-

- * By age it's more than 50% of population suffers from cataracts.
- * Made of PMMA, silicone, elastomer and other materials.
- * 1.4 million implantation in the united states yearly.
- * Good vision is generally restored almost immediately after lens is inserted.

Heart valve :-

- Fabricated from carbons, metals, elastomers, fabrics and natural valves.

- Must not react with chemicals in body.

- Attached by polyester mesh.

- Artificial tendon and ligament - nylon and

dacron.

- Dental implants - Titanium, alumina, calcium-

- phosphate.

Organs :-

- Artificial kidney - cellulose

- Artificial heart - polyurethane.

- Heart lung machine - silicone rubber.

Healing :-

- special process are invoked when a material or device heals in the body.

- Injury to tissue will stimulate the well-

defined inflammatory reaction sequence that leads to healing.

- when a foreign body (eg. an implant) is present in the wound site (surgical incision) the reaction sequence is referred to as the foreign

body reaction.

- Furthermore, this reaction will differ in intensity and duration upon the anatomical site involved.

Mechanical and performance

- Biomaterials that have a mechanical operation must perform to certain standards and be able to cope with pressures.
- It's therefore essential that all biomaterials are well designed and tested.
- Biomaterials that are used with a mechanical application such as hip implants are usually designed using CAD.

Steps involved in development:

- Identifying a need, device design, material synthesis, material testing, fabrication, sterilising and packaging, device testing and clinical use.
- These are the applications of bio-materials. They are closely related to complex tissue, architecture and arrangement in vivo.

write about nuclear engineering materials :-

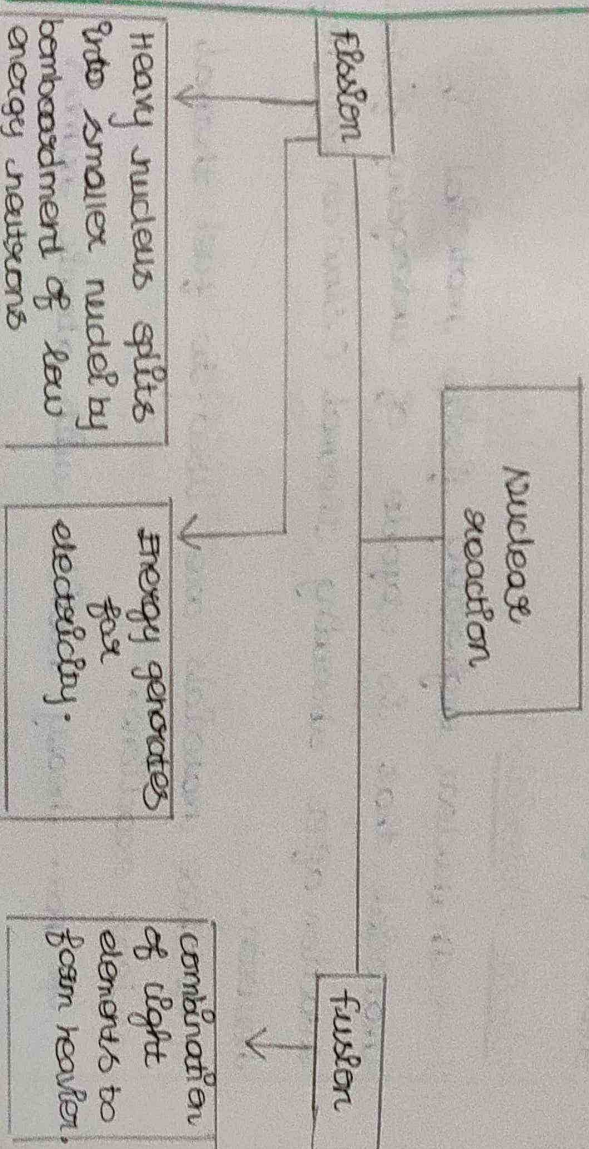
Nuclear Material :-

* A material that possess radioactive properties.

- Nuclear material such as uranium 238 and 235 are used to produce nuclear energy.
- Nuclear materials commonly refers to fissile materials that are capable of sustaining a chain reaction in a process that release energy called nuclear fission.

- The nuclear include isotopes of uranium, Plutonium and protactinium.

Nuclear Energy :-



Nuclear Heat :-

- Nuclear power generates heat from fission heavy isotopes.
 - Uranium 233, 235 (258).
 - Plutonium 239.
- Multiple options exist for the coolant, light water, heavy water, CO₂, helium, fluoride salt, lead, sodium, organic fluids etc.
- In a thermal reactor, the coolant also slows down neutrons.
- Thermal or fast reactors
- Reactors are designed to be stable systems.
- If you increase the power or temperature, the reactor physics will try to reduce power.

Fissile Materials :-

* In nuclear engineering fissile material is material that is capable of undergoing fission reaction after absorbing thermal C slow or fast or neutron.

* These materials are used to fuel thermal nuclear reactions.

* For heavy nuclei with atomic number

of higher mass than 90 most of fission isotopes meet the fission rule.

Isotopes of fissile materials:

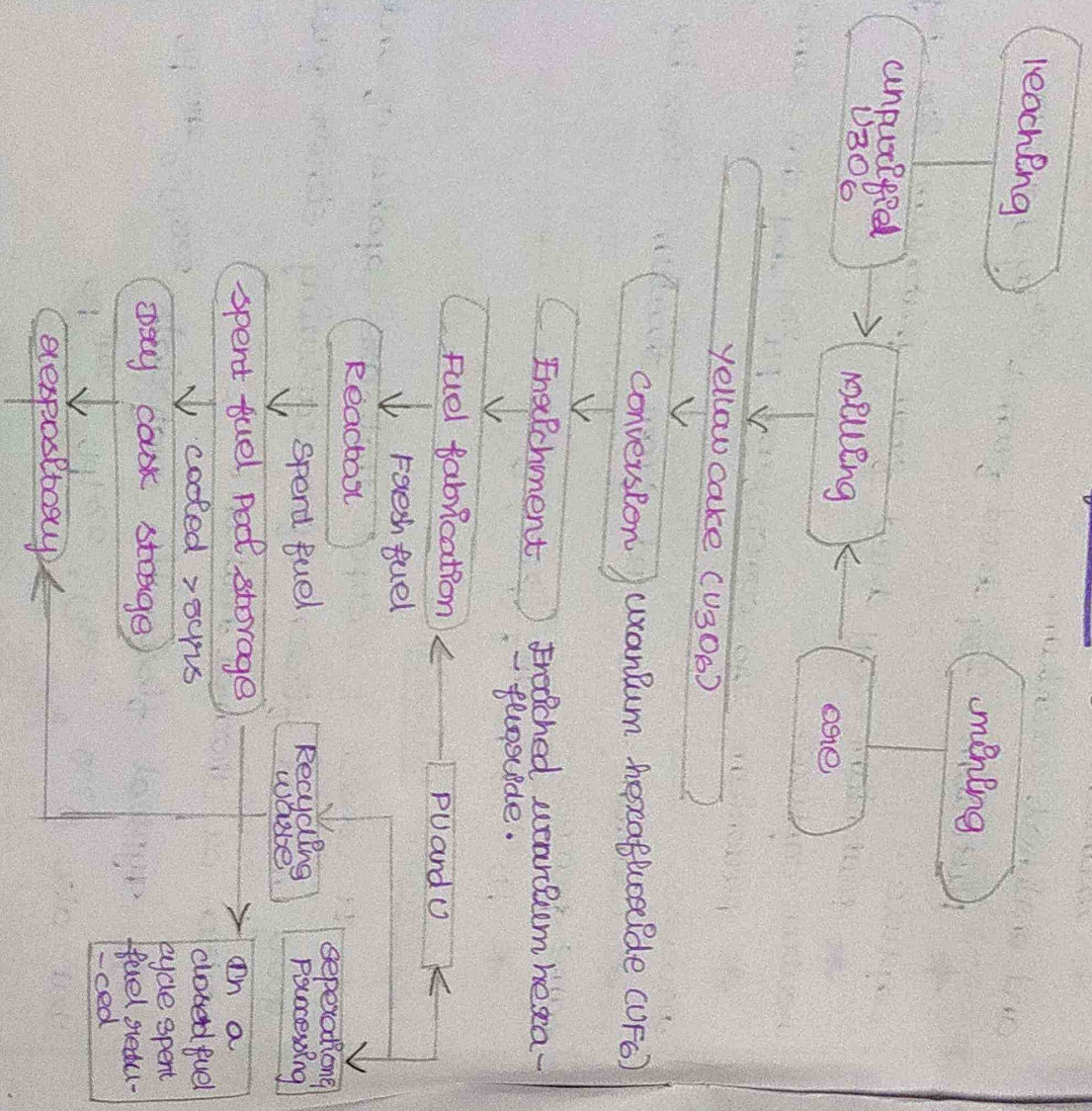
- * uranium - 235 which occurs in natural uranium and enriched uranium.
- * plutonium - 239 bred from U^{238} by neutron capture.
- * plutonium - 241 bred from plutonium - 240 by neutron capture.
- * plutonium - 240 comes from Pu^{239} by the same process.
- * uranium - 233 bred from thorium - 232 by same process.
- * Pu^{239} , Pu^{241} , U^{233} , U^{235}

Fissionable material:

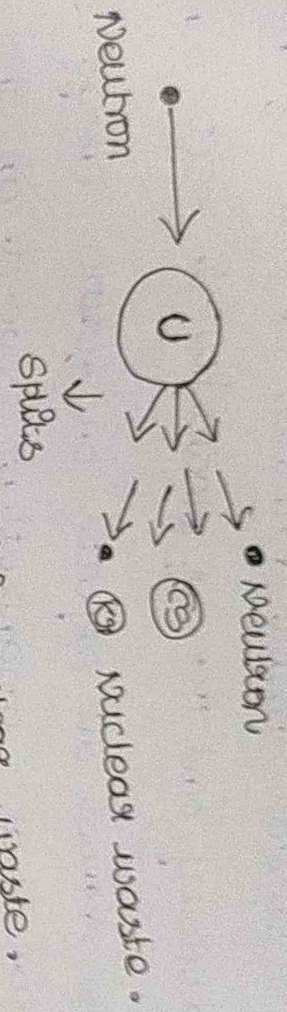
- * It consist of isotopes that are capable of undergoing nuclear fission after capturing either fast neutron or thermal neutron.
- * typical fissionable materials ^{238}U , ^{240}Pu but also U^{235} , ^{233}U , ^{239}Pu , ^{241}Pu .

• The fissionable material consist of fissionable isotopes that are capable of undergoing nuclear fission only after capturing a thermal neutron.

Nuclear fuel cycle - flow chart 3

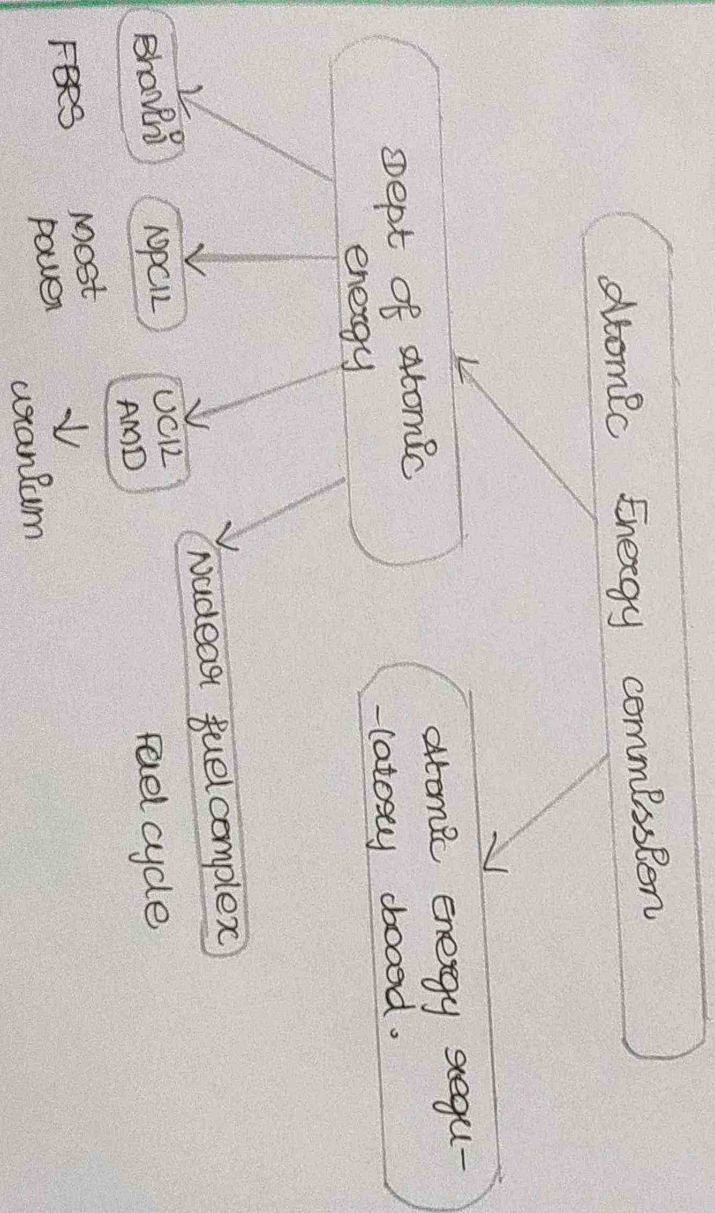


How is the nuclear fuel processed?



The splitting makes up high nuclear waste.

Nuclear power in India.



Nuclear power in Future

* Nuclear power provides over 10% of the world's electricity and 18% of electricity in OECD countries.

* Almost all reports on future energy supply from major organisations suggest an increasing role of nuclear power as an environmentally benign way of producing reliable electricity on a large scale.

UNIT-VI

"MECHANICAL BEHAVIOUR OF MATERIALS"

TWO MARK QUESTIONS :-

1) Define creep :-

- Creep is a time-dependent process where a material under an applied stress exhibits a dimensional change at high temperature.

- High temperature progressive deformation of a material at constant stress is called creep.

- The process is also temperature-dependent.

- Creep always increases with temperature.

- Creep occurs when vacancies in the material migrate toward grain boundaries that are oriented normal to the direction of the applied stress.

- Threshold for creep will be the critical temperature for creep is 40% of the melting temperature.

- If $T > 0.40 T_m \rightarrow$ creep is likely

- where $T_m =$ melting temperature.

- Creep can be occur due to different mechanisms.

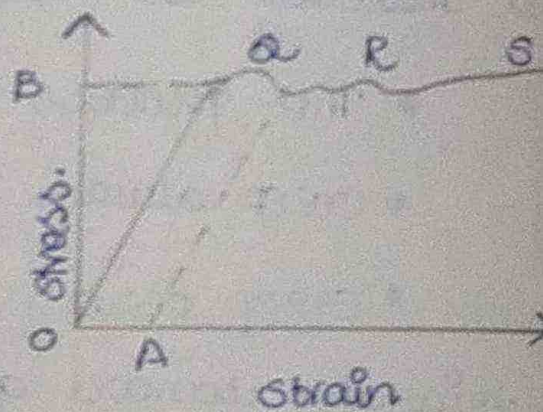
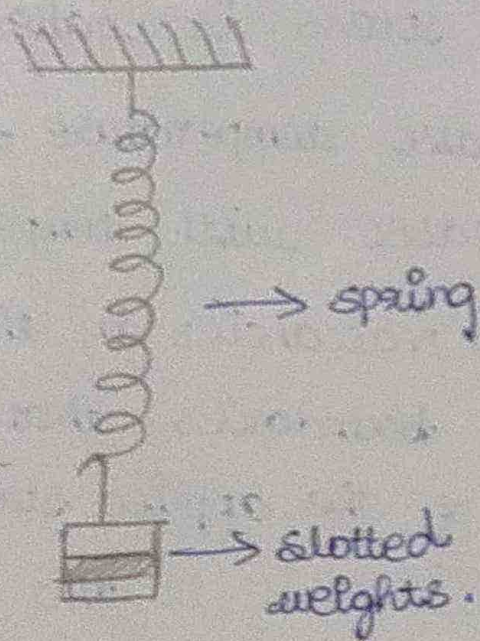
2) State Hooke's law?

• According to Hooke's law, strain produced in a body is directly proportional to the stress that produces it.

• Stress \propto strain

• $\frac{\text{stress}}{\text{strain}} = \text{a constant}$ known as a

modulus of elasticity.



• The unit is Nm^{-2} .

• Its dimension is $\text{ML}^{-1}\text{T}^{-2}$.

What is hot working treatment?

- When the processing temperature of the mechanical deformation is above the recrystallization temperature the process is termed as hot working.
- Large deformation can be successively repeated as the metal remain soft and ductile.
- The hardness of the material cannot be controlled after hot working (cooling).
- Hot working does not produce strain hardening.
- Hence, yield strength will decrease with increase in temperature and the ductility will improve.
- Example: Hot rolled steel, surface finish and tolerances are inferior to cold working process because of surface reaction (oxidation scale etc), deformation process (forces) are low.

4) Give example for ductility?

- ductility is the measure of plastic deformation that has been sustained.
- A material that suffers very little plastic deformation is brittle.
- Ductility may be expressed as either percent reduction in area.
- Examples are gold, silver, copper, and nonmetals.

5) How can you find hardness of the material?

- The hardness of material can be found using
Rockwell & Brinell hardness test.
- Indentation hardness using for steel as opposed to cast or spherulite hardness.
- It is indicative of ultimate tensile strength.
- Atoms move out of the way to create the indentation.

what is deformation?

- Deformation is change in shape due to applied force.
- This can be a result of tensile (pulling), forces, compressive (pushing), shear bending or twisting.
- Elastic deformation - this type of deformation is reversible, once the forces are no longer applied, the object returns to its original shape.
- Plastic deformation - this type of deformation is not reversible. However an object in the plastic deformation stage will first have undergone elastic deformation, which is reversible, so the object will return part way to its original shape.

'Part-B'

1) What are the factors affecting mechanical properties of materials?

The mechanical properties of materials are,

- tensile strength.
- compressive strength.
- shear strength
- toughness: Impact resistance
- Elasticity
- Plasticity
- ductility
- malleability and
- Hardness.

The factors which affect the above mechanical properties are,

- Grain size
- Heat treatment
- Atmospheric exposure
- Low and high temperature.

Effect of grain size:

- The metals are composed of crystals (or) grains.
- If the grain size of a metal is small, it is called a fine grained metal.

• On the otherhand, when the grain size is comparatively large, then it is called a coarse grained metal.

• A fine grained metal has a greater tensile and fatigue strength. It can be easily work hardened.

• A coarse grain causes surface roughness.

• Coarse grain metal is difficult to polish.

• Coarse grained metal is less tough and has a greater tendency to cause vibration than the fine grained metal.

• Coarse grained metal has a better workability, hardenability and forgeability.

• At room temperature the grain boundary is more or fine grained metals. Therefore, it has a higher strength and hardness than the coarse grained metal.

• At high temperature coarse grained materials have better creep resistance than the coarse grained metal (ones).

Effect of heat treatment :-

- Heat treatment is generally done for the following purposes.
- to refine the grain and improve machinability.
- to relieve the internal stresses induced in the metals during cold and hot working of the metal.
- to improve resistance to corrosion.
- to modify the structure, either coarse grained or fine grained.
- to improve chemical, magnetic, electrical and thermal properties.

Effect of Atmospheric Exposure :-

- Most of the metals get oxidized when exposed to the atmospheric. Due to oxidation, of metal surface, a film is formed. The presence of moisture, sulphur dioxide, hydrogen sulphide and other corrosive conditions decrease the electrical resistivity of metals.
- The atmospheric effect on the metal depends on the following.
- characteristics properties of the metal.

- value of the protective film on its surface.
- presence of certain reducing agents.
- local cells formed due to development of cracks and discontinuity on the protective film surface.

Effect of low temperature :-

- decrease in temperature there is an increase in the tensile strength and yield strength of all metals.

• alloys of nickel, copper and aluminium retain most of their ductility and toughness at low temperature.

• For mild steel, the elongation and reduction in cross-sectional area is satisfactory upto 80°C but after that it goes down to a large extent.

- Near absolute zero temperature many metals exhibit the phenomenon of superconductivity.
- Below -100°C non-ferrous metals show better properties than ferrous metals.
- Low temperature causes low thermal vibrations and lattice parameters are stabilized.

Effect of high temperature :-

- Yield stress and ultimate tensile strength decrease with rise in temperature.
- Stiffness and fracture stress of many metals also decrease with increasing temperature.
- At high temperature the toughness of steel is produced.
- At high temperature creep takes place and the material fails even at a very small stress.
- Due to rise in temperature, there is a corresponding rise in thermal vibration of atoms causing changes in structural properties.

Q1) Write a short about cementite :-

Q2) Write about metal forming processes :-

- Metal forming - large set of manufacturing processes in which the material is deformed plastically to take the shape of the die geometry.
- The tools used for such deformation are called die, punch etc, depending on the type of process.
- Plastic deformation - stresses beyond yield strength of the workpiece material is required.

categories - bulk metal forming, sheet metal forming.

- Bulk deformation - rolling processes, forging processes, extrusion processes, wire and bar drawing
- Sheet metal forming - bending operations, stretching, deep or cup drawing, shearing processes, miscellaneous processes.

- Metal forming processes are used for plastically deforming workpiece to desirable shape and obtaining optimum mechanical properties.

- Desired shape
- Improved mechanical properties,
- Grain refinement
- Reduction of voids / defects
- Finer structure
- dimensional homogeneity
- strain hardening.

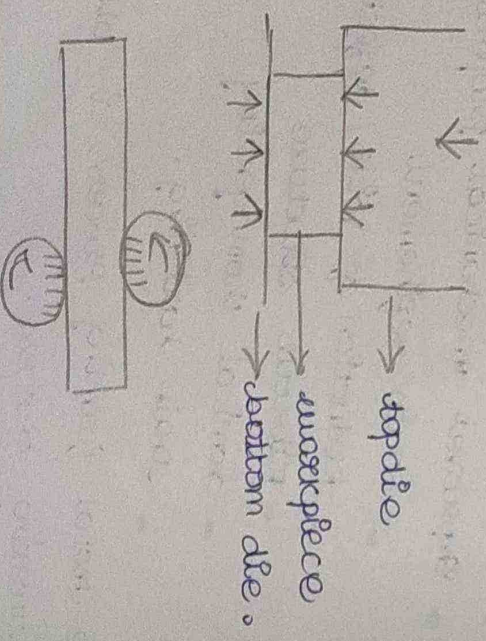
- The metal forming process is also known as metal working process.

Classification of metal working processes :-

- Based on type of forces applied.
- Direct compression - type process \Rightarrow Forging and rolling.
- Indirect compression - type process \Rightarrow wire and tube drawing, extrusion, deep drawing.
- Tension type process \Rightarrow stretch forming.
- Bending processes \Rightarrow bending of sheets.
- Shearing process \Rightarrow in sheet metal forming applications.

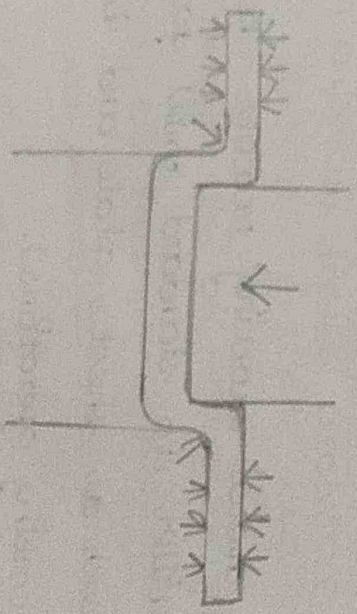
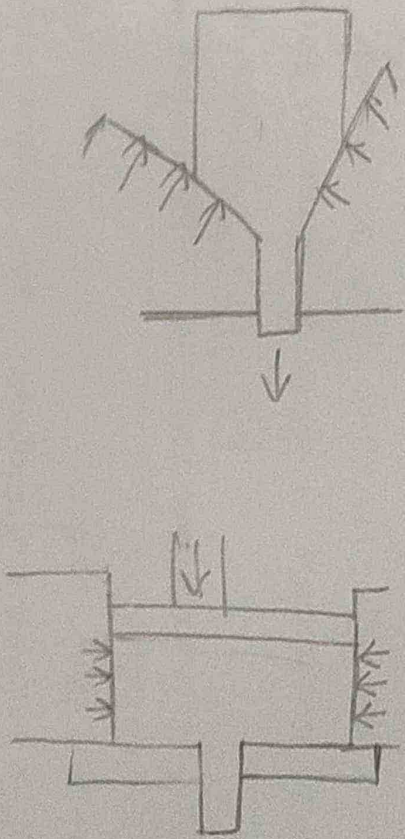
Direction compression type processes :-

- Force is applied to surface of workpiece and metal flow takes place at slight angles to direction of compression.

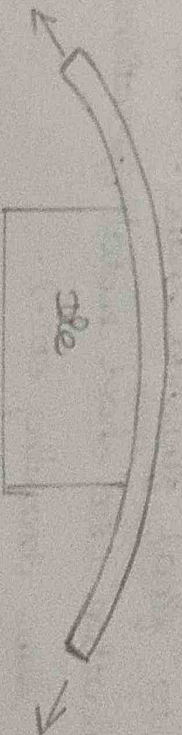


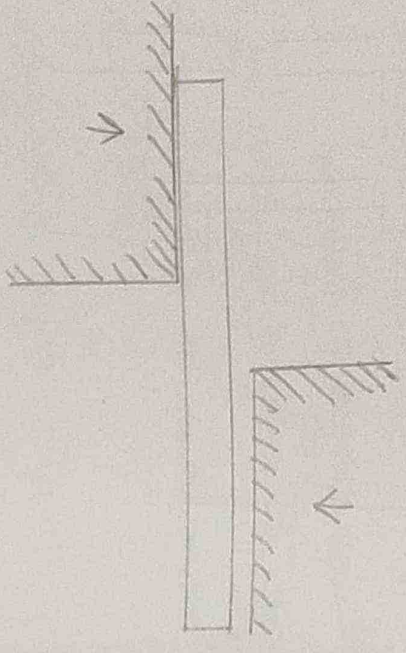
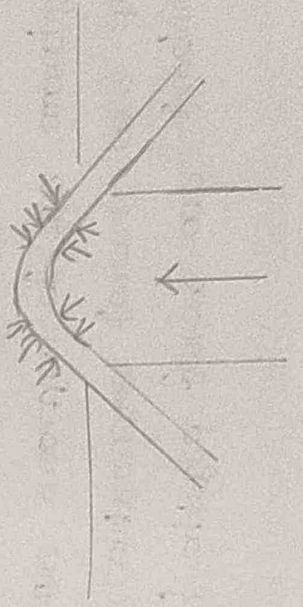
Indirect compression type process :-

• Primarily applied forces are frequently tensile but indirect compressive forces are developed because of the reaction of the workpiece with the die and reach very high values.



reversen type bending and shearing process.

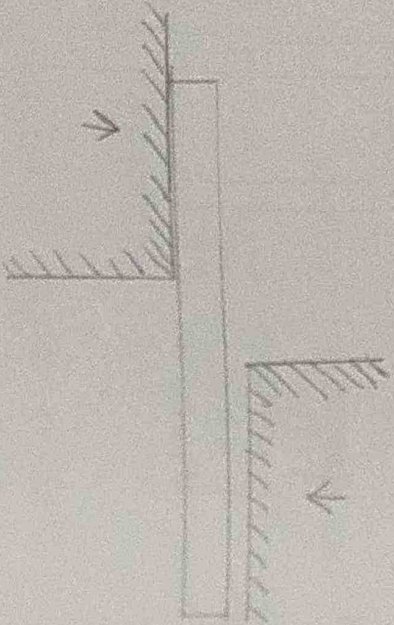
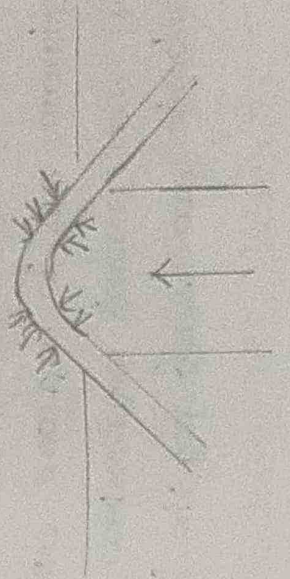




Preliminary and secondary metal working process:

- Preliminary metal working process - Reduction of ingot or billet to standard mill product of simple shape such as sheet, plate and bar (also known as processing operations).

- Secondary metal working processes produce a part to final finished shape. Also known as fabrication (i.e. sheet metal operations, wire drawing, tube drawing etc.).



Preliminary and secondary metal working processes:

- Preliminary metal working processes - Reduction of length or width to standard width/length of simple shape such as sheet, plate and bar (also known as precessing operations).

- Secondary metal working processes produce a part to final finished shape. Also known as fabrication (ex. sheet metal operations, wire drawing, tube drawing etc.).

Deformation process :-

Hot working process? Done at sufficiently high temperature such that continued deformation does not result in increased hardness.

• Example : Hot rolled steel, surface finish and tolerances are inferior to cold working process because of surface reactions (oxidation scale etc).

• Deformation forces are low.

cold working process? strain hardening effects predominate over internal recovery effects.

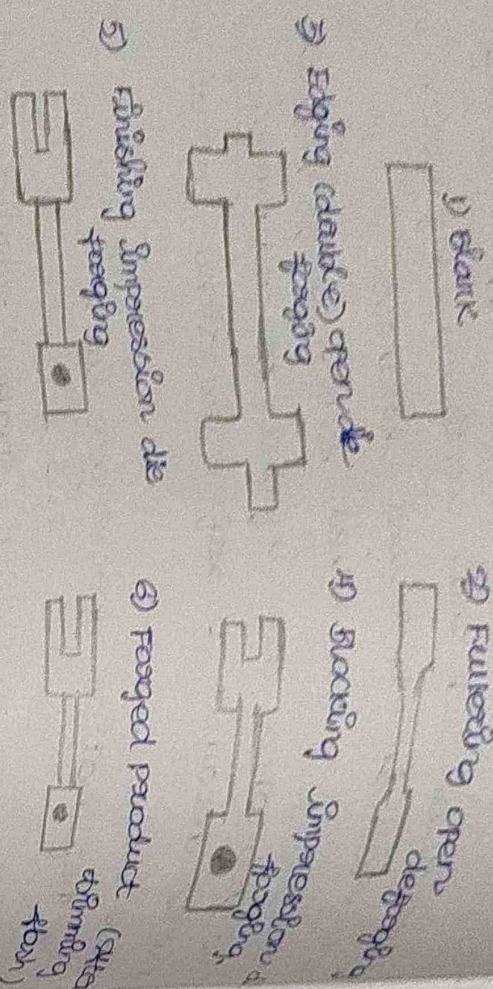
• With continued deformation the hardness and strength increase and the ductility decrease.

• DR results in an elongated grain structure and can be used to harden metals and alloys that do not respond to heat treatment.

• Example : cold rolled sheet steel, excellent surface finish and tolerances,

• Deformation forces are high.

design sequence for a multiple stage forging process:-



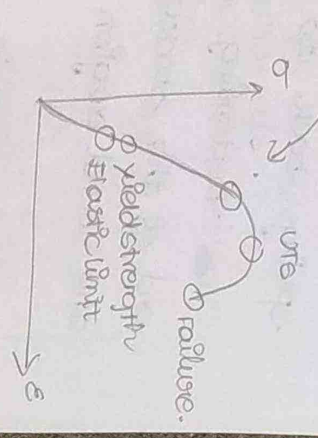
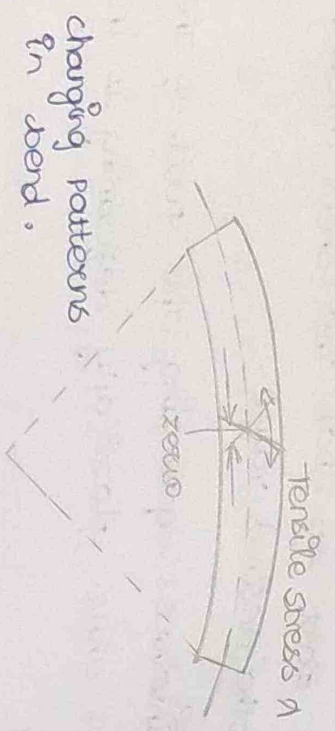
Types of forging process :-

- Hand forging
- Hammer forging
- Drop forging
- Press forging
- Machine forging or upset forging
- Roll forging.

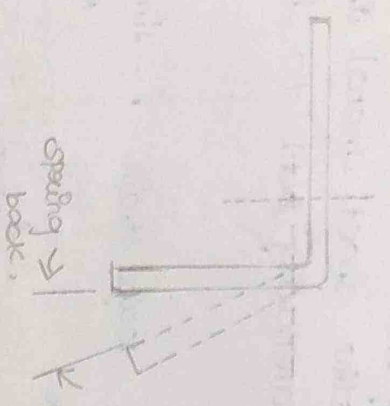
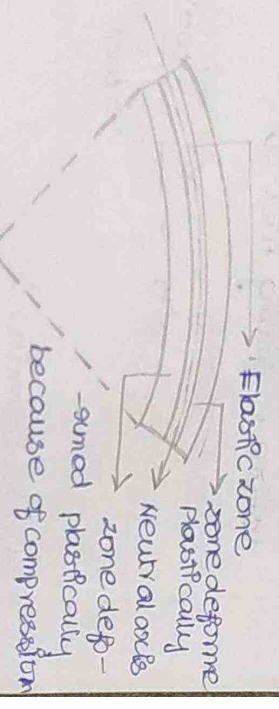
Spring back :-

Spring back occurs because of the variation in bending stresses across, the thickness. i.e., from inner surface to neutral axis to outer surface.

• The tensile stresses decrease and become zero at the neutral axis.



Elastic and plastic deformation during bending.



spring back can be minimized by overbending, workhardening and stretch forming.

- In overbending the punch angle and radius are made smaller than the specified angle on the final angle on the final part so that the sheet metal springs back to the desired value.

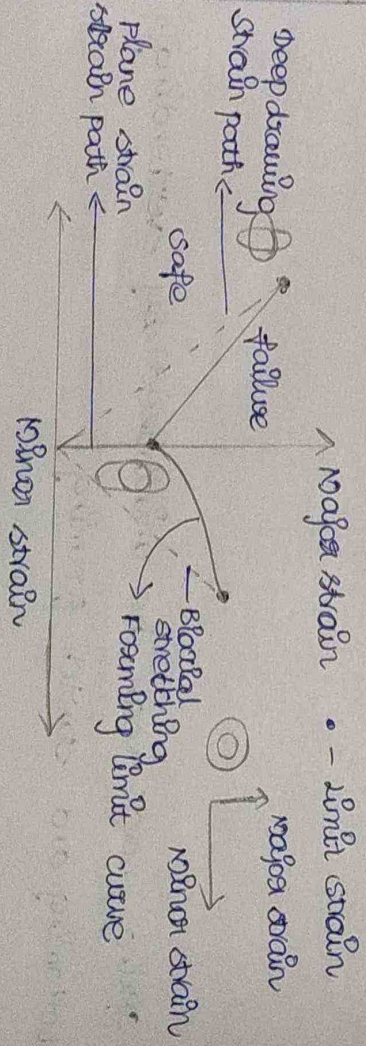
- Bottoming involves squeezing the part of the end of the stroke, thus plastically deforming it in the bend region.

where, spring back is

$$SB = \frac{\alpha - \alpha_{tool}}{\alpha_{tool}}$$

Sheet Forming:

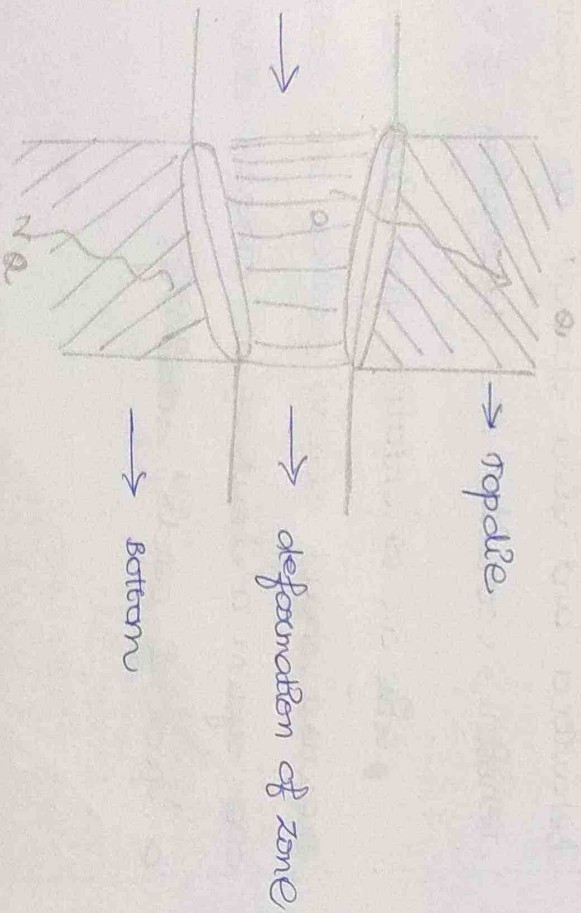
- sheet forming is a sheet metal forming process in which the sheet metal is intentionally stretched and simultaneously bent to have the shape change.



Wedge rates on deformation of metals :-

Deformation processing system :-

- Need to know distribution of stress strain
- particle particle velocities and overall pressure required to perform the operation. Following considerations are important.
- yielding because of applied forces
- metallurgical phenomena like strain hardening, recrystallisation, fracture under strain.
- Friction and lubrication
- Heat transfer from workpiece to die.



Excessive elastic deformation.

- under condition of static equilibrium
- sudden deflection

yielding or excessive plastic deformation.

- change of shape, strain hardening and effect of temperature.

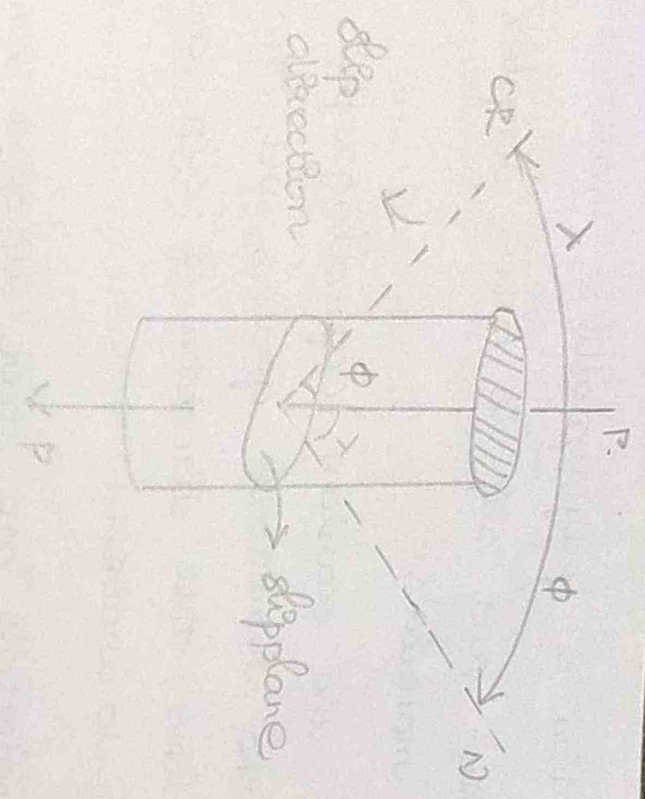
Fracture?

- sudden brittle fracture, fatigue fracture or delayed fracture.

single crystal deformation?

• to make the connection between dislocation behaviour and yield strength as measured in tension, consider the deformation of a single crystal

• Give an orientation for single slip, see the greatest shear stress reaches the critical value of one system a head of all others, then one obtains a 'pack of cards' straining.



→ possible deformation of single crystal without constraint



→ rotation of slip plane due to constraint.



Plastic deformation of polycrystalline materials

- Deformation and slip is more complex in polycrystalline materials.

- Due to the random crystallographic orientation of the numerous grains and the effect of neighbouring atoms, the direction of slip varies from one grain to another.

- These materials are made up of a number of small crystals or grains.

- For each crystal slip occurs along the slip system that has the most favourable orientation.

→ Difference between hot and cold working process:-

Hot working

- Hot working is the process of plastically deforming a metal above the metal's recrystallization temperature.

Cold working

- Cold working is the process of strengthening a metal by plastic deformation at temperatures below the recrystallization temperature.

- Hot welding is carried out above the recrystallization temperature and below the melting point.

- Hence the deformation of metal and recovery take place simultaneously.

- If hot metal welding process is properly done, it does not affect tensile strength, hardness, corrosion and fatigue resistance of the metal.

- Hot welding is most superior metal grains resulting in the improved mechanical properties.

- Hot welding is most preferred where heavy deformation is required.

- Cold welding is carried out below the recrystallization temperature.

- As such, there is no appreciable recovery.

- Cold welding process improves ultimate tensile strength, yield and fatigue strength but reduces the corrosion resistance of the metal.

- Most of the cold welding processes decrease mechanical properties of metal like a elongation, reduction of area and impact values.

- Cold welding is preferred where work hardening is required.

- In hot working, no internal and residual stresses build up in the metal.

- Heavy oxidation requires less energy for plastic deformation therefore, pickling is required to remove oxide.

- Hot working requires less energy for plastic deformation because at higher temperature, metal becomes more ductile and soft.

- Deformation of metal and its recovery happens in hot working.

- Due to higher deformation temperatures, the stress required for a deformation is much less.

- In cold working, there is internal and residual stress build up in the metal.

- Cold working does not require pickling because oxidation of metal takes place.

- Cold working requires more energy for plastic deformation.

- There is no appreciable metal recovery that happens in cold working.

- The stress required.

Part-C

VICKER'S HARDNESS TEST :-

- The Vicker's hardness test was developed in the early 1920's as an alternative method to measure the hardness of the materials.

Vickers tests has two versions :-

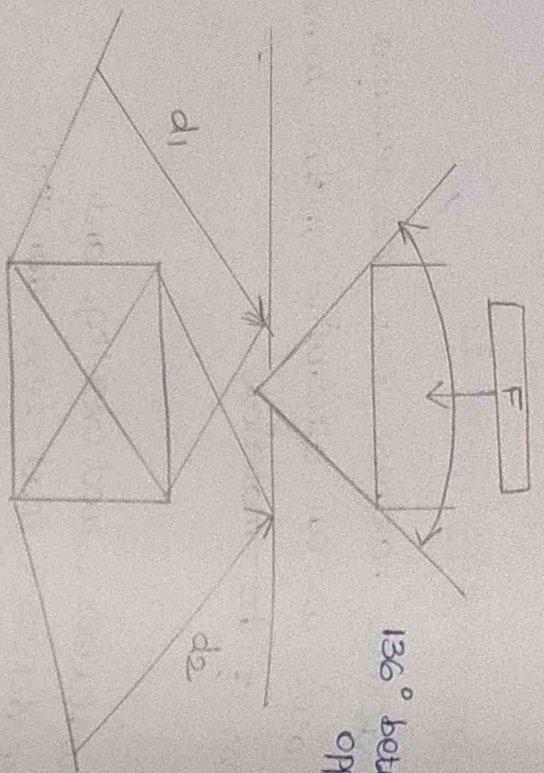
- Macro vickers (load over 1kg) and
- Micro vickers (load less than 1kg).

- The Vickers macrotest is often easier to use than other hardness tests. Since the required calculations are independent of the size of the indenter, and the indenter can be used for all materials irrespective of hardness.

- However, Vickers macrohardness test is not as widely used for all materials irrespective of hardness as Brinell or Rockwell test.

- A diamond in the form of a slight pyramid with a square base angle of 136° between opposite faces is forced into the material under a load.

- It is represented as,



136° between opposite faces

The two diagonals d_1 and d_2 indentation left in the surface of the material after removing they are measured, &

Vicker's hardness number is

$$V.H.N = \frac{P}{A}$$

$$= \frac{2P \sin(92^\circ/2)}{d^2}$$

$$= 1.8544 \frac{P}{d^2}$$

where,

P - applied load in kg

A - surface area of indentation in sq. mm

\bar{d} - mean of diagonal impression mm

θ - angle between opposite faces of diamond pyramid (136°)

$$d = \frac{(d_1 + d_2)}{2}$$

Diagonal Measurement In Vicker's test :-

Diagonals of the indentation produced are approximately seven times larger than the depth of indentation, especially with high hardness metals it provides better accuracy than that could be obtained with the rockwell or brinell.

This is because of the fact by virtue of its indentation, higher measurement accuracy can be obtained even if the indentation depth is small. So this makes the vickers test especially suitable for hardness measurements in thin layers and very hard alloys.

Vickers hardness number is nearly independent of the test loads for homogeneous materials due to the fact that the ratio between the diagonals of the impression remains constant under different test loads above 5kg.

At lower loads it may be load dependent.

The diagonal of the square indentation is measured to an accuracy of 0.001 mm.

Advantages:-

The indentation always have the same shape whatever be the load. This makes the measurement independent of load.

Soft as well as hard metals may be tested. Test may be conducted in low-load and high load range as well.

The vickers hardness apparatus from the micro load range is independent of the test load applied (up to 5 kg). The pyramidal impression damages the work pieces only slightly.

This test is very useful for testing hardness of polished or vitrified surface due to small impression made on the test.

This test is accurate suitable for metals as thin as 0.015 mm.

Hardness is decreased exponentially with absolute temperature of the material $H = Ae^{-B/T}$, where A and B are constants.

Disadvantages:-

It takes more time for each measurement when porosity is present then the measurement taken by vickers shows more deviation than

those of Binet's test.

Write the technological properties of engineering materials:

• Technological properties are those qualities which give information regarding the suitability of metals for various technological operations or processes such properties are highly desirable in shaping, forming and fabrication of materials.

The following technological properties will be discussed

- Malleability
- Weldability
- Castability
- Formability
- Malleability.

Malleability:

- It is defined as the with a given material can be cut permitting the removal of material with a satisfactory finish at lower cost. It's used to signify how well a material takes a good finish.
- It may also called finish ability.

- It have high cutting speed.
- It have low power consumption
- It have a good surface finish

Machinability Index:

- The machinability of different metals to be machined may be compared by using the machinability index of each material which may be defined as follows:

$$\% = \frac{\text{cutting speed of metal investigated for tool life}}{\text{cutting speed of std. steel for combn tool life}}$$

A standard or steel has a carbon content of 0.15%, max, manganese of 0.06 to 0.10% and sulphur of 0.80 to 0.03% and can be machined relatively easily its machinability index is arbitrarily fixed as 100%.

Weldability:

- It is defined as the capacity of a metal to be welded under the fabrication conditions imposed in a specific suitably designed structure.

• The weldability is affected by the following factors,

- composition of metal
- thermal properties
- filler materials
- flux material
- welding technique

The following materials have good weldability in the ascending order.

- stainless steel
- low alloy steel
- cast iron
- carbon steel
- Iron.

Castability.

- The ease with which a metal can be cast into form is known as castability of the metal.

• It is based on factors like solidification rate, gas porosity, segregation, shrinkage etc,

- The following factors are favourable to castability of metal.

→ Fluidity of metal

- low rate of shrinkage (as the contraction in the volume of a metal when it goes from a molten to a solid state).

low or negligible segregation
low gas porosity,

Formability :

• It is the ability of metals of forming into different shapes.

• the various factors which give to a large content, the flow ability or ductility of the material are,

metal structure

grain size

hot and cold working

alloying elements

softening heat treatments (annealing and

normalizing).

A small grain size is recommended for shallow drawing of metals whereas for heavy drawing relatively large grains are recommended.

In softening heat treatments the annealing and normalising the ductility of metal is resolved,

The wrapped and distorted crystal are reformed and consequently the force required slipper is reduced.

Malleability :-

It is the ease with which the material undergoes too much change in shape under compressive stresses without rupture.

The materials like soft steel, wrought iron, copper and aluminium have good malleability,

they can be hammered or rolled into the desired shape without rupture.