



BHARATHIDASAN UNIVERSITY

**Tiruchirappalli- 620024,
Tamil Nadu, India**

Department of Physical Education and Yoga

**Course Title : KINESIOLOGY AND
Course Code BIOMECHANICS
: 21BPE42**

Unit- (III)

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Machines

- The musculoskeletal system is a series of simple machines
- Machines are used to create a mechanical advantage
- They may balance multiple forces
- Enhance force thus reducing the amount of force needed to produce
- Enhance the range of motion or the speed of movement

Terms

- Mechanics
 - Study of physical actions and forces
- Kinematics:
 - Description of motion (e.g, how fast, how high, etc.) without consideration given to its mass or the forces acting on it.
- Kinetics:
 - The study of forces associated with motion.
 - Example: Pushing on the table may or may not move the table, depending upon the strength and direction of the push

Levers

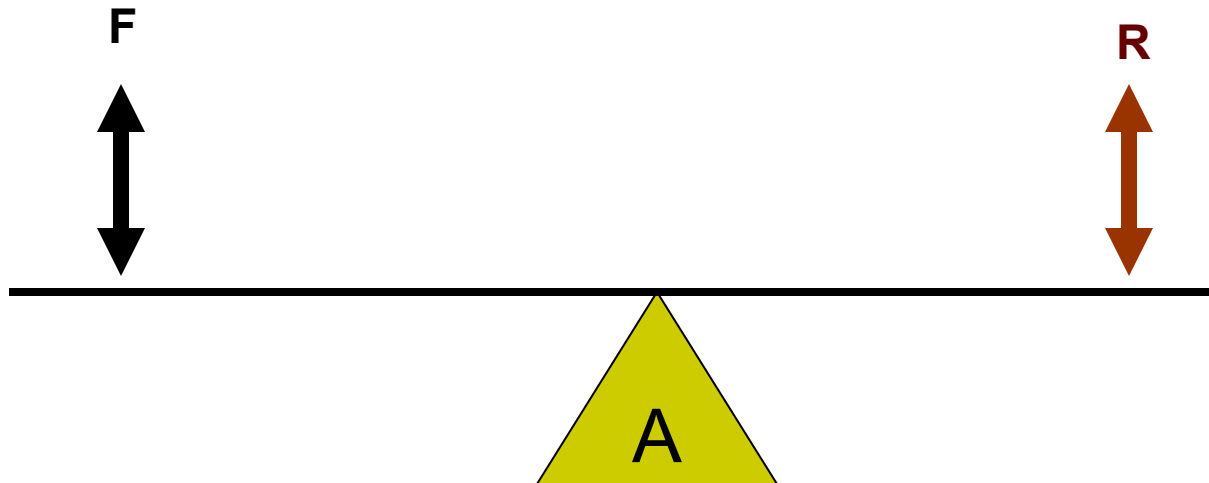
- ❑ Levers are used to alter the resulting direction of the applied force
- ❑ A lever is a rigid bar (bone) that turns about an axis of rotation or fulcrum (joint)
- ❑ The lever rotates about the axis as a result of a force (from muscle contraction)
- ❑ The force acts against a resistance (weight, gravity, opponent, etc.)



Levers

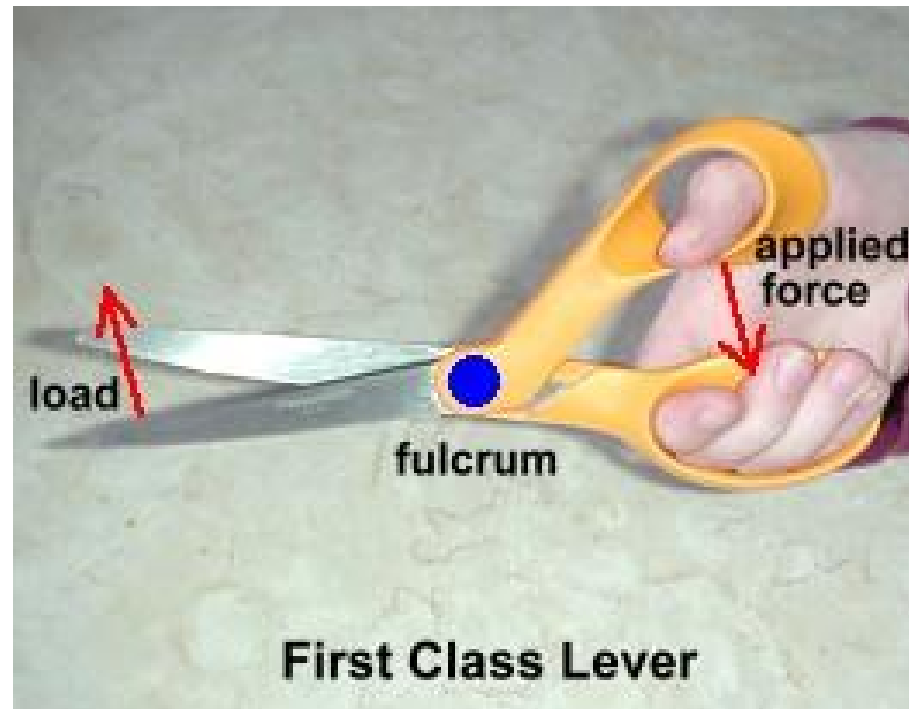
- The relationship of the points determines the type of lever
- The axis (joint), force (muscle insertion point), and the resistance (weight, etc.)

First Class

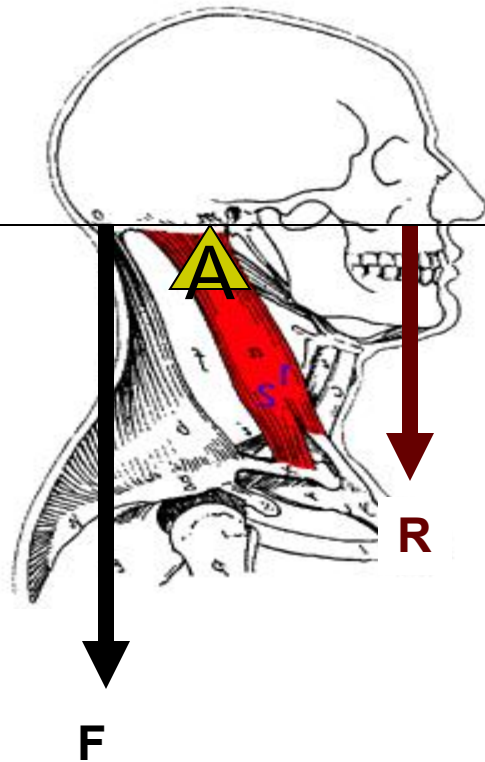


F A R

First Class

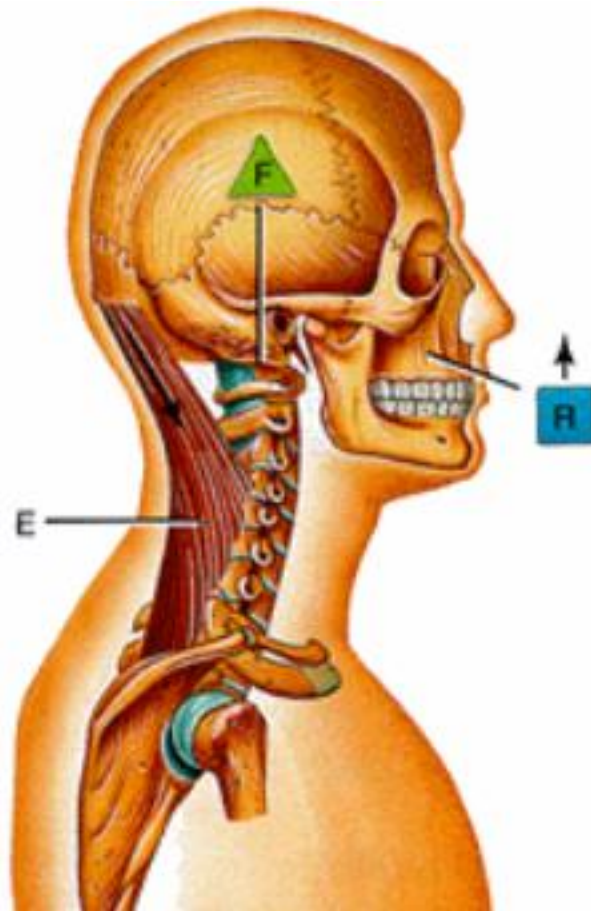


First Class



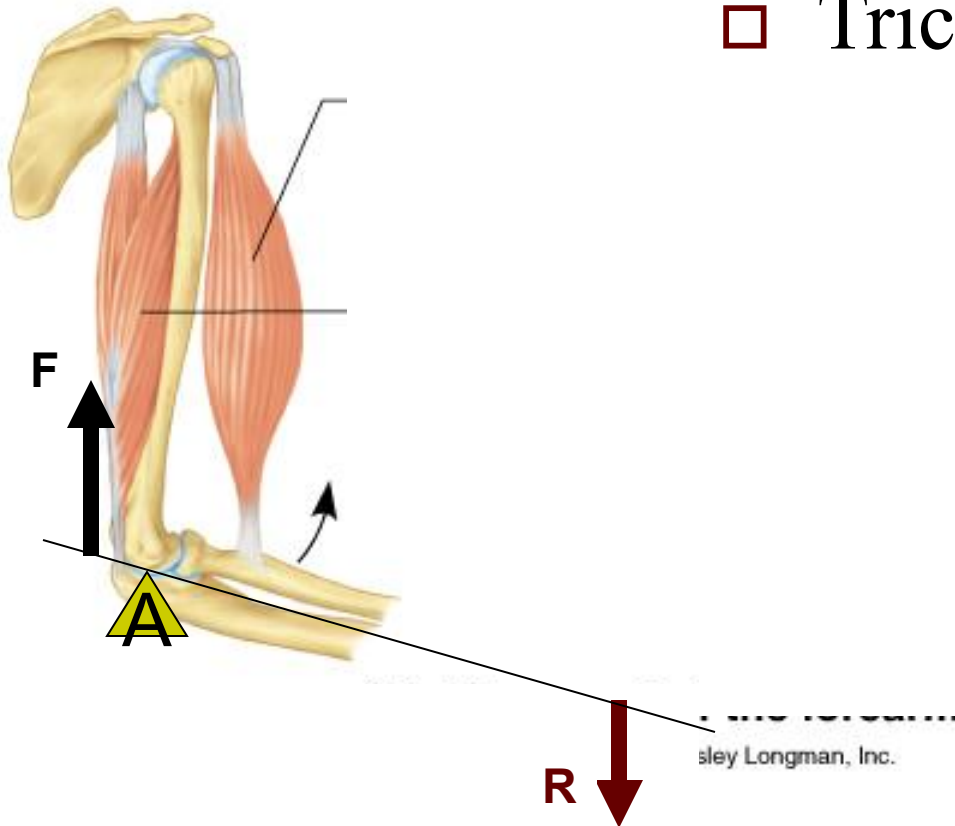
- Neck extension
- Erector spinae and Splenius

First Class



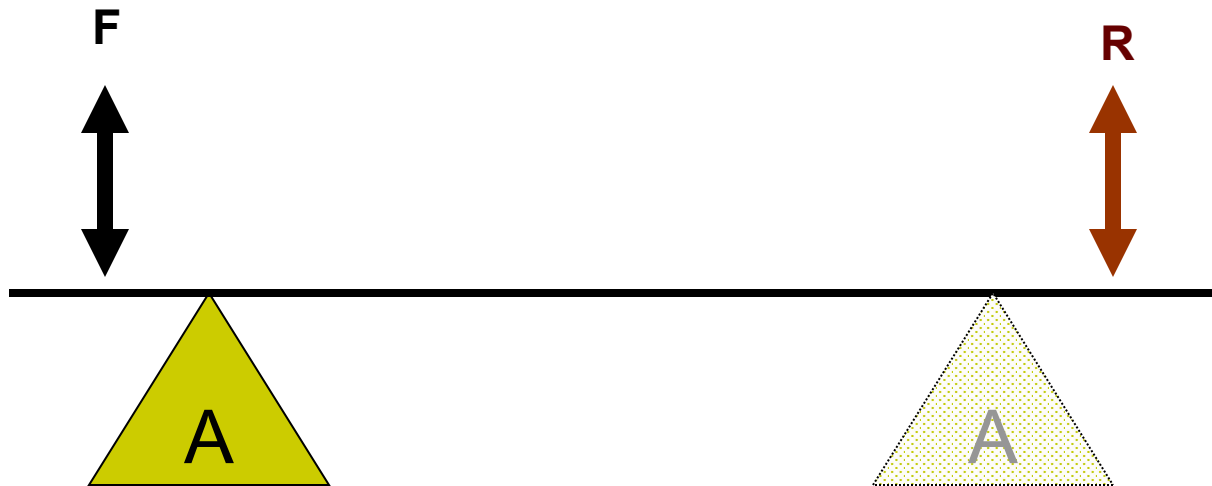
First Class

- Elbow extension
- Triceps

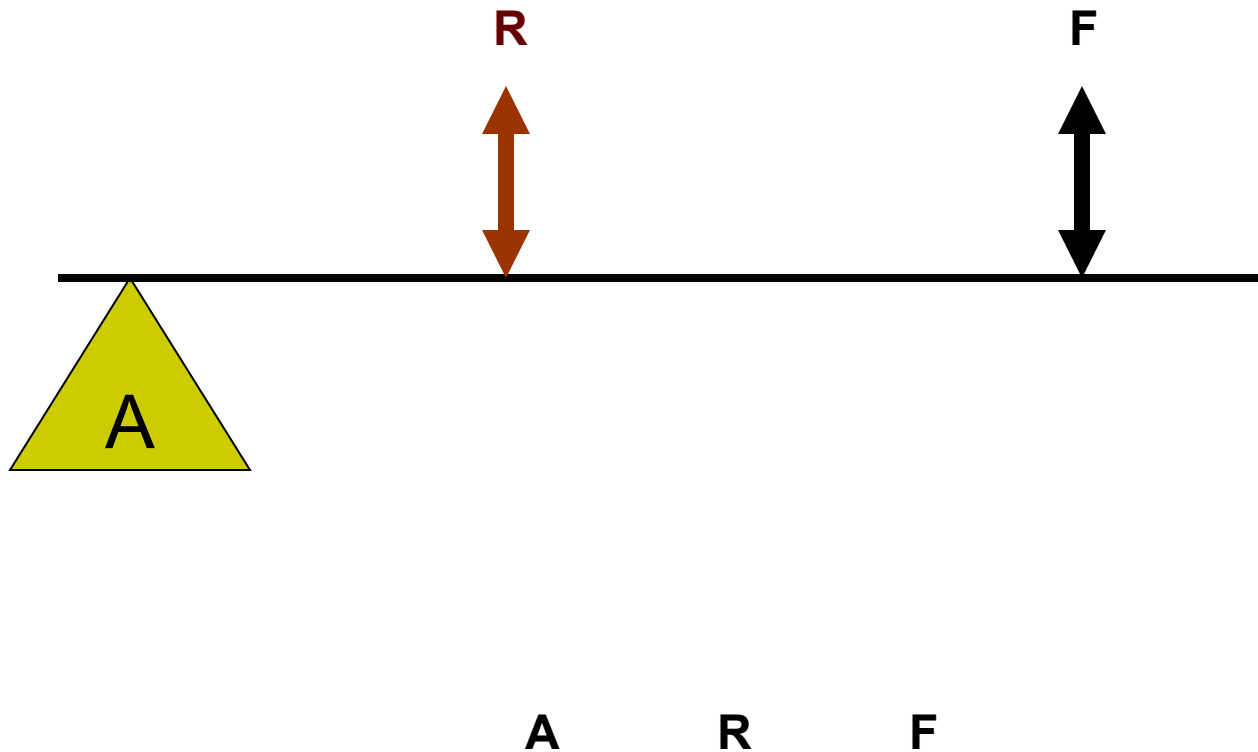


First Class

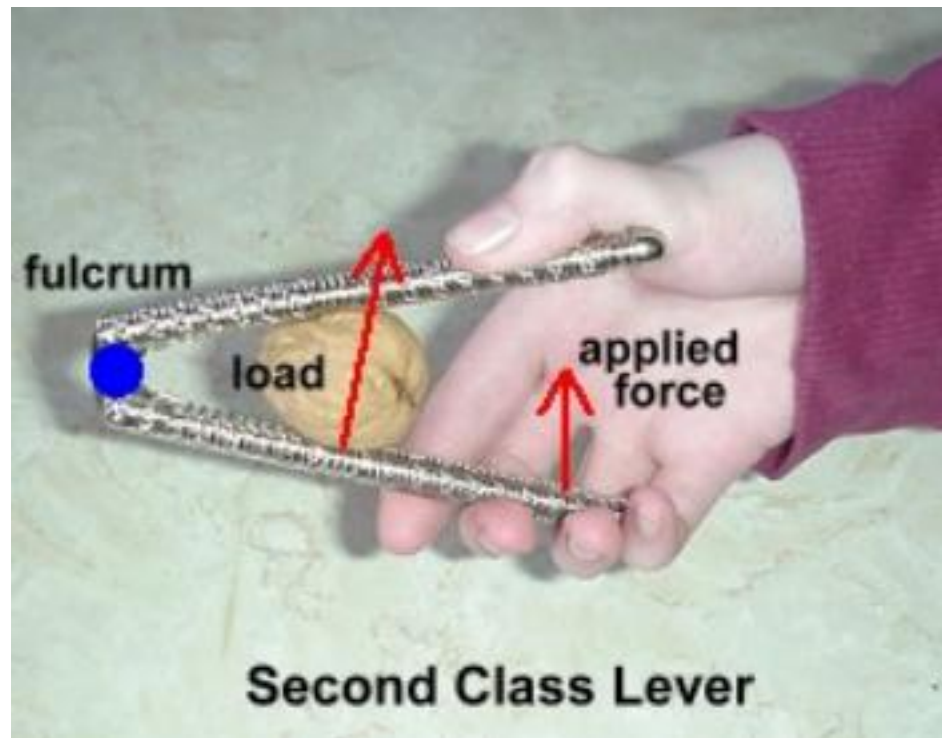
- Designed for speed and range of motion when the axis is closer to the force
- Designed for strength when the axis is closer to the resistance



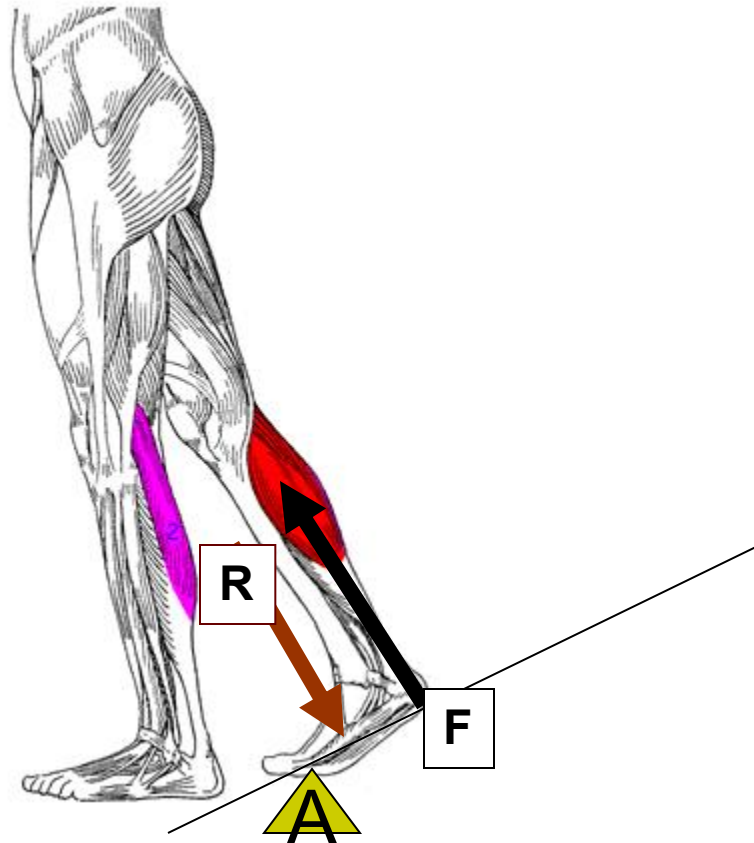
Second Class



Second Class

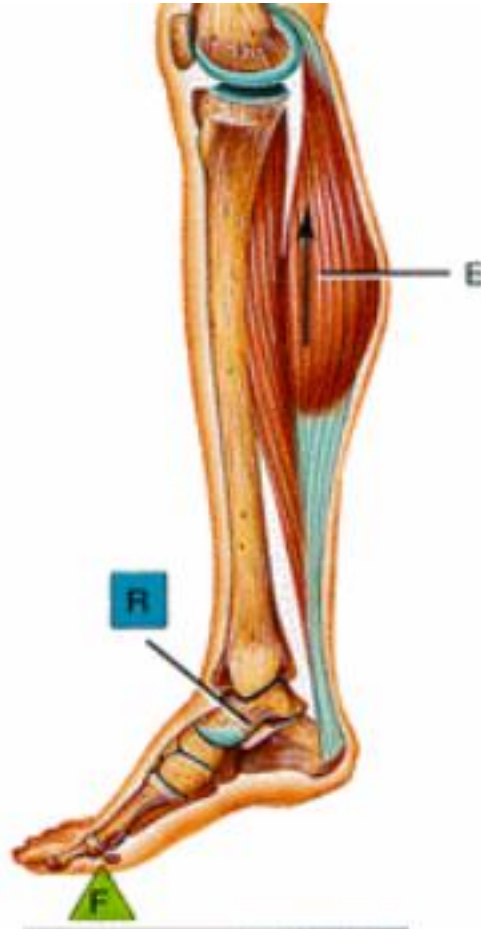


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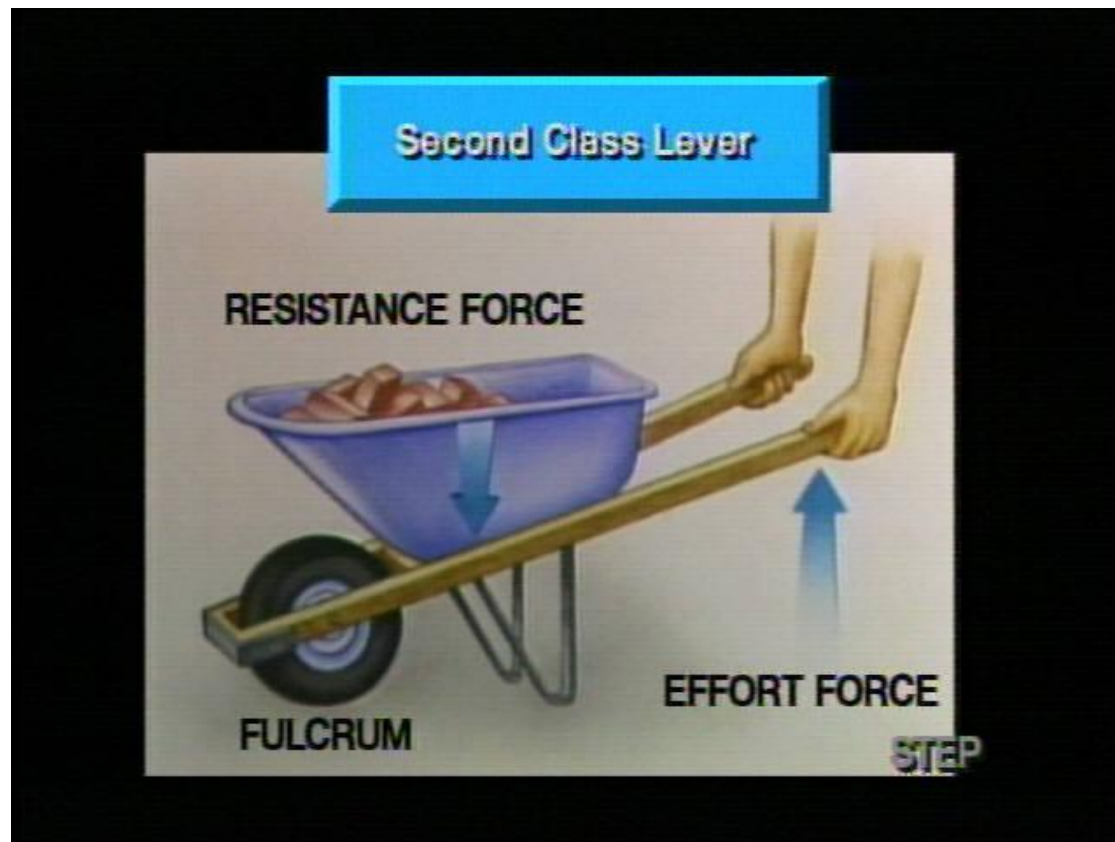
- Plantar flexion
- Gastrocnemius and Soleus

Second Class

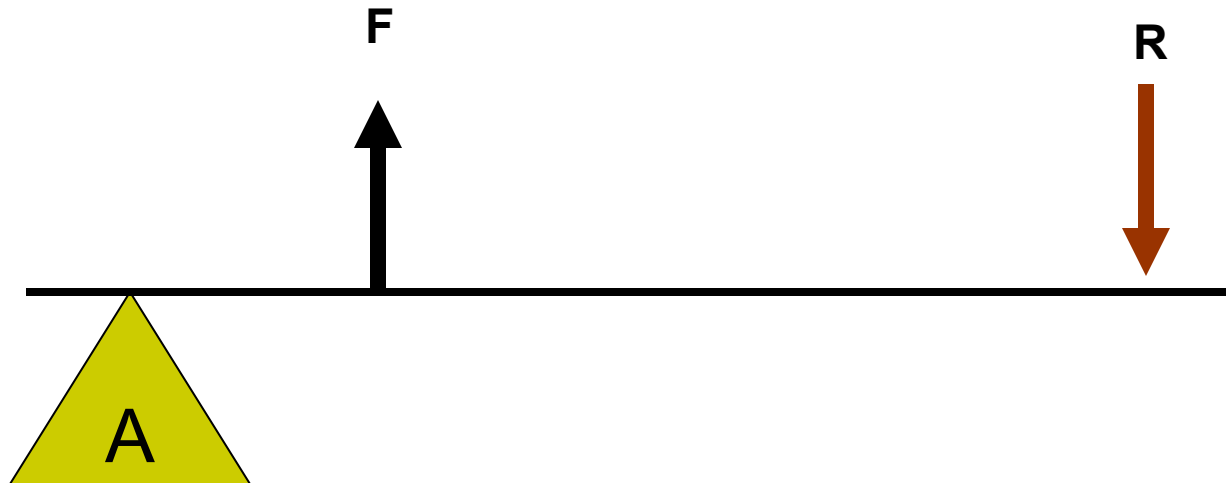


Second Class

- Designed more for force

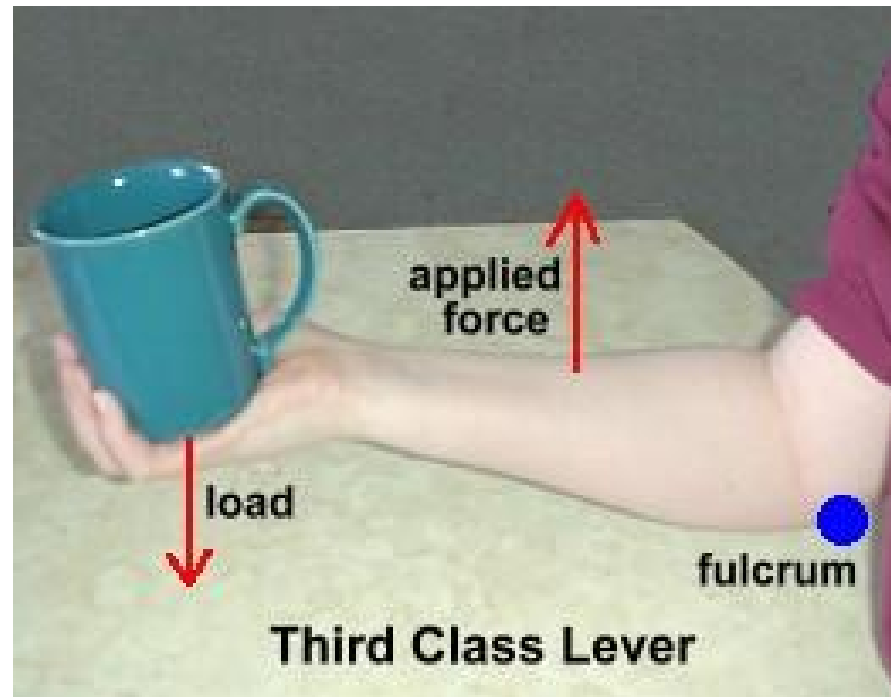


Third Class



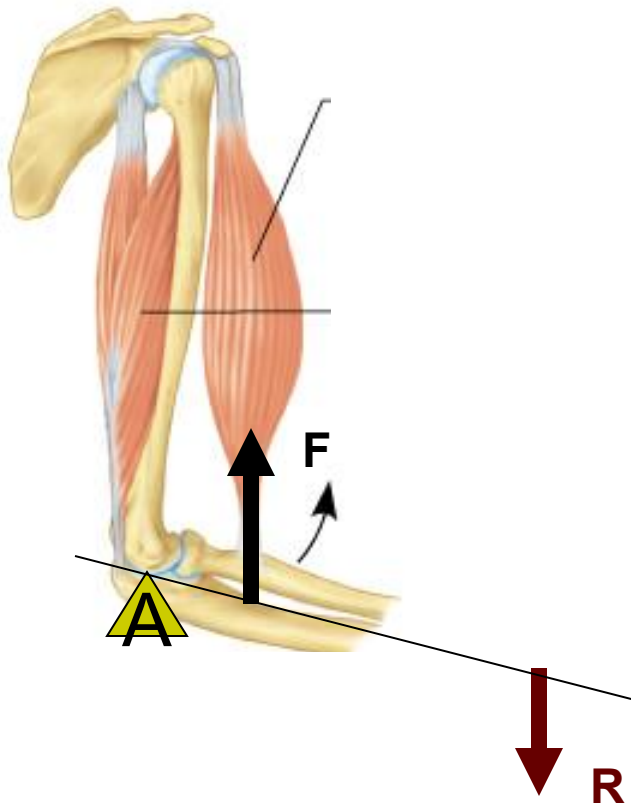
A F R

Third Class



Third Class

- Elbow flexion
- Biceps brachii and Brachialis



Third Class

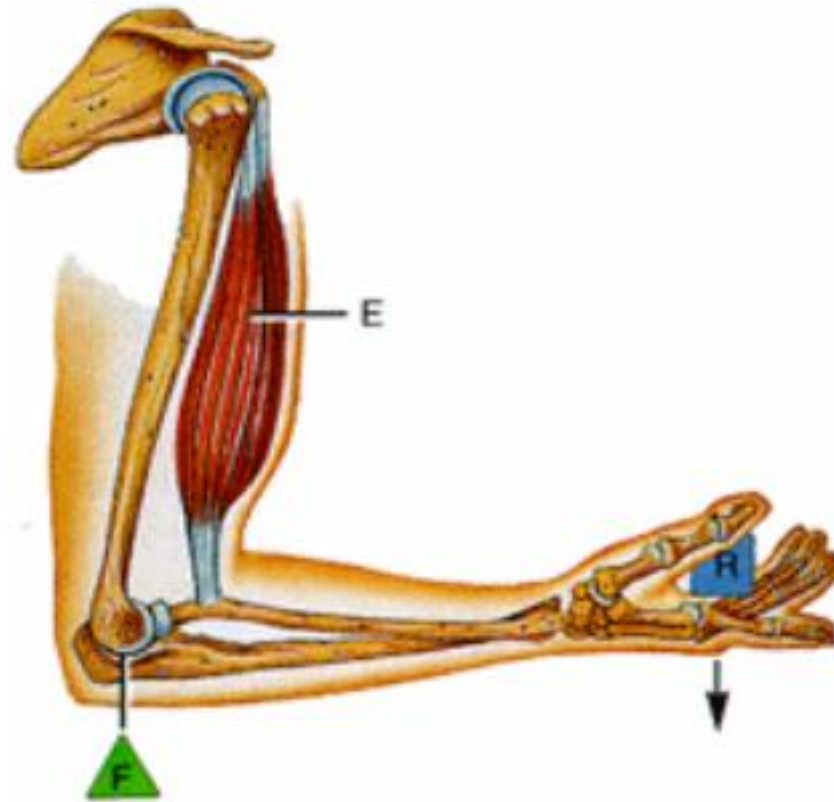




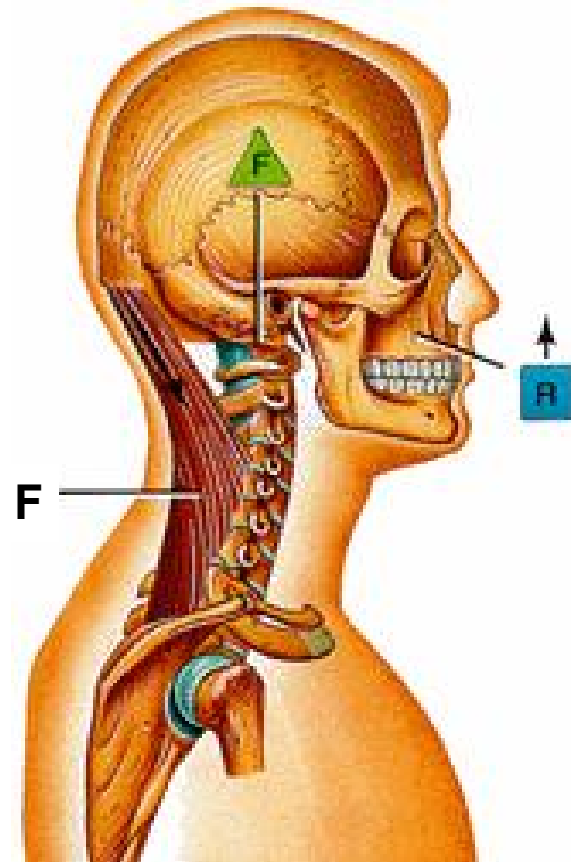


Table 3.1

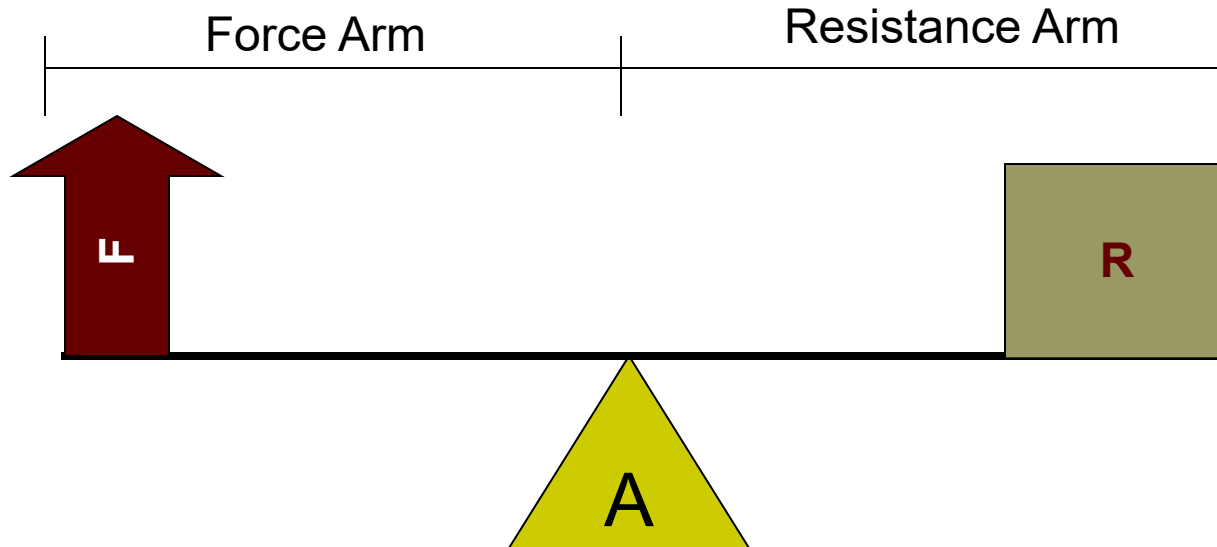
|  CLASS |  ARRANGEMENT | ARM MOVEMENT |  FUNCTIONAL DESIGN | RELATIONSHIP TO AXIS | PRACTICAL EXAMPLE |  HUMAN EXAMPLE |
|--------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------|----------------------------------------------------|--------------------------------------------------------------------------------------------------------|----------------------|--------------------------|------------------------------------------------------------------------------------------------------|
| 1 ST | F-A-R | Resistance arm and force arm in opposite direction | Balanced movements | Axis near middle | Seesaw | Erector spinae neck extension |
| | | | Speed and range of motion | Axis near force | Scissors | Triceps |
| | | | Force (Strength) | Axis near resistance | Crow bar | |
| 2 ND | A-R-F | Resistance arm and force arm in same direction | Force (Strength) | Axis near resistance | Wheel barrow, nutcracker | Gatroc and soleus |
| 3 RD | A-F-R | Resistance arm and force arm in same direction | Speed and range of motion | Axis near force | Shoveling dirt, catapult | Biceps brachii |

Factors In Use of Anatomical Levers

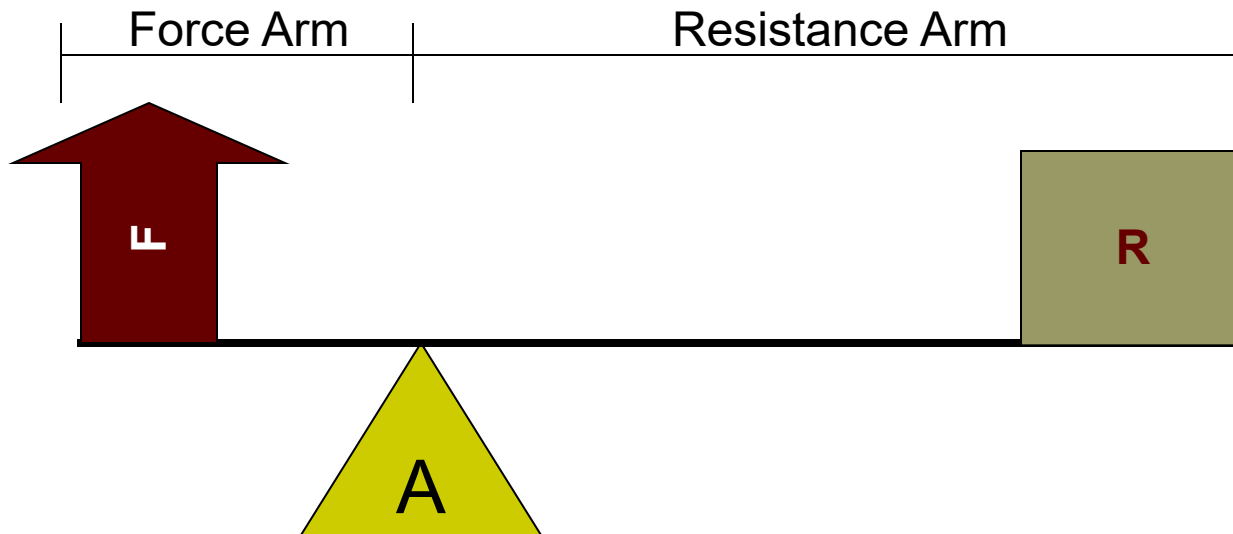
- A lever system can be balanced if the F and FA equal the R and RA



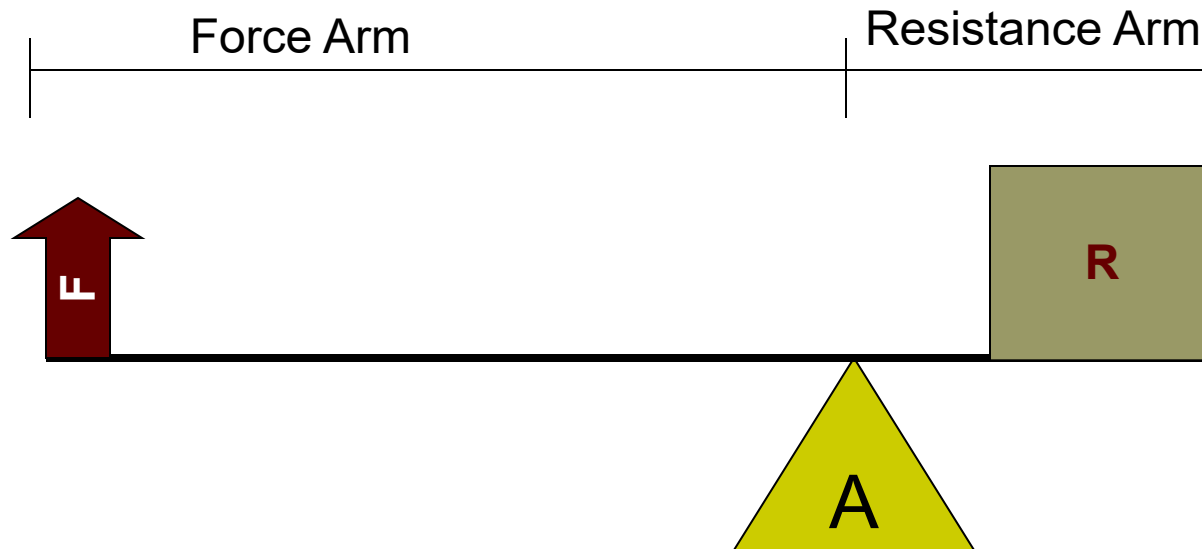
Balanced



Balance with More Force



Balanced with Less Force

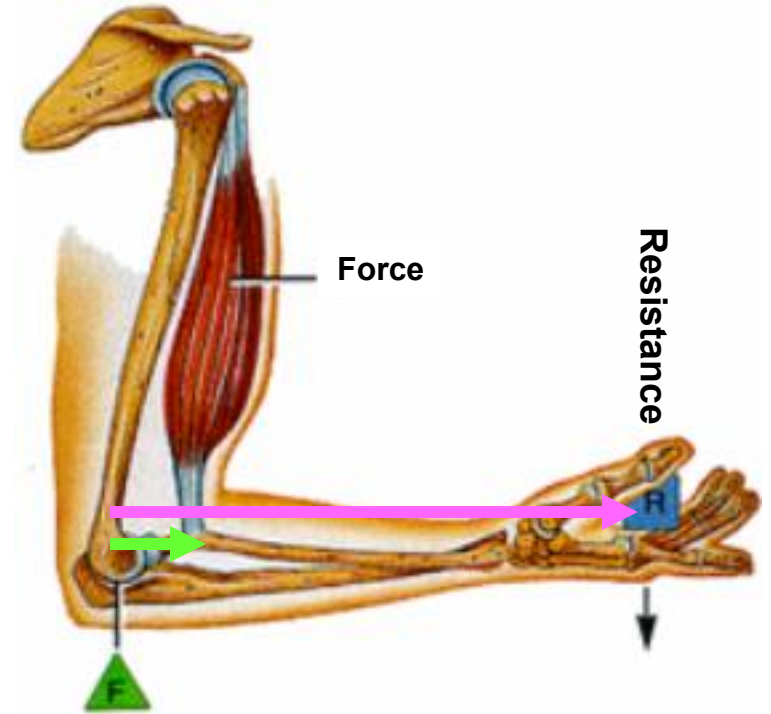


Factors In Use of Anatomical Levers

- A lever system can become unbalance when enough torque is produced
- Torque is the turning effect of a force; inside the body it caused rotation around a joint.
- $\text{Torque} = \text{Force (from the muscle)} \times \text{Force Arm (distance from muscle insertion from the joint)}$

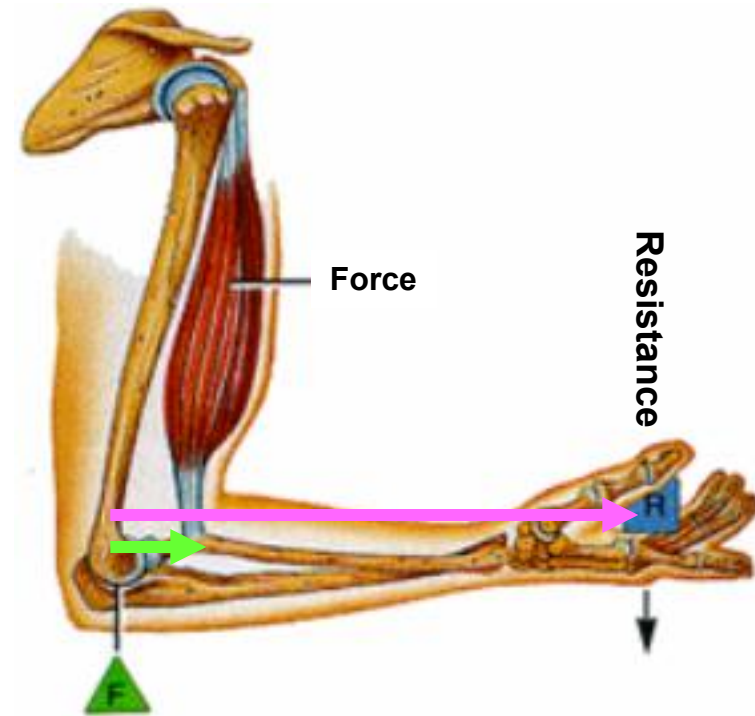
Practical Application

- **Force** is produced by the muscle
- **FA** the distance from joint (i.e. axis or fulcrum) to insertion of the force
- **Resistance** could be a weight, gravity, etc.
- **RA** the distance from joint to the center of the resistance



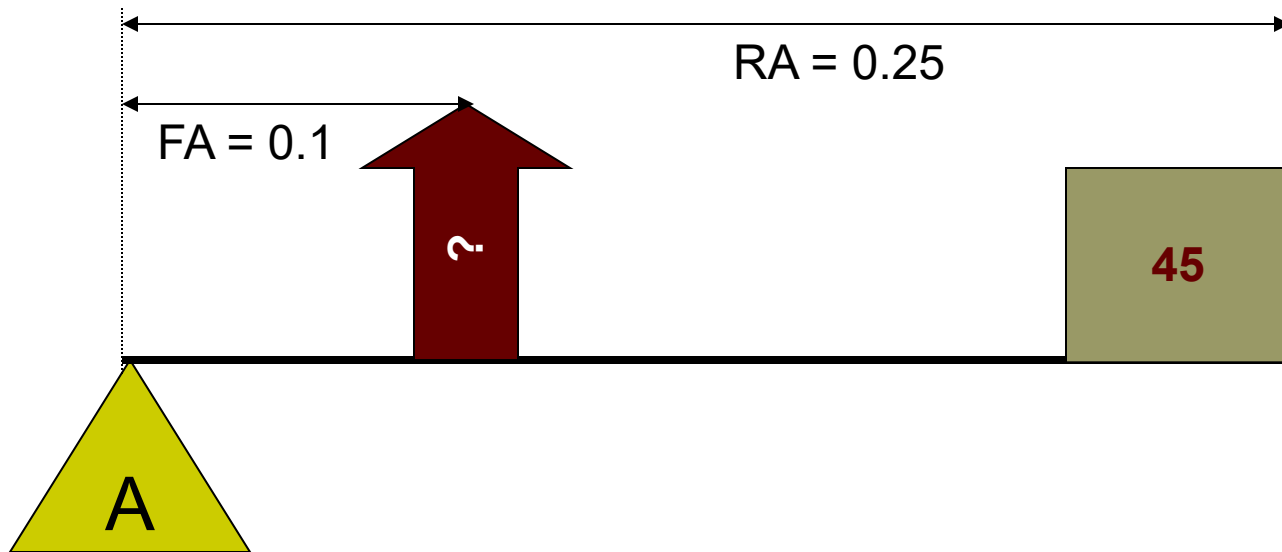
Examples

1. How much torque needs to be produced to move 45 kg when the RA is 0.25 m and the FA is 0.1 meters?
 - Use the formula $F \times FA = R \times RA$
 - Note: A Newton is the unit of force required to accelerate a mass of one kilogram one meter per second per second.



Example 1

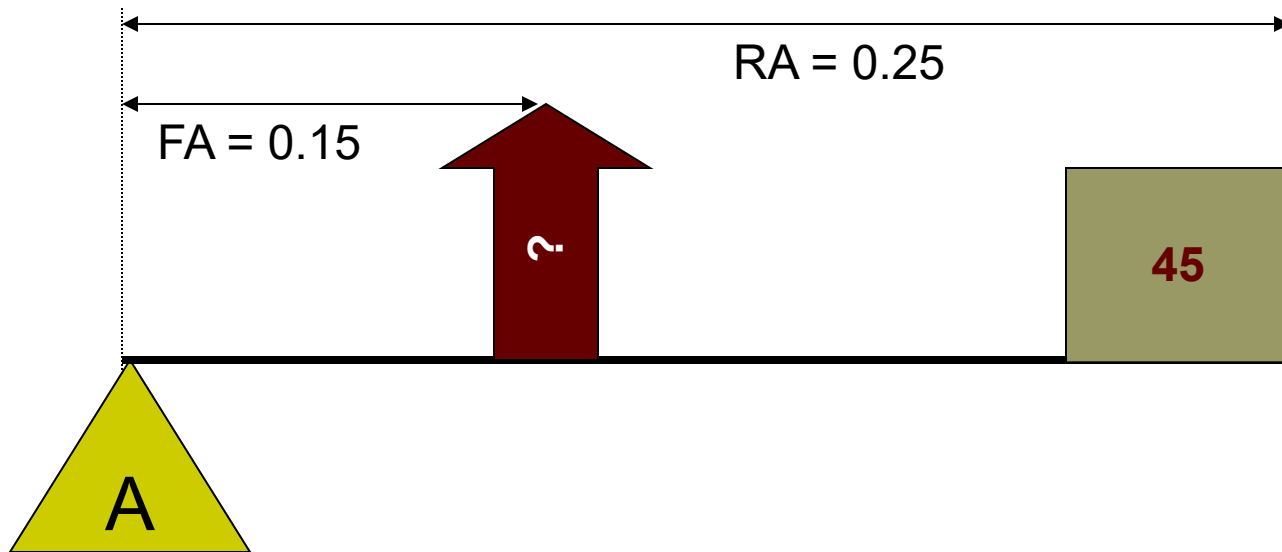
- $F \times 0.1 \text{ meters} = 45 \text{ Kg} \times 0.25 \text{ meters}$
- $F \times 0.1 \text{ kg} = 11.25 \text{ Kg-meters}$
- $F = 112.5 \text{ Kg}$



Example 2: Increasing the FA

2. What if the FA was increased to 0.15 meters?

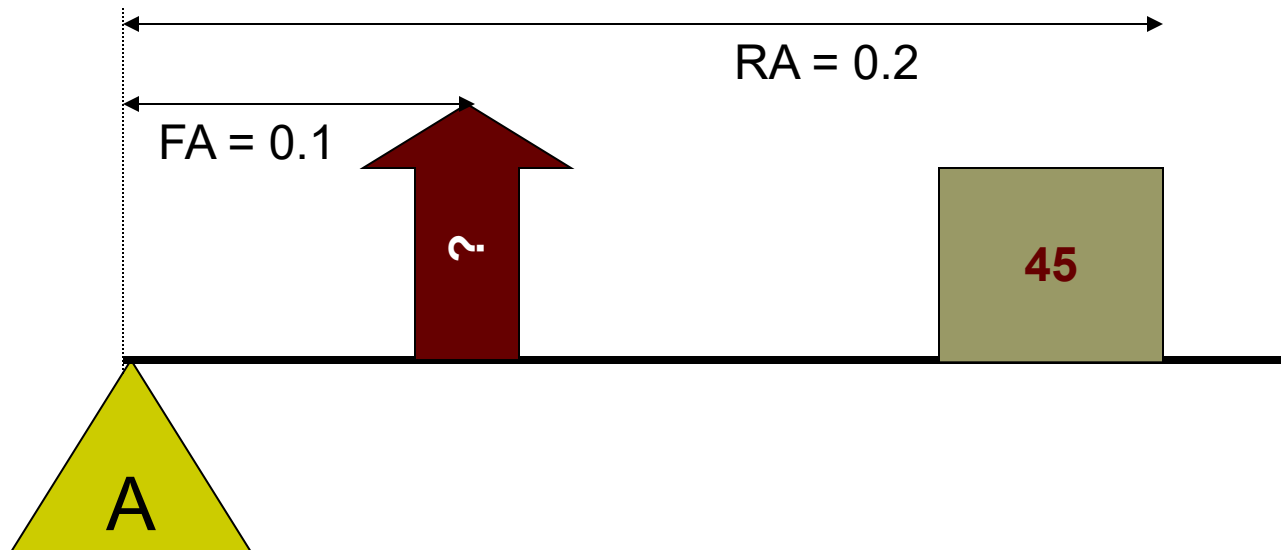
- $F \times 0.15 \text{ meters} = 45 \text{ Kg} \times 0.25 \text{ meters}$
- $F \times 0.15 = 11.25 \text{ Kg-meters}$
- $F = 75 \text{ Kg}$



Example 3: Decreasing the RA

3. What if the RA was decreased to 0.2 meters?

- $F \times 0.1 \text{ meters} = 45 \text{ Kg} \times 0.2 \text{ meters}$
- $F \times 0.1 = 9 \text{ Kg-meters}$
- $F = 90 \text{ Kg}$



Summary

- The actual torque needed to move a given resistance depends on the length of the FA and RA
- As the FA increases or RA decreases, the required torque decreases.
- As the FA decreases or RA increases, the required torque increases.

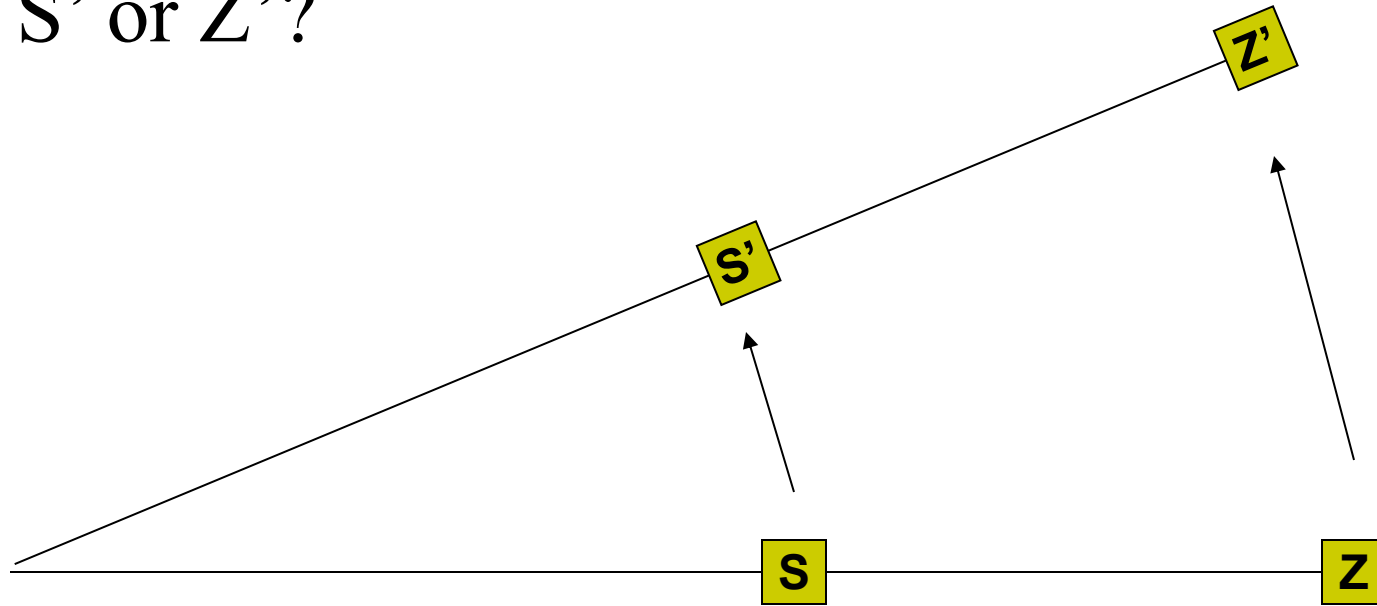


Levers Continued

- Inside the body, several joints can be “added” together to increase leverage (e.g. shoulder, elbow, and wrist).
- An increase in leverage can increase velocity

Lever Length

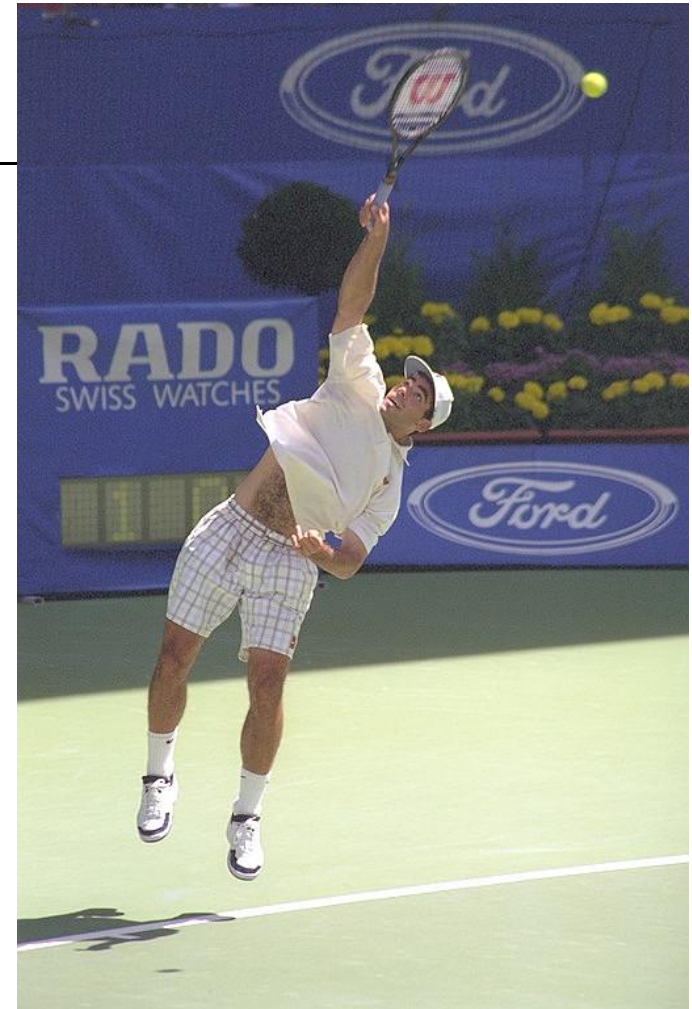
- Where is the velocity or speed the greatest; at S' or Z' ?



- How can this principle be applied to tennis?

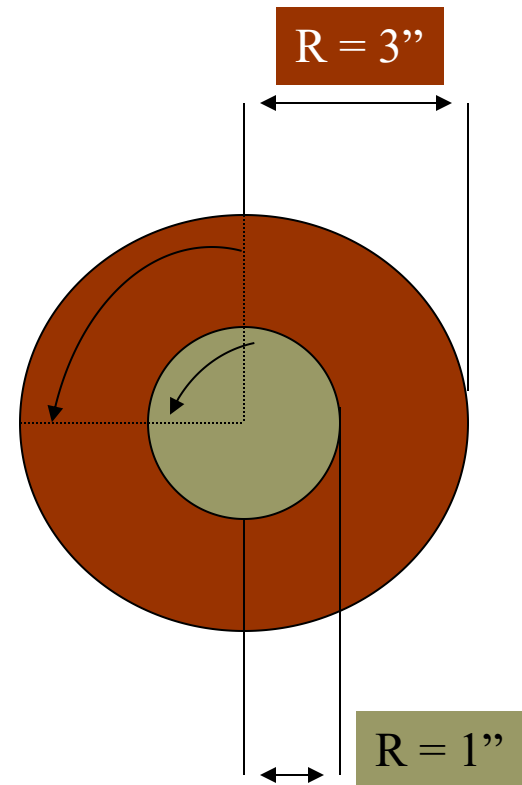
Lever Length

- A longer lever would increase speed at the end of the racquet unless the extra weight was too great. Then the speed may actually be slower.



Wheels and Axles

- Wheels and axles can enhance speed and range of motion
- They function as a form of lever
- Mechanical advantage = **radius of wheel** / **radius of axle**



Wheels and Axles

- Consider the humerus as an axle and the forearm/hand as the wheel
- The rotator cuff muscles inward rotate the humerus a **small amount**
- The hand will travel a **large amount**
- A little effort to rotate the humerus, results in a significant amount of movement at the hand

