

Ordinary Differential Equations

Course Code: 21M03CC

UNIT - III

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HW Prove that $\int_0^1 x^3 J_0(x) dx = 2 J_0(1) - 3 J_1(1)$

Hint: (i) use the above problem: $x \geq 1$

(ii) $J_{p-1}(x) + J_{p+1}(x) = 2 \frac{p}{x} J_p(x) \quad : \underline{p \geq 1}$

The existence and uniqueness of solutions:

Picard \rightarrow French

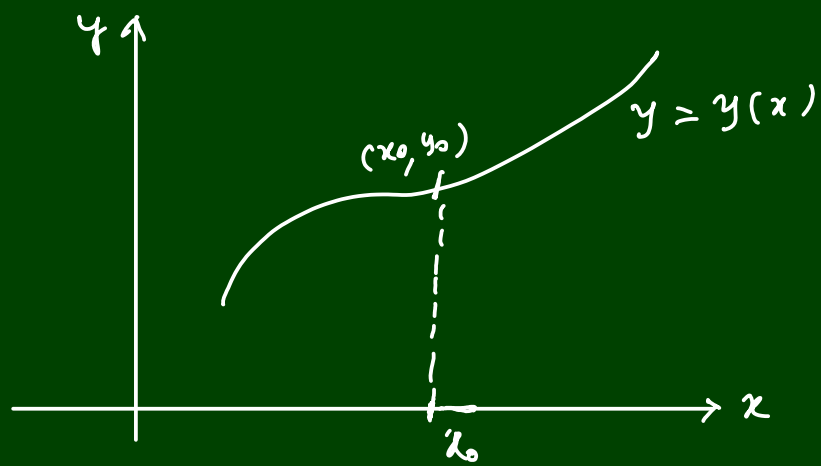
Consider the following first order IVP

(1)
$$\begin{cases} y' = f(x, y) \\ y(x_0) = y_0 \end{cases}, \quad f(x, y) \rightarrow \text{arbitrary function defined and continuous in some neighbourhood of } (x_0, y_0)$$

$$\begin{aligned} F(x, y, y') &= 0 \\ \Downarrow \\ y' &= f(x, y) \end{aligned}$$

$y(x_0) \rightarrow y(x)$ evaluated at $x = x_0$

Aim: To devise a method for constructing a function $y = y(x)$ whose graph passes thro' the point (x_0, y_0) and that satisfies the diff^l eqⁿ $y' = f(x, y)$ in some nbhd of x_0 .



Method of successive approximations

Consider ①

$$y' = f(x, y)$$

$$y(x_0) = y_0$$

Key idea: replacing the ivp ① by an equivalent integral equation.

$$y(x) = y_0 + \int_{x_0}^x f(t, y(t)) dt$$

[This is called an integral equation because the unknown function occurs under the integral sign]

We write ① as

$$y'(x) = f(x, y(x)) \rightarrow DE$$

Integrating w.r.t x

$$\int_{x_0}^x y'(x) dx = \int_{x_0}^x f(t, y(t)) dt$$

$$\int_{x_0}^x d(y(x)) = \int_{x_0}^x f(t, y(t)) dt$$

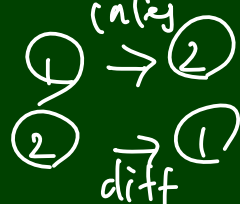
$$\left[\begin{aligned} [y(x)]_{x_0}^x &= \int_{x_0}^x f(t, y(t)) dt \\ y(x) - y(x_0) &= \int_{x_0}^x f(t, y(t)) dt \end{aligned} \right] \quad y(x_0) = y_0$$

$$y(x) - y(x_0) = \int_{x_0}^x f(t, y(t)) dt$$

$$y(x) = y_0 + \int_{x_0}^x f(t, y(t)) dt$$

I. F

intgr



① and ② are equivalent.

Diff ② w.r.t x

$$y'(x) = 0 + \frac{d}{dx} \int_{x_0}^x f(t, y(t)) dt$$

$$= \int_{x_0}^x \frac{\partial}{\partial x} (f(t, y(t))) dt + f[x, y(x)] \frac{d}{dx}(x) - f[x_0, y(x_0)] \frac{d}{dx}(x_0)$$

$$= 0 + f[x, y(x)](1) - 0$$

① $\begin{cases} y'(x) = f(x, y(x)) \\ y(x_0) = y_0 \end{cases} \longrightarrow$ putting $x = x_0$ in ②.

$$\left. \begin{aligned} y' &= f(x, y) \\ y(x_0) &= y_0 \end{aligned} \right\} \xrightarrow{\text{equivalent}} y(x) = y_0 + \int_{x_0}^x f(t, y(t)) dt$$

Any solution $y(x)$ of ① is a continuous solution of ②
If $y(x)$ is a cont^s solⁿ of ② then it is a solⁿ of ①

Successive approximation

We start with our initial approximation as

$$y_0(x) = y_0$$

$$\text{Then } y_1(x) = y_0 + \int_{x_0}^x f[t, y_0(t)] dt$$

$$y_2(x) = y_0 + \int_{x_0}^x f[t, y_1(t)] dt$$

$$\vdots$$
$$y_n(x) = y_0 + \int_{x_0}^x f[t, y_{n-1}(t)] dt$$

\vdots

* This procedure is called Picard's method of successive approximation.

Ex $y' = y, \quad y(0) = 1$

$$y' = f(x, y)$$
$$y(x_0) = y_0$$

$$y_0(x) = y_0$$

$$\text{i.e., } y_0(x) = 1$$

$$x_0 = 0, \quad y_0 = 1$$

$$\underline{f(x, y) = y}$$

$$y_n(x) = y_0 + \int_{x_0}^x f[t, y_{n-1}(t)] dt$$

$$y_n(x) = 1 + \int_0^x y_{n-1}(t) dt$$

$$\therefore y_1(x) = 1 + \int_0^x y_0(t) dt$$
$$= 1 + \int_0^x 1 \cdot dt$$

$$y_0(x) = 1$$
$$y_0(t) = 1$$

$$y_1(x) = 1 + \int_0^x dt = 1 + [t]_0^x = 1 + x \quad \left| \begin{array}{l} y_1(x) = 1+x \\ y_1(t) = 1+t \end{array} \right.$$

$$y_2(x) = 1 + \int_0^x y_1(t) dt = 1 + \int_0^x (1+t) dt$$

$$= 1 + \left[t + \frac{t^2}{2} \right]_0^x = 1 + x + \frac{x^2}{2}$$

$$y_3(x) = 1 + \int_0^x y_2(t) dt = 1 + \int_0^x \left[1+t + \frac{t^2}{2} \right] dt$$

$$= 1 + \left[t + \frac{t^2}{2} + \frac{t^3}{6} \right]_0^x$$

$$= 1 + x + \frac{x^2}{2} + \frac{x^3}{6} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!}$$

⋮

$$y_n(x) = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots + \frac{x^n}{n!}$$

$$\lim_{n \rightarrow \infty} \{ y_n(x) \} \rightarrow e^x \quad (\underline{y(x)})$$

$$\underline{y = e^x} \quad \checkmark$$

$\lim_{n \rightarrow \infty} \{ y_n(x) \}$
 uniformly $\rightarrow y(x) ?$

$\frac{\neq 0}{0}$

check

$$y' = y$$

$$\frac{dy}{dx} = y \Rightarrow \int \frac{dy}{y} = \int dx$$

$$\log y = x + \log c$$

$$\log y - \log c = x$$

$$\log \frac{y}{c} = x \Rightarrow \frac{y}{c} = e^x$$

$$\Rightarrow \underline{\underline{y = ce^x}} \rightarrow y(x) = ce^x \quad | \quad y(0) = 1$$
$$y(0) = ce^0$$
$$\underline{\underline{1 = c}}$$

$$\therefore \underline{\underline{y = e^x}}$$

HW

Use the method of successive approximations to solve $y' = x + y$, $y(0) = 1$.

[Check your answer by solving the diff^l eqⁿ directly]

Δ. Lml
28/12/2020

Recall

Picard's method of successive approximation.

IVP $x_0 \in [a, b]$

$$\begin{cases} y' = f(x, y) \\ y(x_0) = y_0 \end{cases} \leftrightarrow y(x) = y_0 + \int_{x_0}^x \underbrace{f(t, y(t))}_{\text{integrand}} dt$$

PMSt

$$y_n(x) = y_0 + \int_{x_0}^x f(t, y_{n-1}(t)) dt$$

with $y_0(x) = y_0$

$\lim_{n \rightarrow \infty} \{ y_n(x) \} \xrightarrow{\text{uniformly}} y(x) \quad (?)$

$y(x)$ is a solⁿ of I.E and hence it is a solⁿ of IVP

Ex. 2

$$y' = x + y, \quad y(0) = 1$$

Start with $y_0(x) = y_0 = 1$

$$y_1(x) = y_0 + \int_0^x f(t, y_0(t)) dt$$

$$= 1 + \int_0^x (1+t) dt$$

$$y_1(x) = 1 + \left[t + \frac{t^2}{2} \right]_0^x = 1 + x + \frac{x^2}{2}$$

$$= 1 + x + \frac{x^2}{2!}$$

$$y_2(x) = y_0 + \int_0^x f(t, y_1(t)) dt$$

$$= 1 + \int_0^x (1 + 2t + \frac{t^2}{2}) dt$$

$$\begin{cases} y' = f(x, y) \\ y(x_0) = y_0 \\ f(x, y) = x + y \\ x_0 = 0, y_0 = 1 \\ f(x, y) = x + y \\ f(t, y_0(t)) = t + 1 \\ f(x, y) = x + y \\ f(t, y_1(t)) = t + 1 + t + \frac{t^2}{2} \\ = 1 + 2t + \frac{t^2}{2} \end{cases}$$

$$= 1 + \left[t + \frac{2t^2}{2} + \frac{t^3}{6} \right]_0^x = 1 + x + x^2 + \frac{x^3}{6}$$

$$= 1 + x + x^2 + \frac{x^3}{3!}$$

$$y_3(x) = y_0 + \int_0^x f(t, y_2(t)) dt$$

$$= 1 + \int_0^x \left(1 + 2t + t^2 + \frac{t^3}{6} \right) dt$$

$$= 1 + \left[t + t^2 + \frac{t^3}{3} + \frac{t^4}{24} \right]_0^x$$

$$= 1 + x + x^2 + \frac{x^3}{3} + \frac{x^4}{4!}$$

$$f(x, y) = x + y$$

$$f(t, y_2(t)) =$$

$$t + 1 + t + t^2 + \frac{t^3}{6}$$

$$= 1 + 2t + t^2 + \frac{t^3}{6}$$

$$f(x, y) = x + y$$

$$f(t, y_3(t)) =$$

$$t + 1 + t + t^2 + \frac{t^3}{3} + \frac{t^4}{24}$$

$$y_4(x) = y_0 + \int_0^x f(t, y_3(t)) dt$$

$$= 1 + \int_0^x \left[1 + 2t + t^2 + \frac{t^3}{3} + \frac{t^4}{24} \right] dt$$

$$= 1 + \left[t + t^2 + \frac{t^3}{3} + \frac{t^4}{12} + \frac{t^5}{120} \right]_0^x$$

$$y_4(x) = 1 + x + x^2 + \frac{x^3}{3} + \frac{x^4}{3 \cdot 4} + \frac{x^5}{5!}$$

⋮

$$y_n(x) = 1 + x + x^2 + \frac{x^3}{3} + \frac{x^4}{3 \cdot 4} + \dots + \frac{x^n}{3 \cdot 4 \cdot \dots \cdot n} + \frac{x^{n+1}}{(n+1)!}$$

$$= 1 + x + 2 \left\{ \frac{x^2}{2} + \frac{x^3}{2 \cdot 3} + \frac{x^4}{2 \cdot 3 \cdot 4} + \dots + \frac{x^n}{2 \cdot 3 \cdot \dots \cdot n} \right\} + \frac{x^{n+1}}{(n+1)!}$$

$$y_n(x) = 1 + x + 2 \left\{ \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots + \frac{x^n}{n!} \right\} + \frac{x^{n+1}}{(n+1)!}$$

looking for: $\lim_{n \rightarrow \infty} \{y_n(x)\} \rightarrow y(x)$ (if it exists)

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

$$\underline{e^x - 1 - x} = \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

$\therefore \lim_{n \rightarrow \infty} (y_n(x))$ converges to $1 + x + 2(e^x - 1 - x) + 0$

$$\lim_{n \rightarrow \infty} (y_n(x)) \rightarrow \underline{2e^x - x - 1} \rightarrow y(x)$$

i.e., $y(x) = 2e^x - x - 1$

check

$$y' = x + y, \quad y(0) = 1$$

$$\frac{dy}{dx} = x + y$$

$$\frac{dy}{dx} + p(x)y = q(x)$$

$$y \cdot e^{\int p dx} = \int q(x) e^{\int p dx} dx + c$$

$$\frac{dy}{dx} - y = x \rightarrow p(x) = -1, \quad q(x) = x$$

$$\int p(x) dx = \int -dx = -x \Rightarrow e^{-x}$$

$$y e^{-x} = \int x e^{-x} dx + c$$

$$= -x e^{-x} - \int -e^{-x} dx + c$$

$$u = x, \quad du = dx$$

$$\int dv = \int e^{-x} dx$$

$$v = -e^{-x}$$

$$y e^{-x} = -x e^{-x} - e^{-x} + c$$

$$y = -x - 1 + c e^x$$

$$y(x) = -x - 1 + c e^x$$

$$y(0) = 1$$

$$y(0) = -0 - 1 + c e^0$$

$$1 = -1 + c \Rightarrow c = 2$$

$$\therefore y = 2e^x - x - 1$$

Ex: Find the exact solution of the initial value problem $y' = y^2$, $y(0) = 1$. Starting with $y_0(x) = 1$ apply Picard's method to calculate $y_1(x)$, $y_2(x)$, $y_3(x)$ and compare these results with the exact solution.

Exact solⁿ: $\frac{dy}{dx} = y^2 \Rightarrow \int \frac{dy}{y^2} = \int dx \Rightarrow \frac{y^{-1}}{-1} = x + C$

$$\Rightarrow -\frac{1}{y} = x + C \Rightarrow y(x) = -\left(\frac{1}{x+C}\right)$$

$$y(0) = 1 \Rightarrow y(0) = -\left(\frac{1}{0+C}\right)$$

$$1 = -\frac{1}{C} \Rightarrow C = -1$$

$$y(x) = -\frac{1}{x-1} \Rightarrow y = \frac{1}{1-x}, \quad |x| < 1$$

$$y = 1 + x + x^2 + x^3 + \dots, \quad |x| < 1$$

$$y_1(x) = 1 + x$$

$$y_2(x) = 1 + x + x^2 + \frac{1}{3}x^3$$

$$y_3(x) = 1 + x + x^2 + x^3 + \frac{2}{3}x^4 + \frac{1}{3}x^5 + \frac{1}{9}x^6 + \frac{1}{63}x^7$$

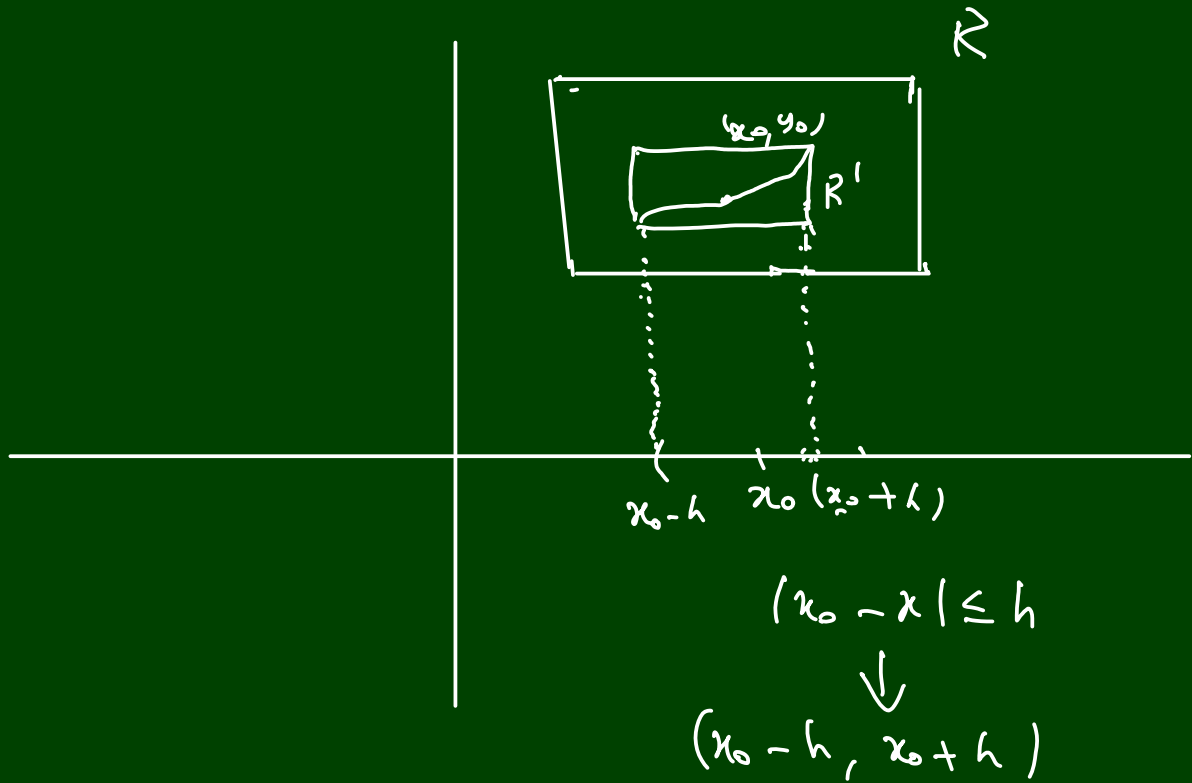
Picard's Theorem: Let $f(x, y)$ and $\frac{\partial f}{\partial y}$ be

continuous functions of x and y on a closed rectangle R with sides parallel to the axes. If (x_0, y_0) is any interior point of R , then there exists a number $h > 0$ with the property that the initial value problem $y' = f(x, y)$, $y(x_0) = y_0$ has one and only one solution $y = y(x)$ on the interval $|x - x_0| \leq h$.

$$\text{IVP} \begin{cases} y' = f(x, y) \\ y(x_0) = y_0 \end{cases}$$

existence and uniqueness of
the solution for this IVP

$f(x, y), \frac{\partial f}{\partial y} \rightarrow$ continuous f^{ns} of x & y
on R



Condition: $\frac{\partial f}{\partial y} \rightarrow$ cont^s (strong condition)

$f(x, y) \rightarrow$ cont^s, even though not necessary that
 $\frac{\partial f}{\partial y}$ has to exist.

✓ C.W.
29/12/2023

Recall

Picard's theorem

$$\textcircled{1} \begin{cases} y' = f(x, y) \\ y(x_0) = y_0 \end{cases}$$

When will a unique solution exist? (where?)

Assumptions: $f(x, y)$, $\frac{\partial f}{\partial y}$ continuous functions of x & y on R .

$(x_0, y_0) \rightarrow$ interior point of R .

$\exists h > 0 \Rightarrow \textcircled{1}$ has one and only one solution

$y = y(x)$ on the interval $|x - x_0| \leq h$.

$(x_0 - h, x_0 + h)$

$f(x, y)$ is continuous in $R \rightarrow f(x, y)$ is bdd on R

$$\therefore |f(x, y)| \leq M$$

$\frac{\partial f}{\partial y}$ is continuous in $R \rightarrow \frac{\partial f}{\partial y}$ is bdd on R

$$\therefore \left| \frac{\partial f}{\partial y} \right| \leq k$$

Recall! Mean value theorem $\rightarrow f(x)$

f is cont^d on $[a, b]$

f is diff^l on (a, b)

$$\text{then } \exists c \in (a, b) \Rightarrow \frac{f(b) - f(a)}{b - a} = f'(c)$$

Use MVT for $f(x, y)$

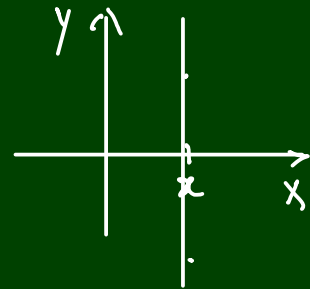
$$f(b) - f(a) = f'(c)(b - a)$$

$$(x, y_1), (x, y_2) \in \mathbb{R}$$

$$|f(x, y_1) - f(x, y_2)| = \left| \frac{\partial}{\partial y} f(x, y^*) \right| |y_1 - y_2|,$$

$$y_1 < y^* < y_2$$

i.e., $|f(x, y_1) - f(x, y_2)| \leq K |y_1 - y_2|$



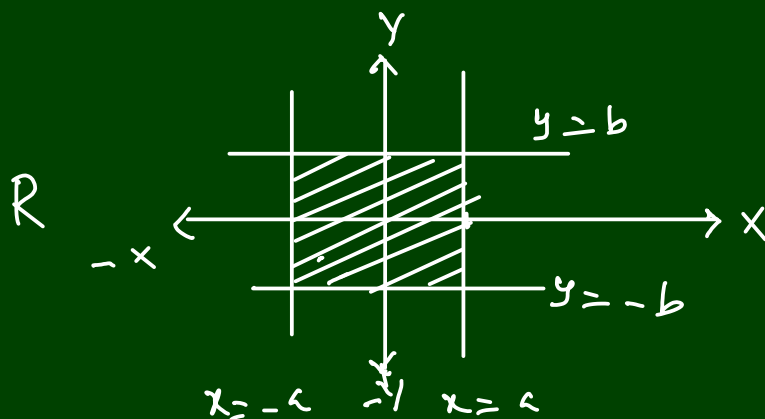
∴ Lipchitz condition

∴ $f(x, y) \rightarrow$ Lipchitz function.

$$\frac{|f(x, y_1) - f(x, y_2)|}{|y_1 - y_2|} \leq \textcircled{K} \rightarrow \text{finite constant}$$

∴ (Lipchitz constant)

Example (i) If R is a rectangle defined by $|x| \leq a$, $|y| \leq b$, show that $f(x, y) = x^2 + y^2$ satisfies the Lipchitz condition. Find the Lipchitz constant.



$$\forall (x, y_1), (x, y_2) \in \mathbb{R}, \quad f(x, y) = x^2 + y^2$$

$$\Rightarrow f(x, y_1) - f(x, y_2) = (x^2 + y_1^2) - (x^2 + y_2^2) \\ = y_1^2 - y_2^2$$

$$|f(x, y_1) - f(x, y_2)| = |y_1^2 - y_2^2| \\ = |y_1 + y_2| |y_1 - y_2| \\ \leq (|y_1| + |y_2|) |y_1 - y_2|$$

$$|ab| = |a||b|$$

$$y_1^2 - y_2^2 = (y_1 - y_2)(y_1 + y_2)$$

$$|a+b| \leq |a| + |b|$$

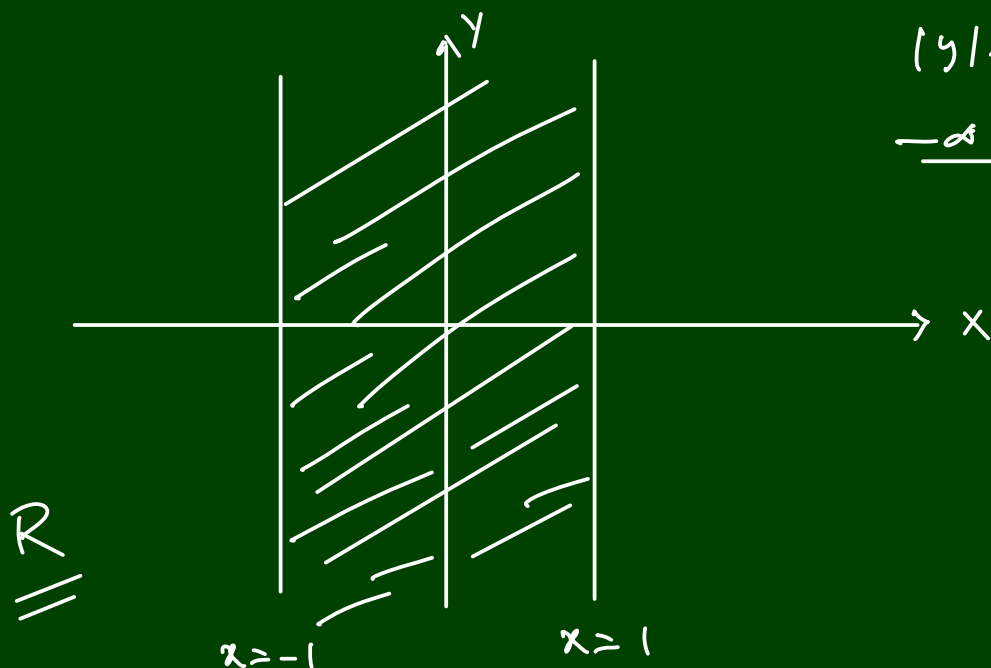
$$|f(x, y_1) - f(x, y_2)| \leq 2b |y_1 - y_2| \quad (\because |y| < b \text{ in } \mathbb{R})$$

$\therefore f(x, y) = x^2 + y^2$ satisfies the Lipschitz condition

Lipschitz constant is 2b

(ii) $f(x, y) = xy^2, \quad \mathbb{R} : |x| \leq 1, |y| < \infty$

Test whether f is Lipschitz or not.



$$|y| < \infty$$

$$-\infty < y < \infty$$

Choose $(x, 0)$ and $(x, y_2) \in \mathbb{R}$ | $f(x, y) = xy^2$

Then

$$|f(x, 0) - f(x, y_2)| = |0 - xy_2^2| = |x||y_2^2|$$

$$|0 - y_2| = |y_2|$$

$$\frac{|f(x, 0) - f(x, y_2)|}{|0 - y_2|} = \frac{|x||y_2^2|}{|y_2|}$$

$$\leq |y_2|$$

$$\rightarrow \infty \text{ as } |y_2| \rightarrow \infty$$

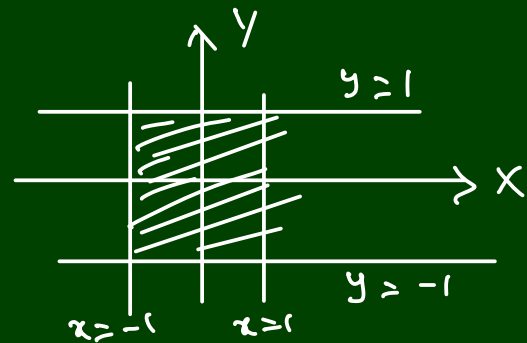
$\therefore f(x, y) = xy^2$ on \mathbb{R} is not Lipschitz

* Note $f(x, y)$ is continuous $\nRightarrow f(x, y)$ is Lipschitz

Example: $f(x, y) = y^{2/3}$, $R: (x| \leq 1, |y| \leq 1)$

$$\left| \frac{\partial f}{\partial y} \right| \leq k$$

Here $\frac{\partial f}{\partial y} = \frac{2}{3} y^{-1/3}$



Here $f(x, y) = y^{2/3}$ is continuous on R .

$$\text{But } \left| \frac{\partial f(x, y)}{\partial y} \right| = \left| \frac{2}{3y^{1/3}} \right| \rightarrow \infty \text{ as } y \rightarrow 0$$

Since $y = 0$ is a point in R , the Lipschitz constant is infinite. $\therefore f(x, y) = y^{2/3}$ is not a Lipschitz function in R .

Note Give an example to show that the existence of partial derivative of $f(x, y)$ is not necessary for $f(x, y)$ to be a Lipschitz function

Let $f(x, y) = |y|$. Let $R = \{(x, y) \mid |x| \leq 1, |y| \leq 1\}$

Claim (i) $f(x, y)$ is Lipschitz in R

$\forall (x, y_1), (x, y_2)$ in R , we have

$$\frac{|f(x, y_1) - f(x, y_2)|}{|y_1 - y_2|} = \frac{||y_1| - |y_2||}{|y_1 - y_2|}$$

$$\boxed{\begin{aligned} ||a| - |b|| \\ \leq |a - b| \end{aligned}}$$

$$\leq \frac{|y_1 - y_2|}{|y_1 - y_2|}$$

$$\leq 1$$

$\Rightarrow f(x, y) = |y|$ is a Lipschitz function in R .

Claim (ii) $\left(\frac{\partial f}{\partial y}\right)$ does not exist in R

Recall partial derivative of $f(x, y)$ w.r.t y at (x', y') is defined by

$$\left(\frac{\partial f}{\partial y}\right)_{(x', y')} = \lim_{k \rightarrow 0} \frac{f(x', y' + k) - f(x', y')}{k}$$

$$\boxed{\begin{aligned} f(x, y) \\ = |y| \end{aligned}}$$

Use this defⁿ: $\left(\frac{\partial f}{\partial y}\right)_{(x, 0)} = \lim_{k \rightarrow 0} \frac{f(x, 0+k) - f(x, 0)}{k}$

$$= \lim_{k \rightarrow 0} \frac{|k|}{k} \quad \text{which does not exist}$$

Thus $\frac{\partial f}{\partial y}$ does not exist at $(x, 0)$

$(x, 0) \in \mathbb{R}$

A.T. 3/11/2022

Recall Picard's theorem

Existence and uniqueness of the solution

$$\text{for the IVP } y' = f(x, y)$$

$$y(x_0) = y_0$$

$f(x, y) \rightarrow$ continuous
 $\frac{\partial f}{\partial y} \rightarrow$ continuous

Lipschitz condition:

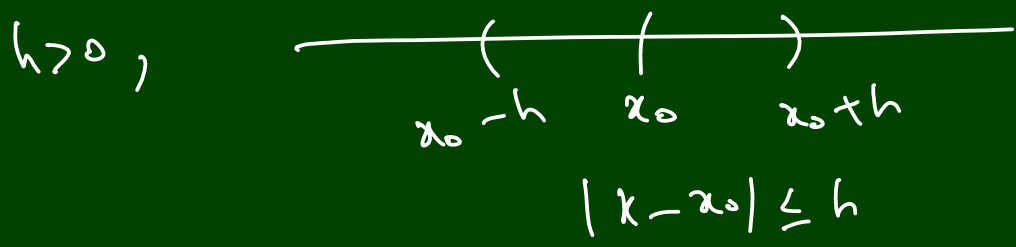
$$\left. \begin{array}{l}
 R \\
 \left(\frac{\partial f}{\partial y} \right) \leq k \checkmark \\
 y = y(x), \quad |x - x_0| \leq h \checkmark
 \end{array} \right\}
 \begin{array}{l}
 |f(x, y)| \leq M \\
 \checkmark
 \end{array}$$

$$\boxed{|f(x, y_1) - f(x, y_2)| \leq k |y_1 - y_2| \checkmark}$$

$(x, y_1) \text{ \& } (x, y_2) \in R$

$$\frac{|f(x, y_1) - f(x, y_2)|}{|y_1 - y_2|} \leq k \checkmark$$

$\checkmark f(x, y)$ is a Lipschitz function
 k is called Lipschitz constant



$R \rightarrow$ important

Ex: $f(x, y) = x \sin y + y \cos x$ | Show that f is Lipschitz

$R : \{ (x, y) / |x| \leq a, |y| \leq b \}$ | is Lipschitz

pf: $x, \sin y, \cos x$ are cont^d $\rightarrow f(x, y)$ cont^d
 $\frac{\partial f}{\partial y}$ is also cont^d

on \mathbb{R}

$$|\cos x| \leq 1$$

$$|\cos y| \leq 1$$

$$\frac{\partial f}{\partial y} = x \cos y + \cos x$$

$$\left| \frac{\partial f}{\partial y} \right| = |x \cos y + \cos x|$$

$$\leq |x| |\cos y| + |\cos x|$$

$$\leq |x| + 1$$

$$\leq \underline{\underline{a+1}}$$

$\therefore f$ is Lipschitz, the Lipschitz const^t is $a+1$

f cont^d \nRightarrow f is Lipschitz

Note: We can't drop the Lipschitz condition in the statement of Picard's theorem.

proof (by an example)

consider $y' = 3y^{2/3}$, $y(0) = 0$.

Let $R := \{(x, y) \mid |x| \leq 1, |y| \leq 1\}$

clearly $f(x, y) = 3y^{2/3}$, which is cont^d on R .

$$y' = 3y^{2/3} \Rightarrow \frac{dy}{y^{2/3}} = 3 dx$$

$$\Rightarrow \int y^{-2/3} dy = 3 \int dx$$

$$\Rightarrow \frac{y^{1/3}}{1/3} = 3x + 3C \quad | \quad 3y^{1/3} = 3x + 3C$$

$$y^{1/3} = x + C$$

$$y(0) = 0 \Rightarrow 0 = 0 + C \Rightarrow \underline{\underline{C=0}}$$

\therefore one solution is $y^{1/3} = x$

$$\text{i.e., } \boxed{y = x^3}$$

PMSA

$$y_0(x) = 0$$

$$y_1(x) = y_0 + \int_0^x f(t, y_0(t)) dt$$

$$f(x, y) = 3y^{2/3}$$

$$|f(t, y_0(t))| = 0$$

$$y_1(x) = 0$$

$$y_2(x) = y_0 + \int_0^x f(t, y_1(t)) dt$$

$$|f(t, y_1(t))| = 0$$

$$\vdots = 0$$

$$y_n(x) = 0$$

$$\lim_{n \rightarrow \infty} \{y_n(x)\} \rightarrow 0$$

Another solution is $\boxed{y = 0}$

\therefore The given problem has two solutions.

Because $f(x, y)$ is not Lipschitz on \mathbb{R} .

for, $(x, y_1), (x, 0) \in \mathbb{R}$

$$\frac{|f(x, y_1) - f(x, 0)|}{|y_1 - 0|} = \frac{|3y_1^{2/3}|}{|y_1|} = \frac{3}{|y_1|^{1/3}}$$

which is unbounded when $y_1 \rightarrow 0$. (every n th Nbd of 0 in \mathbb{R})

Systems of first order equations

$$\textcircled{1} \begin{cases} y_1' = f_1(x, y_1, y_2, \dots, y_n) \\ y_2' = f_2(x, y_1, y_2, \dots, y_n) \\ \vdots \\ y_n' = f_n(x, y_1, y_2, \dots, y_n) \end{cases}$$

$y_1(x), y_2(x), \dots, y_n(x)$
are unknown functions
of a single independent
variable x .

Solve $\left. \begin{matrix} y' = f(x, y) \\ y(x_0) = y_0 \end{matrix} \right\} \rightarrow$ Find $\underbrace{y(x)}_{\text{unknown function}} \in C^1 \ni$
 $\frac{d}{dx}(y(x)) = f(x, y)$
 and $y(x_0) = y_0$

Consider $y^{(n)} = f(x, y, y', \dots, y^{(n-1)})$ — $\textcircled{2}$

$\textcircled{2}$ can always be regarded as a special case of $\textcircled{1}$. \textcircled{X}

We put

$$\textcircled{3} \quad y_1 = y, \quad y_2 = y', \quad y_3 = y'', \quad y_4 = y''', \quad \dots, \quad y_n = y^{(n-1)}$$

Then $\textcircled{2}$ is equivalent to the system

$$\textcircled{4} \begin{cases} y_1' = y_2 \\ y_2' = y_3 \\ \dots \\ y_n' = f(x, y_1, y_2, \dots, y_n) \end{cases}$$

Ex: (i) consider $y'' - x^2 y' - xy = 0$

system $\left\{ \begin{array}{l} y' = z \\ z' = x^2 z + xy \end{array} \right.$

Hint
 $y' = z \rightarrow y'' = z'$
 $(z' - x^2 z - xy = 0$
 $z' = x^2 z + xy)$

(ii) consider $y''' = y'' - x^2 y'^2$

system $\left\{ \begin{array}{l} y' = z \\ z' = \omega \\ \omega' = \omega - x^2 z^2 \end{array} \right.$

Hint
 $y' = z$
 $z' = \omega \text{ (}\& y'')$
 $\rightarrow \omega' = z'' = y'''$

✓ (CWS)
04/01/2021

Linear Systems

$$\begin{cases} \frac{dx}{dt} = f(t, x, y) \\ \frac{dy}{dt} = g(t, x, y) \end{cases}$$

dep. variables $\rightarrow x, y$
(Unknowns $\rightarrow x(t), y(t)$)

Ind. variable $\rightarrow t$

find $x(t)$ & $y(t)$

$$\textcircled{1} \begin{cases} \frac{dx}{dt} = a_1(t)x + b_1(t)y + f_1(t) \\ \frac{dy}{dt} = a_2(t)x + b_2(t)y + f_2(t) \end{cases}$$

$a_1(t), a_2(t), b_1(t), b_2(t), f_1(t), f_2(t)$ are continuous functions on $[a, b]$ of t -axis.

If $f_1(t)$ and $f_2(t)$ are zero then $\textcircled{2}$ is called homogeneous; otherwise $\textcircled{2}$ is non homogeneous.

A solution of $\textcircled{1}$ on $[a, b]$ is a pair of functions $x(t)$ and $y(t)$ that satisfy both equations of $\textcircled{2}$ throughout $[a, b]$.

Result If t_0 is any point of $[a, b]$ and if x_0 and y_0 are any numbers whatever, then $\textcircled{1}$ has one and only one solution

$$\begin{cases} x = x(t) \\ y = y(t) \end{cases} \text{ valid throughout } [a, b]$$

such that $x(t_0) = x_0$ and $y(t_0) = y_0$.

Consider the homogeneous system obtained from

$$\begin{cases} \textcircled{1} : \\ \textcircled{2} \end{cases} \left\{ \begin{array}{l} \frac{dx}{dt} = a_1(t)x + b_1(t)y \\ \frac{dy}{dt} = a_2(t)x + b_2(t)y \end{array} \right. \quad \left\{ \begin{array}{l} x(t) \equiv 0 \\ y(t) \equiv 0 \\ \text{trivial sol}^n \end{array} \right.$$

Theorem: If the homogeneous system $\textcircled{2}$ has

two solutions $\begin{cases} x = x_1(t) \\ y = y_1(t) \end{cases}$ and $\begin{cases} x = x_2(t) \\ y = y_2(t) \end{cases}$

on $[a, b]$ then

$$\begin{cases} x = c_1 x_1(t) + c_2 x_2(t) \\ y = c_1 y_1(t) + c_2 y_2(t) \end{cases} \quad \text{is also}$$

a solution on $[a, b]$ for any constants c_1 and c_2 .

proof: HW

Hint $y'' + p(x)y' + q(x)y = 0$
 $y_1, y_2 \rightarrow \text{sol}^n$
 $c_1 y_1 + c_2 y_2 \rightarrow \text{sol}^n$

To have the general solⁿ

$$x(t_0) = x_0, \quad y(t_0) = y_0, \quad \text{if } t_0 \in [a, b]$$

$$c_1 x_1(t_0) + c_2 x_2(t_0) = x_0$$

$$c_1 y_1(t_0) + c_2 y_2(t_0) = y_0$$

$$\text{i.e.,} \quad \begin{cases} c_1 x_1(t_0) + c_2 x_2(t_0) = x_0 \\ c_1 y_1(t_0) + c_2 y_2(t_0) = y_0 \end{cases}$$

c_1, c_2 unique: $\begin{vmatrix} x_1(t_0) & x_2(t_0) \\ y_1(t_0) & y_2(t_0) \end{vmatrix} \neq 0$ $W(t) = \begin{vmatrix} x_1(t) & y_1(t) \\ x_2(t) & y_2(t) \end{vmatrix} \neq 0$

Theorem: If $w(t)$ is the Wronskian of the two solutions $\begin{cases} x = x_1(t) \\ y = y_1(t) \end{cases}$ and $\begin{cases} x = x_2(t) \\ y = y_2(t) \end{cases}$ of the homogeneous system (2), then $w(t)$ is either identically zero or nowhere zero on $[a, b]$

pf: HW

Hint

$$\int [a_1(t) + b_2(t)] dt$$

$$w(t) = c e$$

$$\frac{dw}{dt} = [a_1(t) + b_2(t)] w$$

Remark: Higher order equations are equivalent to systems. (but not the reverse)

~~SCALAR~~ SYSTEMS ARE MORE GENERAL

Homogeneous Linear Systems with constant coeffs

$$\textcircled{1} \begin{cases} \frac{dx}{dt} = a_1 x + b_1 y \\ \frac{dy}{dt} = a_2 x + b_2 y \end{cases}, \quad a_1, a_2, b_1, b_2 \text{ are given constants.}$$

Let $\begin{cases} x = A e^{mt} \\ y = B e^{mt} \end{cases}$ be the solutions of (1)

Then $\frac{dx}{dt} = mAe^{mt}$
 $\frac{dy}{dt} = mBe^{mt}$

\therefore (1) becomes $mAe^{mt} = a_1 Ae^{mt} + b_1 Be^{mt}$
 $mBe^{mt} = a_2 Ae^{mt} + b_2 Be^{mt}$

$\Rightarrow (m - a_1)Ae^{mt} - b_1 Be^{mt} = 0$
 $-a_2 Ae^{mt} + (m - b_2)Be^{mt} = 0$

\Rightarrow $\begin{cases} (m - a_1)A - b_1 B = 0 \\ -a_2 A + (m - b_2)B = 0 \end{cases}$ $A, B e^{mt} \neq 0$

which is a linear algebraic system in the unknowns A and B.

This system has non trivial solution for A and B if $\begin{vmatrix} m - a_1 & -b_1 \\ -a_2 & m - b_2 \end{vmatrix} = 0$

$\Rightarrow (m - a_1)(m - b_2) - a_2 b_1 = 0$

$\Rightarrow \boxed{m^2 - \underbrace{(a_1 + b_2)}_{\text{trace } A} m + \underbrace{a_1 b_2 - a_2 b_1}_{\text{det } A} = 0}$ \rightarrow auxiliary equation.

$\begin{cases} \frac{dx}{dt} = a_1 x + b_1 y \\ \frac{dy}{dt} = a_2 x + b_2 y \end{cases} \Rightarrow \dot{X} = AX,$
 where, $X = \begin{pmatrix} x \\ y \end{pmatrix}, A = \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}$

Let m_1 and m_2 be the roots of (1) a.e

If we replace m by m_1 in (*), we get nontrivial solutions for A and B (say A_1 & B_1)

So $\begin{cases} x = A_1 e^{m_1 t} \\ y = B_1 e^{m_1 t} \end{cases}$ is a nontrivial solⁿ of (1)

Similarly if we replace m by m_2 in (*), we get nontrivial solⁿ for A and B (say A_2 & B_2)

So $\begin{cases} x = A_2 e^{m_2 t} \\ y = B_2 e^{m_2 t} \end{cases}$ is another nontrivial solⁿ of (1)

— o —

~~Exam~~
 05/01/2021
 Linear homogeneous system
 with constant coefficients

Recall

$$\begin{cases} \frac{dx}{dt} = a_1x + b_1y \\ \frac{dy}{dt} = a_2x + b_2y \end{cases}, \quad t \in [a, b]$$

a_1, b_1, a_2, b_2 are known real constants

Let $\begin{cases} x = A e^{mt} \\ y = B e^{mt} \end{cases}$ be the solution of ①

Then $\frac{A \cdot x}{m^2 - (a_1 + b_2)m + a_1 b_2 - a_2 b_1} = 0$ if:

$$m = m_1, m = m_2$$

$$(*) \begin{cases} (m - a_1)A - b_1 B = 0 \\ -a_2 A + (m - b_2)B = 0 \end{cases} \quad 'x'$$

$m = m_1 \rightarrow A_1 \& B_1$

$$\begin{cases} x_1 = A_1 e^{m_1 t} \\ y_1 = B_1 e^{m_1 t} \end{cases}$$

$m = m_2 \rightarrow A_2 \& B_2$

$$\begin{cases} x_2 = A_2 e^{m_2 t} \\ y_2 = B_2 e^{m_2 t} \end{cases}$$

General solⁿ of ①

$$\begin{cases} x = c_1 x_1 + c_2 x_2 \\ y = c_1 y_1 + c_2 y_2 \end{cases}$$

① can be written in the matrix form as:

$$\dot{x} = Ax$$

$$x = \begin{pmatrix} x \\ y \end{pmatrix}, \quad \dot{x} = \begin{pmatrix} dx/dt \\ dy/dt \end{pmatrix}$$

$$A = \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}$$

Trace of A

$$m^2 - (a_1 + b_2)m + a_1 b_2 - a_2 b_1 = 0$$

\downarrow
 $\det A$

$$W(t) = \begin{vmatrix} x_1(t) & x_2(t) \\ y_1(t) & y_2(t) \end{vmatrix} \neq 0$$

Case (i) The a.e has distinct real roots
(Say m_1 and m_2 are real, $m_1 \neq m_2$)

Example Solve:
$$\begin{cases} \frac{dx}{dt} = x + y \\ \frac{dy}{dt} = 4x - 2y \end{cases}$$

Solution: The given system is of the form

$$\begin{cases} \frac{dx}{dt} = a_1x + b_1y \\ \frac{dy}{dt} = a_2x + b_2y \end{cases}, \text{ where } \begin{matrix} a_1 = 1, b_1 = 1 \\ a_2 = 4, b_2 = -2 \end{matrix}$$

Let $\begin{cases} x = Ae^{mt} \\ y = Be^{mt} \end{cases}$ be a solⁿ of the given system.

Then we have, $m^2 - (a_1 + b_2)m + a_1b_2 - a_2b_1 = 0$

and (*) $\begin{cases} (m - a_1)A - b_1B = 0 \\ -a_2A + (m - b_2)B = 0 \end{cases}$

Now the a.e becomes

$$m^2 - (1 - 2)m + (-2) - (4) = 0$$

$$\text{i.e., } m^2 + m - 6 = 0 \Rightarrow (m + 3)(m - 2) = 0$$

$$\Rightarrow m_1 = -3, m_2 = 2$$

✓ When we replace m with $m_1 = -3$ in (*), we have

$$\begin{cases} (-3 - 1)A - B = 0 \\ -4A + (-3 + 2)B = 0 \end{cases} \Rightarrow \begin{cases} -4A - B = 0 \\ -4A - B = 0 \end{cases}$$

both the equations reduces to a single eqⁿ

as $-4A - B = 0$ i.e., $4A + B = 0$

A simple nontrivial solution of this system is

$$\underline{A = 1, B = -4}$$

$$\sqrt{\begin{matrix} B = 1 \\ A = -\frac{1}{4} \end{matrix}}$$

\therefore The first set of solution is

$$\begin{cases} x_1 = e^{-3t} \\ y_1 = -4e^{-3t} \end{cases}$$

$$\begin{aligned} x &= A e^{mt} \\ y &= B e^{mt} \\ m &= m_1 = -3 \\ A &= 1, B = -4 \end{aligned}$$

Again if we replace m with $m_2 = 2$ in (*) , we have

$$\begin{cases} (2-1)A - B = 0 \\ -4A + (2+2)B = 0 \end{cases} \Rightarrow \begin{cases} A - B = 0 \\ -4A + 4B = 0 \end{cases}$$

This algebraic system reduces to a

single equation as: $A - B = 0$

i.e. $A = B$

\therefore a simple nontrivial solution is $A = 1, B = 1$

\therefore The second set of solution is

$$\begin{cases} x_2 = e^{2t} \\ y_2 = e^{2t} \end{cases}$$

\therefore The general solⁿ of the given system of equations is

$$\begin{cases} x = c_1 e^{-3t} + c_2 e^{2t} \\ y = -4c_1 e^{-3t} + c_2 e^{2t} \end{cases}$$

$$\begin{aligned} W(t) &= \begin{vmatrix} x_1(t) & x_2(t) \\ y_1(t) & y_2(t) \end{vmatrix} \\ &= \begin{vmatrix} e^{-3t} & e^{2t} \\ -4e^{-3t} & e^{2t} \end{vmatrix} \\ &= e^{-t} + 4e^{-t} \\ &= 5e^{-t} \neq 0. \end{aligned}$$

Case (ii) The a.e has distinct complex roots

Let m_1 and m_2 be distinct complex numbers.

Say $m_1 = a + ib$, $m_2 = a - ib$ (a, b real numbers) and $b \neq 0$

In this case we expect the values of A and B obtained from (*) to be complex numbers.

The two linearly independent solutions will be of the form

$$\left\{ \begin{array}{l} x_1 = A_1^* e^{(a+ib)t} \\ y_1 = B_1^* e^{(a+ib)t} \end{array} \right\}, \left\{ \begin{array}{l} x_2 = A_2^* e^{(a-ib)t} \\ y_2 = B_2^* e^{(a-ib)t} \end{array} \right\}$$

where $A_1^* = A_1 + iA_2$, $B_1^* = B_1 + iB_2$ etc.

Consider the first set of solution:

$$\left\{ \begin{array}{l} x = (A_1 + iA_2) e^{at} e^{ibt} \\ y = (B_1 + iB_2) e^{at} e^{ibt} \end{array} \right.$$

$$i.e., \left\{ \begin{array}{l} x = (A_1 + iA_2) e^{at} \left\{ \cos bt + i \sin bt \right\} \\ y = (B_1 + iB_2) e^{at} \left\{ \cos bt + i \sin bt \right\} \end{array} \right\} \quad (\text{Euler's formula})$$

$$\left\{ \begin{array}{l} x = e^{at} \left\{ \underbrace{(A_1 \cos bt - A_2 \sin bt)}_{\text{real part}} + i \underbrace{(A_1 \sin bt + A_2 \cos bt)}_{\text{imaginary part}} \right\} \\ y = e^{at} \left\{ \underbrace{(B_1 \cos bt - B_2 \sin bt)}_{\text{real part}} + i \underbrace{(B_1 \sin bt + B_2 \cos bt)}_{\text{imaginary part}} \right\} \end{array} \right\}$$

We have two real parts and two imaginary parts but which are real valued functions.

Hence the two real valued solutions are

$$\begin{cases} x_1 = e^{at} (A_1 \cos bt - A_2 \sin bt) \\ y_1 = e^{at} (B_1 \cos bt - B_2 \sin bt) \end{cases}$$

and $\begin{cases} x_2 = e^{at} (A_1 \sin bt + A_2 \cos bt) \\ y_2 = e^{at} (B_1 \sin bt + B_2 \cos bt) \end{cases}$

$$\begin{cases} x = c_1 x_1 + c_2 x_2 \\ y = c_1 y_1 + c_2 y_2 \end{cases} \text{ is the general solution.}$$

Example: solve: $\begin{cases} \frac{dx}{dt} = 4x - 2y \\ \frac{dy}{dt} = 5x + 2y \end{cases}$

The given system is of the form $\begin{cases} \frac{dx}{dt} = a_1 x + b_1 y \\ \frac{dy}{dt} = a_2 x + b_2 y \end{cases}$

where $a_1 = 4, b_1 = -2$
 $a_2 = 5, b_2 = 2$

Let $\begin{cases} x = A e^{mt} \\ y = B e^{mt} \end{cases}$ be a solution of the given system.

Then we have $m^2 - (a_1 + b_2)m + a_1 b_2 - a_2 b_1 = 0$ and

$$(*) \begin{cases} (m - a_1)A - b_1 B = 0 \\ -a_2 A + (m - b_2)B = 0 \end{cases}$$

The a.e is $m^2 - (4+2)m + 8 + 10 = 0$

i.e, $m^2 - 6m + 18 = 0$

$$m = \frac{6 \pm \sqrt{36 - 72}}{2} \Rightarrow m = \frac{6 \pm \sqrt{-36}}{2}$$

$$m = \frac{6 \pm 6i}{2} \Rightarrow \underline{\underline{m = 3 \pm i3}}$$

$$m_1 = 3 + i3, m_2 = 3 - i3$$

If we replace m with $m_1 = 3 + i3$ in (*), we have

$$\begin{cases} (2 + i3 - 4)A + 2B = 0 \\ -5A + (2 + i3 - 2)B = 0 \end{cases}$$

$$\Rightarrow \begin{cases} (-1 + i3)A + 2B = 0 \\ -5A + (1 + i3)B = 0 \end{cases}$$

Consider

$$-5A + (1 + i3)B = 0$$

Take $A = 1$

$$B = \frac{5}{1 + i3}$$

$$B = \frac{5(1 - i3)}{(1 + i3)(1 - i3)} = \frac{5 - i15}{10}$$

$$\underline{\underline{B = \frac{1}{2} - \frac{i3}{2}}}$$

$$\therefore \begin{cases} x = e^{(3 + i3)t} \\ y = \left(\frac{1}{2} - i\frac{3}{2}\right) e^{(3 + i3)t} \end{cases}$$

$$\begin{cases} x = e^{3t} \cdot e^{i3t} \\ y = \left(\frac{1}{2} - i\frac{3}{2}\right) e^{3t} \cdot e^{i3t} \end{cases}$$

$$\begin{cases} x = e^{3t} \{ \cos 3t + i \sin 3t \} \\ y = \left(\frac{1}{2} - i \frac{3}{2} \right) e^{3t} \{ \cos 3t + i \sin 3t \} \end{cases}$$

$$\begin{cases} x = e^{3t} \{ \cos 3t + i \sin 3t \} \\ y = e^{3t} \left\{ \left(\frac{1}{2} \cos 3t + \frac{3}{2} \sin 3t \right) + i \left(\frac{1}{2} \sin 3t - \frac{3}{2} \cos 3t \right) \right\} \end{cases}$$

\therefore The two set of solutions are

$$\begin{cases} x_1 = e^{3t} \cos 3t \\ y_1 = e^{3t} \left(\frac{1}{2} \cos 3t + \frac{3}{2} \sin 3t \right) \end{cases}$$

and $\begin{cases} x_2 = e^{3t} \sin 3t \\ y_2 = e^{3t} \left(\frac{1}{2} \sin 3t - \frac{3}{2} \cos 3t \right) \end{cases}$

\therefore The general solution is

$$\begin{cases} x = c_1 e^{3t} \cos 3t + c_2 e^{3t} \sin 3t \\ y = c_1 e^{3t} \left(\frac{1}{2} \cos 3t + \frac{3}{2} \sin 3t \right) + c_2 e^{3t} \left(\frac{1}{2} \sin 3t - \frac{3}{2} \cos 3t \right) \end{cases}$$

HW

(i) solve:

$$\begin{cases} \frac{dx}{dt} = -3x + 4y \\ \frac{dy}{dt} = -2x + 3y \end{cases}$$

(ii) solve:

$$\begin{cases} \frac{dx}{dt} = x - 2y \\ \frac{dy}{dt} = 4x + 5y \end{cases}$$

A. T. C. M. L
06/01/2021

HW (i) $\begin{cases} \frac{dx}{dt} = -3x + 4y \\ \frac{dy}{dt} = -2x + 3y \end{cases}$

Recall

Ans: $\begin{cases} x = 2c_1 e^{-t} + c_2 e^t \\ y = c_1 e^{-t} + c_2 e^t \end{cases}$

(ii) $\begin{cases} \frac{dx}{dt} = x - 2y \\ \frac{dy}{dt} = 4x + 5y \end{cases}$

Ans: $\begin{cases} x = e^{3t} [c_1 \cos 2t + c_2 \sin 2t] \\ y = e^{3t} [c_1 (\sin 2t - \cos 2t) - c_2 (\sin 2t + \cos 2t)] \end{cases}$

CASE (ii) Equal real roots ($m_1 = m_2 = m$, say)

Here $\begin{cases} x = A_1 e^{m_1 t} \\ y = B_1 e^{m_1 t} \end{cases}$ and $\begin{cases} x = A_2 e^{m_2 t} \\ y = B_2 e^{m_2 t} \end{cases}$

are not linearly independent (x)

As $m_1 = m_2 = m$, we have only one

solution $\begin{cases} x = A e^{mt} \\ y = B e^{mt} \end{cases}$

$y'' - 4y' + 4y = 0$
 $\therefore m^2 - 4m + 4 = 0$
 $(m-2)^2 = 0$
 $m = 2$ twice
 $2x$
 $y_1 = e^{2x}$
 $y_2 = x e^{2x}$
 $w(y_1, y_2) \neq 0$
 $y = (c_1 + c_2 x) e^{2x}$

To have another linearly independent solution we can expect it of the form

will not work (notable difference) $\begin{cases} x = A t e^{mt} \\ y = B t e^{mt} \end{cases}$

But unfortunately this is not quite simple.

We look for a second solution of the form

$$\checkmark \dot{X} = \begin{cases} x = (A_1 + A_2 t) e^{mt} \\ y = (B_1 + B_2 t) e^{mt} \end{cases} \quad \text{--- (a)}$$

\therefore The general solution is

$$\begin{cases} x = c_1 A e^{mt} + c_2 (A_1 + A_2 t) e^{mt} \\ y = c_1 B e^{mt} + c_2 (B_1 + B_2 t) e^{mt} \end{cases} \quad // \dot{X}$$

The constants A_1, A_2, B_1, B_2 are found by substituting (a) into the system

Example solve $\begin{cases} \frac{dx}{dt} = 3x - 4y \\ \frac{dy}{dt} = x - y \end{cases}$

The given system is of the form

$$\begin{cases} \frac{dx}{dt} = a_1 x + b_1 y \\ \frac{dy}{dt} = a_2 x + b_2 y \end{cases}, \text{ where } \begin{matrix} a_1 = 3, & b_1 = -4 \\ a_2 = 1, & b_2 = -1 \end{matrix}$$

Let $\begin{cases} x = A e^{mt} \\ y = B e^{mt} \end{cases}$ be a solution of the given system.

Then $m^2 - (a_1 + b_2)m + a_1 b_2 - a_2 b_1 = 0$ and

$$(*) \begin{cases} (m - a_1) A - b_1 B = 0 \\ -a_2 A + (m - b_2) B = 0 \end{cases}$$

a.e is $m^2 - (3 - 1)m + (-3) - (-4) = 0 \Rightarrow m^2 - 2m + 1 = 0$
 $\Rightarrow m = 1$ twice

Replace $m=1$ in (4), $\begin{cases} -2A+4B=0 \\ -A+2B=0 \end{cases}$

Both the equations reduce to $-A+2B=0$

The simple nontrivial solution is $B=1, A=2$

\therefore The one solⁿ is $\begin{cases} x = 2e^t \\ y = e^t \end{cases}$

Choose the second solution as

$$\begin{cases} x = (A_1 + A_2 t) e^t \\ y = (B_1 + B_2 t) e^t \end{cases} \quad (m=1)$$

Then, $\begin{cases} \frac{dx}{dt} = (A_1 + A_2 t) e^t + A_2 e^t \\ \frac{dy}{dt} = (B_1 + B_2 t) e^t + B_2 e^t \end{cases}$

Substituting the above into the given system we have

$$\begin{aligned} (A_1 + A_2 t) e^t + A_2 e^t &= 3(A_1 + A_2 t) e^t - 4(B_1 + B_2 t) e^t \\ (B_1 + B_2 t) e^t + B_2 e^t &= (A_1 + A_2 t) e^t - (B_1 + B_2 t) e^t \end{aligned}$$

$$\Rightarrow \begin{cases} (A_2 - 3A_2 + 4B_2) t + (A_1 + A_2 - 3A_1 + 4B_1) = 0 \\ (B_2 - A_2 + B_2) t + (B_1 + B_2 - A_1 + B_1) = 0 \end{cases}$$

$$\therefore, \begin{cases} (-2A_2 + 4B_2) t + (-2A_1 + A_2 + 4B_1) = 0 \\ (2B_2 - A_2) t + (2B_1 + B_2 - A_1) = 0 \end{cases}$$

$$\Rightarrow \begin{aligned} -2A_2 + 4B_2 &= 0 \quad (i) & -2A_1 + A_2 + 4B_1 &= 0 \quad (ii) \\ 2B_2 - A_2 &= 0 \quad (iii) & 2B_1 + B_2 - A_1 &= 0 \quad (iv) \end{aligned}$$

(i) & (iii) reduces to a single equation $2B_2 - A_2 = 0$
 $B_2 = 1, A_2 = 2$

(ii) & (iv) becomes
 $-2A_1 + 4B_1 = -2$
 $-A_1 + 2B_1 = -1$
 both eqⁿ reduces to
 $-A_1 + 2B_1 = -1$
 $A_1 = 1, B_1 = 0$

\therefore The second solution is

$$\left\{ \begin{aligned} x &= (1+2t)e^t \\ y &= (0+t)e^t \end{aligned} \right. \quad \text{ie,} \quad \left\{ \begin{aligned} x &= (1+2t)e^t \\ y &= te^t \end{aligned} \right.$$

\therefore The general solⁿ of the given system is

$$\left\{ \begin{aligned} x &= 2c_1 e^t + c_2 (1+2t)e^t \\ y &= c_1 e^t + c_2 t e^t \end{aligned} \right.$$

Non-homogeneous system

Consider,

$$(1) \begin{cases} \frac{dx}{dt} = a_1(t)x + b_1(t)y + f_1(t) \\ \frac{dy}{dt} = a_2(t)x + b_2(t)y + f_2(t) \end{cases}$$

$$y'' + P(x)y' + Q(x)y = R(x)$$

Corresponding homogeneous eqⁿ

$$y'' + P(x)y' + Q(x)y = 0$$

$$\downarrow$$

$$y = c_1 y_1 + c_2 y_2$$

PI \rightarrow MVP

$$y = \sigma_1 y_1 + \sigma_2 y_2$$

Corresponding homogeneous system of (1) is

$$(2) \begin{cases} \frac{dx}{dt} = a_1(t)x + b_1(t)y \\ \frac{dy}{dt} = a_2(t)x + b_2(t)y \end{cases}$$

Let $\begin{cases} x = x_1(t) \\ y = y_1(t) \end{cases}$ and $\begin{cases} x = x_2(t) \\ y = y_2(t) \end{cases}$

be linearly independent solutions of (2)

So that $\begin{cases} x = c_1 x_1(t) + c_2 x_2(t) \\ y = c_1 y_1(t) + c_2 y_2(t) \end{cases}$ is its general solution.

Let the particular solution of (1) be

$$\begin{cases} x = \sigma_1(t)x_1(t) + \sigma_2(t)x_2(t) \\ y = \sigma_1(t)y_1(t) + \sigma_2(t)y_2(t) \end{cases} \quad \text{i.e.} \begin{cases} x = \sigma_1 x_1 + \sigma_2 x_2 \\ y = \sigma_1 y_1 + \sigma_2 y_2 \end{cases}$$

Then $\frac{dx}{dt} = \sigma_1 x_1' + \sigma_1' x_1 + \sigma_2 x_2' + \sigma_2' x_2$

$$\frac{dy}{dt} = \sigma_1 y_1' + \sigma_1' y_1 + \sigma_2 y_2' + \sigma_2' y_2$$

Substitute the above in (1)

$$(3) \begin{cases} \sigma_1 x_1' + \sigma_1' x_1 + \sigma_2 x_2' + \sigma_2' x_2 = a_1(\sigma_1 x_1 + \sigma_2 x_2) + b_1(\sigma_1 y_1 + \sigma_2 y_2) + f_1 \\ \sigma_1 y_1' + \sigma_1' y_1 + \sigma_2 y_2' + \sigma_2' y_2 = a_2(\sigma_1 x_1 + \sigma_2 x_2) + b_2(\sigma_1 y_1 + \sigma_2 y_2) + f_2 \end{cases}$$

$$\begin{cases} x = x_1(t) \\ y = y_1(t) \end{cases} \text{ sub in (2)} \quad \frac{dx}{dt} = \frac{dx_1}{dt} = x_1' = a_1 x_1 + b_1 y_1$$

$$\frac{dy}{dt} = \frac{dy_1}{dt} = y_1' = a_2 x_1 + b_2 y_1$$

$$\left. \begin{aligned} x &= x_2(t) \\ y &= y_2(t) \end{aligned} \right\} \text{sub in (2)} \quad \frac{dx}{dt} = \frac{dx_2}{dt} = x_2' = a_1 x_2 + b_1 y_2$$

$$\frac{dy}{dt} = \frac{dy_2}{dt} = y_2' = a_2 x_2 + b_2 y_2$$

(3) becomes

$$\sigma_1 [a_1 x_1 + b_1 y_1] + \sigma_1' x_1 + \sigma_2 [a_1 x_2 + b_1 y_2] + \sigma_2' x_2 = a_1 [\sigma_1 x_1 + \sigma_2 x_2] + b_1 [\sigma_1 y_1 + \sigma_2 y_2] + f_1$$

$$\sigma_1 [a_2 x_1 + b_2 y_1] + \sigma_1' y_1 + \sigma_2 [a_2 x_2 + b_2 y_2] + \sigma_2' y_2 = a_2 (\sigma_1 x_1 + \sigma_2 x_2) + b_2 (\sigma_1 y_1 + \sigma_2 y_2) + f_2$$

$$\Rightarrow \begin{aligned} \sigma_1' x_1 + \sigma_2' x_2 &= f_1 & \text{--- (i)} \\ \sigma_1' y_1 + \sigma_2' y_2 &= f_2 & \text{--- (ii)} \end{aligned} \quad w(t) = \begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix} = x_1 y_2 - y_1 x_2$$

$$\begin{aligned} \text{(i)} \times y_1 &\rightarrow \sigma_1' x_1 y_1 + \sigma_2' x_2 y_1 = f_1 y_1 \\ \text{(ii)} \times x_1 &\rightarrow \sigma_1' x_1 y_1 + \sigma_2' x_1 y_2 = f_2 x_1 \end{aligned}$$

$$\sigma_2' [y_1 x_2 - x_1 y_2] = y_1 f_1 - x_1 f_2$$

$$- \sigma_2' [x_1 y_2 - y_1 x_2] = y_1 f_1 - x_1 f_2$$

$$\Rightarrow \sigma_2' = \frac{x_1 f_2 - y_1 f_1}{w(t)}$$

$$\Rightarrow \sigma_2 = \int \frac{x_1 f_2 - y_1 f_1}{w(t)} dt$$

$$\text{(i)} \times y_2 \rightarrow \sigma_1' x_1 y_2 + \sigma_2' x_2 y_2 = y_2 f_1$$

$$\text{(ii)} \times x_2 \rightarrow \sigma_1' y_1 x_2 + \sigma_2' y_2 x_2 = x_2 f_2$$

$$J_1'(x_1, y_2 - y_1, x_2) = y_2 f_1 - x_2 f_2$$

$$J_1' = \frac{y_2 f_1 - x_2 f_2}{w(t)}$$

$$\Rightarrow \boxed{J_1 = \int \frac{y_2 f_1 - x_2 f_2}{w(t)} dt}$$

HW: Solve:

$$\left\{ \begin{array}{l} \frac{dx}{dt} = x + y - 5t + 2 \\ \frac{dy}{dt} = 4x - 2y - 8t - 8 \end{array} \right.$$

Hint
 $f_1 = -5t + 2$
 $f_2 = -8t - 8$

————— xx —————

V. R. ML
07/01/2021

NHLS

Recall:

$$\frac{dx}{dt} = a_1(t)x + b_1(t)y + f_1(t)$$

$$\frac{dy}{dt} = a_2(t)x + b_2(t)y + f_2(t)$$

PI: $x = v_1 x_1 + v_2 x_2$

$y = v_1 y_1 + v_2 y_2$

where v_1 and v_2 are functions of 't'.

$$\begin{cases} v_1' x_1 + v_2' x_2 = f_1 \\ v_1' y_1 + v_2' y_2 = f_2 \end{cases}$$

$$v_1 = \int \frac{y_2 f_1 - x_2 f_2}{w(t)} dt$$

$$v_2 = \int \frac{x_1 f_2 - y_1 f_1}{w(t)} dt$$

Hw Solve:

①

$$\begin{cases} \frac{dx}{dt} = x + y - 5t + 2 \\ \frac{dy}{dt} = 4x - 2y - 8t - 8 \end{cases}$$

$$y'' + p(x)y' + q(x)y = R(x)$$

HE
 $y'' + p(x)y' + q(x)y = 0$

y_1, y_2

CF: $c_1 y_1 + c_2 y_2$

PI:

$y = CF + PI$

The corresponding homogeneous eqⁿ of (1) is

②

$$\begin{cases} \frac{dx}{dt} = x + y \\ \frac{dy}{dt} = 4x - 2y \end{cases}$$

which is of the form

$$\frac{dx}{dt} = a_1 x + b_1 y$$

$$\frac{dy}{dt} = a_2 x + b_2 y$$

where $a_1 = 1, b_1 = 1$
 $a_2 = 4, b_2 = -2$.

Let $\begin{cases} x = A e^{mt} \\ y = B e^{mt} \end{cases}$ be a solⁿ of (2)

Then we have $m^2 - (a_1 + b_2)m + a_1 b_2 - a_2 b_1 = 0$

and (*) $\begin{cases} (m - a_1)A - b_1 B = 0 \\ -a_2 A + (m - b_2)B = 0 \end{cases}$

\therefore The a.e is $m^2 - (1 - 2)m + (-2) - (4) = 0$
 $\therefore, m^2 + m - 6 = 0 \Rightarrow (m + 3)(m - 2) = 0$
 $m = -3, m = 2$

Example (1)

$\begin{cases} x_1 = e^{-3t} \\ y_1 = -4e^{-3t} \end{cases}, \begin{cases} x_2 = e^{2t} \\ y_2 = e^{2t} \end{cases}$

Let the particular solution be

$\begin{cases} x = \sigma_1 x_1 + \sigma_2 x_2 \\ y = \sigma_1 y_1 + \sigma_2 y_2 \end{cases}$

Then $\sigma_1 = \int \frac{y_2 f_1 - x_2 f_2}{w(t)} dt$

and $\sigma_2 = \int \frac{x_1 f_2 - y_1 f_1}{w(t)} dt$

$w(t) = \begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix} = \begin{vmatrix} e^{-3t} & e^{2t} \\ -4e^{-3t} & e^{2t} \end{vmatrix}$
 $= e^{-t} + 4e^{-t} = 5e^{-t}$

$$\begin{aligned}
 y_2 f_1 - x_2 f_2 &= e^{2t}(-5t+2) - e^{2t}(-8t-8) \\
 &= -5t e^{2t} + 2e^{2t} + 8t e^{2t} + 8e^{2t} \\
 &= 3t e^{2t} + 10e^{2t}
 \end{aligned}$$

$$\begin{aligned}
 x_1 f_2 - y_1 f_1 &= e^{-3t}(-8t-8) - (-4e^{-3t})(-5t+2) \\
 &= -8t e^{-3t} - 8e^{-3t} - 20t e^{-3t} + 8e^{-3t} \\
 &= -28t e^{-3t}
 \end{aligned}$$

$$\therefore U_1 = \int \frac{y_2 f_1 - x_2 f_2}{w(t)} dt$$

$$= \int \frac{(3t e^{2t} + 10e^{2t})}{5e^{-t}} dt = \frac{1}{5} \int (3t e^{3t} + 10e^{3t}) dt$$

$$= \frac{1}{5} \left[t e^{3t} - \frac{e^{3t}}{3} + 10 \frac{e^{3t}}{3} \right]$$

$$= \frac{1}{5} \left[t e^{3t} + 3 e^{3t} \right]$$

$$= \frac{e^{3t}}{5} \underline{\underline{[t+3]}}$$

$3 \int t e^{3t} dt$
 $\left\{ \begin{aligned} & \left[\frac{t e^{3t}}{3} - \int \frac{e^{3t}}{3} dt \right] \\ & \left[\frac{t e^{3t}}{3} - \frac{e^{3t}}{9} \right] \end{aligned} \right. \begin{cases} u=t \\ du=dt \\ \int dv = \int \frac{e^{3t}}{3} dt \\ v = \frac{e^{3t}}{3} \end{cases}$
 $t e^{3t} - \frac{e^{3t}}{3}$

$$U_2 = \int \frac{x_1 f_2 - y_1 f_1}{w(t)} dt = \int \frac{-28t e^{-3t}}{5e^{-t}} dt$$

$$= -\frac{28}{5} \int t e^{-2t} dt$$

$u=t$
 $du=dt$
 $\int dv = \int e^{-2t} dt$
 $v = \frac{e^{-2t}}{-2}$

$$= -\frac{28}{5} \left\{ \frac{te^{-2t}}{-2} - \int \frac{e^{-2t}}{-2} dt \right\}$$

$$= -\frac{28}{5} \left\{ \frac{te^{-2t}}{-2} + \frac{1}{2} \left(\frac{e^{-2t}}{-2} \right) \right\}$$

$$= -\frac{28}{5} \left\{ -\frac{te^{-2t}}{2} - \frac{e^{-2t}}{4} \right\}$$

$$V_2 = \frac{28}{10} e^{-2t} \left[t + \frac{1}{2} \right]$$

\therefore The particular integral is

$$x = \frac{e^{3t}}{5} (t+3) e^{-3t} + \frac{28}{10} e^{-2t} \left(t + \frac{1}{2} \right) e^{2t}$$

$$y = \frac{e^{3t}}{5} (t+3) (-4e^{-3t}) + \frac{28}{10} e^{-2t} \left(t + \frac{1}{2} \right) e^{2t}$$

$$\therefore, x = \frac{1}{5} (t+3) + \frac{28}{10} \left(t + \frac{1}{2} \right)$$

$$y = -\frac{4}{5} (t+3) + \frac{28}{10} \left(t + \frac{1}{2} \right)$$

$$\therefore, \boxed{\begin{matrix} x = 3t + 2 \\ y = 2t - 1 \end{matrix}}$$

$$\left[\frac{t}{5} + \frac{3}{5} + \frac{28t}{10} + \frac{28}{20} \right]$$

$$\frac{2t+28t}{10} + \frac{12+28}{20}$$

$$\underline{\underline{3t + 2}}$$

$$-\frac{4}{5}t - \frac{12}{5} + \frac{28}{10}t + \frac{28}{20}$$

$$\frac{-8t+28t}{10}$$

$$+ \frac{-48+28}{20}$$

$$\underline{\underline{2t - 1}}$$

\therefore The solution of (1) is

$$x = c_1 e^{-3t} + c_2 e^{2t} + 3t + 2$$

$$y = -4c_1 e^{-3t} + c_2 e^{2t} + 2t - 1$$

HW: ① Solve:

$$\begin{cases} \frac{dx}{dt} = x + 2y + t - 1 \\ \frac{dy}{dt} = 3x + 2y - 5t - 2 \end{cases}$$

② Solve:

$$\begin{cases} \frac{dx}{dt} = 7x + 6y \\ \frac{dy}{dt} = 2x + 6y \end{cases}$$

③ Solve:

$$\begin{cases} \frac{dx}{dt} = 4x - 3y \\ \frac{dy}{dt} = 8x - 6y \end{cases}$$

④ Solve:

$$\begin{cases} \frac{dx}{dt} = -4x - y \\ \frac{dy}{dt} = x - 2y \end{cases}$$

⑤ Solve:

$$\begin{cases} \frac{dx}{dt} = -3x + 4y \\ \frac{dy}{dt} = -2x + 3y \end{cases}$$